Operation/Programming 10/2004 Edition

sinumerik

SINUMERIK 840D/840Di/810D ShopMill



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SINUMERIK® Documentation

Printing history

Brief details of this edition and previous editions are listed below.

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- **B**.... Unrevised reprint with new Order No.
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Preface		
Struc Docu	ture of the mentation	 The SINUMERIK documentation is organized in 3 parts: General Documentation User Documentation Manufacturer/Service Documentation
Audie	ence	This documentation is intended for use by operators of vertical machining centers or universal milling machines controlled by the SINUMERIK 840D/840Di/810D system.
Valid	ity	This Operation/Programming Guide is valid for ShopMill SW 6.4.
Hotlii	ne	Please address any queries to the following hotline: A&D Technical Support Tel.: +49 (0) 180 5050-222 Fax: +49 (0) 180 5050-223 Email: adsupport@siemens.com
		If you have any queries (suggestions, corrections) concerning the documentation, please send them to the following fax number or email address: Fax: +49 (0) 9131 98-2176 Fax form at the end of the documentation Email: motioncontrol.docu@erlf.siemens.de
Interi	net address	http://www.cnc-werkstatt.de http://www.siemens.com/motioncontrol
SINU powe	MERIK 840D erline	Since 09.2001, improved-performance variants SINUMERIK 840D powerline and SINUMERIK 840DE powerline are available. For a list of available powerline modules, please refer to the following Hardware Description: Reference: (PHD/ SINUMERIK 840D Configuration Manual
SINU powe	MERIK 810D erline	Since 12.2001, improved-performance variants SINUMERIK 810D powerline and SINUMERIK 810DE powerline are available. For a list of available powerline modules, please refer to the following Hardware Description: Reference : /PHC/, SINUMERIK 810D Configuration Manual
Stand	dard scope	This Operator's/Programming Guide describes the functionality of the ShopMill operator interface. Extensions or changes made by the machine tool manufacturer are documented by the machine tool manufacturer.
		More detailed information about other publications relating to SINUMERIK 840D/840Di/810D and publications that apply to all SINUMERIK controls (e.g. Universal Interface, Measuring Cycles) can be obtained from your local Siemens branch office.

	Other functions not described in this documentation might be executable in the control. This does not, however, represent as obligation to supply such functions with a new control or when servicing.
Principle	Your SIEMENS 840D/840Di/810D with ShopMill has been designed and constructed according to state-of-the-art technology and approved safety regulations and standards.
Additional equipment	SIEMENS offers special add-on equipment, products and system configurations for the focused expansion of SIEMENS controls in your field of application.
Personnel	Only suitably trained, authorized, reliable personnel should be allowed to handle the equipment. Persons who are not qualified should never be allowed to work on the control, even for a short time.
	The relevant responsibilities of personnel who set up, operate and maintain the equipment must be clearly defined and adherence to these responsibilities monitored .
Procedure	Before the control is started up, it should be ensured that the Operator's Guides have been read and understood by the people responsible. The operator also has a permanent obligation to continuously monitor the overall technical condition (externally recognizable defects and damage and changes in the operating behavior) of the control.
Servicing	Repairs must be carried out by personnel who are specially trained and qualified in the relevant technical subject according to the information supplied in the service and maintenance guide. All appropriate safety specifications must be observed.
	The following is deemed to be improper usage and exempts the manufacturer from any liability: • Any application deviating from the above points or usage
	extending beyond the given limits.
	• Cases where the control is not maintained in perfect technical condition , or is operated without due regard to safety or danger,
	and cases where any or all of the instructions in the Operator's Guide have not been observed.
	 If faults that might affect the safety of the equipment are not rectified before the control is started up.



		 Any modification, bypassing or disabling of items of equipment on the control that are required to ensure fault-free operation, unlimited use and active and passive safety.
	Structure of the documentation	This documentation uses the following information blocks, identified by pictograms:
		Function
=?		Background information
,		Operating sequence
		Explanation of parameters
		Additional notes
T		Software option The function described is a software option. This means that the function will only run on the control if you have purchased the relevant option.
	Warnings	The following 5 warnings with varying degrees of severity are used in this documentation.
Δ		Danger Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury or in substantial property damage.
Δ		Warning Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury or in substantial property damage.
Δ		Caution Used with the safety alert symbol indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury or in property damage.



	Caution Used without safety alert symbol indicates a potentially hazardous situation which, if not avoided, may result in property damage. Notice Used without the safety alert symbol indicates a potential situation which, if not avoided, may result in an undesirable result or state.
Machine manufacturer	If changes or additions exist for a particular topic, they are referenced here:
	Please observe the details provided by the machine manufacturer.
References	Further references for particular topics are indicated here:
	Reference:
	A complete list of available literature is included in the Appendix of this Operator's Guide.
Terms	The meanings of several fundamental terms used in this docu- mentation are defined below:
	Program A program is a sequence of instructions for the CNC control, which produce a particular workpiece at the machine.
	Contour A contour outlines a workpiece. The term "contour" is also used to denote the section of a program that uses individual elements to define the outline of a workpiece.
	Cycle A cycle, for example, mill rectangular pocket, is a subroutine specified by ShopMill to execute a repetitive machining process. (a cycle is sometimes also called a "function".)

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"Unit of measurement"

The parameter units are always specified in metric units in this documentation. The corresponding inch measures are given in the table below.

Metric	Inch
mm	in
mm/tooth	in/tooth
mm/min	in/min
mm/rev	in/rev
m/min	ft/min



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1.1 ShopMill

	ShopMill is operating and programming software for milling machines that makes it easy for you to operate the machine and to program workpieces.
	These are some of the features the software provides:
Setting up the machine	Special measurement cycles make it easier to measure the tools and the workpiece.
Creating a program	 3 different programming methods are available: G code programs for mold-making applications imported from CAD/CAM systems. G code programs that you create directly at the machine. You can use all technology cycles for programming: Sequential control programs that you create directly at the machine (software option). The workpiece is programmed with ease because graphical techniques are used and no knowledge of G codes is required. ShopMill displays the program as a clearly understandable process plan and presents the individual cycles and contour elements in a dynamic graphical display.
	 Irrespective of the programming method you use, the following functions will simplify programming and processing: A powerful contour calculator lets you enter any contours. A stock removal cycle complete with detection of residual material saves unnecessary machining (software option). A swivel cycle allows multiple-surface machining and machining on inclined surfaces, irrespective of the machine kinematics of the machine.
Executing a program	You can display the execution of programs on the screen three-dimensionally. This makes it easy for you to check the result of programming and to observe the progress of workpiece machining at the machine (software option).
	The execution of sequential control programs is a software option.



Executing a program	You can display the execution of programs on the screen three-dimensionally. This makes it easy for you to check the result of programming and to observe the progress of workpiece machining at the machine (software option).
	The execution of sequential control programs is a software option.
Tool management	ShopMill stores your tool data. The software can also manage the data for tools that are not in the tool magazine.
Program management	Programs can be created simply by copying and modifying similar programs; there is no need to start again from the beginning.
	With ShopMill you can implement multiple clamping of identical or different (software option) workpieces with optimization of the tool sequence.
	You can access external programs from a network or from a diskette drive (software option).

1.1.1 Sequence of operations

Two typical working situations are considered separately in this Guide.

- You want to execute a program for the purpose of automatically machining a workpiece.
- You want to create the program to be used for machining a workpiece.

Executing a programBefore you execute a program, you have to set up your machine. You
must perform the following steps with the support of ShopMill (see
Sec. "Operation"):

- approach the reference point of the machine (only for incremental position measuring systems)
- gauge the tools
- define the workpiece zero
 - enter any other work offsets

When you have finished setting up the machine, you can select a program and execute it automatically (see Sec. "Automatic operation").

Creating a program	As you create a new program, you can choose whether it will be a sequential control program or a G code program (see "Creating a ShopMill program" or "G code program"). During creation of a sequential control program, ShopMill prompts you to enter all the relevant parameters. Programming progress is automatically indicated in a dashed-line diagram. Help screens that explain the parameters in each operation also support you with
	programming. You can, of course, also insert G code commands in a sequential control program. A G code program, however, must be created entirely out of G code commands.

1.2 Workstation

A ShopMill workstation comprises the milling machine complete with a CNC/positioning control plus an operator panel and a machine control panel.

	Operator panel
Milling machine complete with control	Machine control panel

Workstation configuration

Milling machine	You can use ShopMill on vertical or universal milling machines with up to 10 axes (including rotary axes and spindles). Of the 10 axes, 3 linear and 2 rotary axes plus 1 spindle can be displayed at any one time. Machining step and G code programs are suitable for 2D to 2½D machining; for 3D machining, use G code programs from CAD/CAM systems.
Control	ShopMill runs on the SINUMERIK 840D/840Di/810D CNC with PCU 20 and PCU 50.
Operator panel	You communicate with ShopMill via the operator panel.
Machine control panel	You operate the milling machine via the machine control panel.

1.2.1 Coordinate system

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The basic coordinate system used to machine a workpiece on a milling machine is right-angled. It consists of the three coordinate axes X, Y, and Z that are parallel to the machine axes.

The positions of the coordinate system and the machine zero depend on the type of machine used.



Position of the coordinate system, machine zero and workpiece zero (example)

The axis directions are governed by the "right-hand rule" (according to DIN 66217).

Seen from in front of the machine, the middle finger of the right hand points in the opposite direction to the infeed of the main spindle. Therefore:

- the thumb points in the +X direction
- the index finger points in the +Y direction
- the middle finger points in the +Z direction



Right-hand rule

1.2.2 Operator panels

	You can use one of the following operator panels for the PCU: OP 010 OP 010C OP 010S with OP 032S full CNC keyboard OP 012 OP 015 with 19" full CNC keyboard
Operator panel OP 010	
	Operator panel OP 010
	1 10" screen
	2 Screen keys
	3 Horizontal softkey bar
	4 Vertical softkey bar
	Alphanumeric keypad
	Correction/cursor pad with control keys and input key

• USB interface



- 1 10" screen
- 2 Screen keys
- 3 Horizontal softkey bar
- 4 Vertical softkey bar
- Alphanumeric keypad
 Correction/cursor pad with control keys and input key
- 6 USB interface

1

2 4

OP 010S operator panel

1 10" screen

2

- 2 Screen keys
- **3** Horizontal softkey bar
- 4 Vertical softkey bar
- 5 USB interface





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Operator panel OP 010C



Introduction 1.2 Workstation

OP 012 operator panel



OP 012 operator panel

- 1 12" screen
- 2 Screen keys
- 3 Horizontal softkey bar
- 4 Vertical softkey bar
- Alphanumeric keypad
 Correction/cursor pad with control keys and input key
- 6 USB interface
- 7 Mouse

Operator panel OP 015



Operator panel OP 015

- 1 15" screen
- 2 Screen keys
- 3 Horizontal softkey bar
- 4 Vertical softkey bar
- 5 USB interface

1.2.3 Operator panel keys



HELP













Alarm Cancel

Cancels the alarm that is marked with this symbol.

Channel

Irrelevant in ShopMill.

Help

Toggles between the process plan and programming graphics as well as between the parameterization screen form with programming graphics and the parameterization screen form with the help display.

Next Window

Irrelevant in ShopMill.

Page Up or Page Down

Page upward or downward in the directory or in the process plan.

Cursor

Navigate between different fields or lines.

Use Cursor right to open a directory or program.

Use Cursor left to switch to the next highest level in the directory tree.

Select

Chooses one of a number of options presented. This key has the same function as the "Alternat." softkey.

End

Moves the cursor to the last input field in a parameterization screen form.

Backspace

- Deletes the value in the input field.
- In insertion mode, it deletes the character after the cursor.

Tab

Irrelevant in ShopMill.

Shift

Depress the Shift key to enter the upper character shown on the dual input keys.

CTRL

ALT DEL













Ctrl

Use the following key combinations to navigate in the process plan and in the G code editor:

- Ctrl + Home: Jump to the beginning.
- Ctrl + End: Jump to the end.

Alt

Irrelevant in ShopMill.

Del - not with OP 031

- Deletes the value in the parameter field.
- In insertion mode, it deletes the character marked by the cursor.

Insert

Activates insertion mode or the pocket calculator.

Input

- Terminates entry of a value in the input field.
- Opens a directory or program.

Alarm - only OP 010 and OP 010C

Opens the "Messages/Alarms" operating area. This key has the same function as the "Alarm list" softkey.

Program - only OP 010 and OP 010C

Opens the "Program" operating area. This key has the same function as the "Prog. edit" softkey.

Offset - only OP 010 and OP 010C

Opens the "Tools/Offsets" operating area. This key has the same function as the "Tools WOs" softkey.

Program Manager - only OP 010 and OP 010C

Opens the "Program Manager" operating area. This key has the same function as the "Program" softkey.

1.2.4 Machine control panels

You can equip your milling machine with a SIEMENS machine control panel or with a specific machine control panel supplied by the machine manufacturer.

You use the machine control panel to initiate actions on the milling machine such as traversing an axis or starting the machining of a workpiece.

When functions are active, the LEDs on the corresponding keys on the machine control panel light up.

1.2.5 Elements of the machine control panels



Emergency Stop button

Press this pushbutton in an emergency, i.e. when there is a danger to life or there is a risk of damage to the machine or workpiece. All drives will be stopped with the greatest possible braking torque.

For additional responses to pressing the Emergency Stop button, please refer to the machine manufacturer's instructions.

Reset

- Interrupts execution of the current program.
 The NC control remains synchronized with the machine. It is in its initial state and ready for a new program run.
- Cancels an alarm

Jog

Selects Machine Manual operating mode.

Teach In

Irrelevant in ShopMill.

MDI

Selects MDI mode.

Auto

Selects Machine Auto operating mode.







Executes the program block by block (single block).

Repos

Repositions, re-approaches the contour.

Ref Point

Approaches the reference point.

Inc Var (incremental feed variable) Incremental mode with variable increment size.

Inc (incremental feed) Incremental mode with predefined increment size of 1, ..., 10000 increments.

A machine data code defines how the increment value is interpreted.

Please refer to the machine manufacturer's instructions.

Cycle Start Starts execution of a program.

Cycle Stop Stops execution of a program.

Axis keys Selects an axis.

Direction keys

Traverses axis in negative or positive direction.

Rapid

Traverses axis at rapid traverse (fastest speed).

WCS MCS

Switches between the workpiece coordinate system (WCS = work) and machine coordinate system (MCS = machine).







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Feedrate/Rapid Traverse Override

Raises or lowers the programmed feedrate or rapid traverse. The programmed feedrate or rapid traverse is set to 100% and can be adjusted between 0% and 120% (only up to 100% for rapid traverse). The new feedrate setting appears in the feedrate status display on the screen as an absolute value and as a percentage.

Introduction

1.2 Workstation

Feed Stop

Stops execution of the running program and shuts down axis drives.

Feed Start

Continues execution of the program in the current block and ramps up to the feedrate specified in the program.

Spindle Override

Increases or decreases the programmed spindle speed. The programmed spindle speed is set to 100% and can be controlled from 50 to 120%. The new spindle speed setting appears in the spindle status display on the screen as an absolute value in percent.

Spindle Dec. – only OP032S machine control panel

Decreases the programmed spindle speed.

Spindle Inc. – only OP032S machine control panel Increases the programmed spindle speed.

100 % – only OP032S machine control panel Restores the programmed spindle speed.

Spindle Stop Stop spindle.

Spindle Start

Start spindle.

Spindle Left – machine control panel OP032S only Starts spindle (CCW rotation).

Spindle Right – machine control panel OP032S only Starts spindle (CW rotation).

Keyswitch

Protection level 4

You can use the keyswitch to set various access rights. The keyswitch has four settings for protection levels 4 to 7.

Machine data can be programmed to interlock access to programs, data, and functions at various protection levels.

Please refer to the machine manufacturer's instructions.

The keyswitch has three keys of different colors that you can remove in the specified positions:

Position 0 Lowest No key access authorization Protection level 7 Position 1 Key 1 black Protection level 6 Increasing access authorization Position 2 Key 1 green Protection level 5 Position 3 Highest Key 1 red access authorization

When you change the key position to change the access authorization, this is immediately not visible on the operator interface. You have to initiate an action first (e.g. close or open a directory).

If the PLC is in the STOP state (LEDs on the machine control panel are flashing), ShopMill will not read the keyswitch settings as it boots.

The machine manufacturer can set up protection levels 0 to 3 using a password. If this password is set, ShopMill does not read the keyswitch setting.

Please refer to the machine manufacturer's instructions.

(

1.2.6 Mini handheld unit



- A EMERGENCY STOP button, two-channel
- B Enabling key, two-channel
- C Axis selector switch for 5 axes and neutral position
- D Function keys F1, F2, F3
- E Traversing keys, directions +, -
- F Rapid traverse key for high-speed travel with traversing keys or handwheel
- G Handwheel
- H Magnets for attachment to metal parts
- I Connecting cable 1.5 m ... 3.5 m

Control elements

EMERGENCY STOP button

The EMERGENCY STOP button must be pressed in an emergency

- 1. when a person is at risk,
- 2. when there is a danger of the machine or workpiece being damaged.

Enabling button

The enabling button is designed as a 2-way switch. It must be pressed to initiate traversing movements.

Axis selection switch

You can select up to 5 axes with the axis selector switch.

Function keys

The function keys can be used to trigger machine-specific functions.

Traversing keys

The +, - traversing keys can be used to trigger traversing movements on the axis selected via the axis selection switch.

Handwheel

The handwheel can be used to initiate movements at the axis selected using the axis selection switch. The handwheel supplies two guide signals with 100 I/U.

Rapid traverse key

The rapid traverse key increases the traversing speed of the axis selected with the axis selector switch. The rapid traverse key acts both on travel commands from the +/- keys and on the handwheel signals.

1.3 User interface

1.3.1 Overview

Screen layout



User interface

- 1 Active operating mode/operating area and secondary mode
- 2 Alarm and message line
- 3 Program name
- 4 Program path
- 5 Channel state and program control
- 6 Channel operational messages
- 7 Position display of the axes
- 8 Display for
 - active tool T
 - current feedrate F
 - spindle S
 - spindle utilization in percent
- 9 Display of active work offsets and rotation
- 10 Working window
- 11 Dialog line for additional explanatory text
- 12 Horizontal softkey bar
- 13 Vertical softkey bar
- 14 Softkeys
- 15 Screen buttons

Introduction 1.3 User interface

Secondary mode	REF: REPOS:	Approaching a reference point Repositioning		
	INC_VAR:	Variable increment		
Channel status	RESET			
Program control	SKP: Skip G code	e block		
	IROV: Feedrate ov	prate verride only (not feedrate and rapid traverse		
	override) SBL1: Single block (stop after every block that triggers a			
	SBL2: Not possible to select in ShopMill (stop each every block) SBL3: Single block fine (stop after every block, even within a cycle)			
M01: Progr		d stop		
	PRT: Program tes	st		
Channel operational messages	Stop: An oper	ator action is required. ator action is required.		
	If a dwell time is ac either displayed in s	tive, the remaining dwell time is displayed. It is seconds or as spindle revolutions.		
Position display of the axes	The actual value display in the position display refers to the SZS coordinate system (settable zero system). The position of the active tool relative to the workpiece zero is displayed.			
	Symbols used for a ⊀¥ Linear axis clan C Rotary axis clar	xis display nped nped		
Feedrate status		ot enabled		
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Spindle not enabled

Spindle is stationary

Spindle is turning clockwise

Spindle is turning counterclockwise

The display of the spindle utilization as a percentage can be 200 %.

Please refer to the machine manufacturer's instructions. Key to the meaning of the symbol colors: Red: Machine is stationary Green: Machine is running Yellow: Waiting for operator to take action Gray: Miscellaneous





Machine

Call active operating mode (Machine Manual, MDI, or Machine Auto).

Return

Irrelevant in ShopMill.

Expansion

Changes the horizontal softkey bar.

Menu Select

Calls the main menu:

61

The machine manufacturer can display defined symbols instead of the program path (4). The program path is then displayed together with the program name (3).

Please refer to the machine manufacturer's instructions.





1.3.2 Operation by means of softkeys and hardkeys

PROGRAM MANAGER Jog The ShopMill user interface consists of different screens featuring eight horizontal and eight vertical softkeys. You operate the softkeys with the keys next to the softkey bars.

Each softkey displays a new screen form.

ShopMill has 3 operating modes (Machine Manual, MDI, and Machine Auto) and 4 operating areas (Program Manager, Program Messages/ Alarms, and Tools/Work Offsets).

To switch from one operating mode/operating area to another, press the "Menu Select" key. The main menu is displayed, in which you can select the appropriate operating area via a softkey.

Alternatively, you can call the operating areas via the hardkeys on the operator panel.

You can activate an operating mode directly at any time via the keys on the machine control panel.

If you select the "Machine" softkey in the main menu, the screen form for the currently active mode appears.

If you select another operating mode or operating area, the horizontal and vertical softkey bars change.

🗹 MANUAL				
// Reset				
Workpiece Position	[mm]	T,F,S		
X 6.000)	Т	D1	
Y 10.000)	F 0.000	042 100%	
Z 35.000)	S 0.000	90% I	
		0%	80% 100%	
		_	_	
Ma- chine Pro- gram	Edit prog. Alarm Ist	Vos		ISO ISO

Main menu

MANUAL				
∥ Reset				G function
WCS	Position [mm]	T,F,S		
Х	5.000	т	D1 ä↓z	Auxiliary function
Y Z	10.000	F	0.000 100% 0.000 mm/rev	All G functions
2 A C	0.000 0.000 0.000	S	0.000 🗈 90% 0.000 I	Run- times
_		0%	80% 100%	
				Act. val. Mach(MCS)
Ţ Т,S,M	Set Weas.	tool 👌 Swivel	Posi- tion Face mill.	

Machine Manual operating mode

M MANUAL ∥ Reset G function WCS Position [r T,F Auxiliary function D1 Х 5.000 Т ₿↓z Y 10.000 All G functions F 0.000 0.000 100% mm/rev Ζ 0.000 S 0.000 I 90% 0.000 0.000 Run-times A C 80% 100% Act. val. Mach(MCS) $\mathbf{\Sigma}$ Weas. Meas. tool Swivel Posi- Face mill. Ţ, Т,S,M ₹ Set WO

If you press a horizontal softkey within an operating mode or operating area, only the vertical softkey bar will change.

Machine Manual operating mode

MANUAL					
1 Reset					() Alternat.
WCS	Position [mm]	T.	F,S		
х	5.000	т	FRAESER_10 R 5.000	D1 ä↓Z	
Y _	10.000	F	RAPID	100%	
2 A C	000.0 000.0 000.0	s	0.000 0.000	90%	
		0%		80% 100%	5
Position			Target	position	Rapid traverse
		x		abs	
		Y		abs	
		Z		abs abs	
		č		abs	
		F	*Rapid tr.*	nm/min	
					« Back
2 29	Set IR Meas	Meas	Posi-L	Eaco	
🖡 Т,S,M 🍋	WO Workp.	tool 🦿 Swive	el tion	mill.	

Function within Machine Manual operating mode



Program manager

You can display a sequential control program in various views.

In the program manager, you manage all your programs. You can also select a program here for machining the workpiece.

DIR	ECTORY							
	Name		Туре	e Loaded	Size	Date/ti	ме	
5	SHOPMILL	.WPD∖						
2	T_011_TM	Z	INI		6236	27.09.2	002 09:14	
2	UP_11_1_	TMZ	INI		273	27.09.2	002 09:14	New
ì	T_011		MPF	x	5882	27.09.2	002 10:52	
ì	T_012		MPF		215	27.09.2	002 09:14	Rename
ľ	UP_11_1		MPF	x	1352	27.09.2	002 10:52	
ì	UP_11_2		MPF	x	1060	27.09.2	002 10:52	Mark
								Carry
								сору
								Paste
								Cut
Fre	e memory		Hard	disk :	1.2 GBytes	NC:	458264	Continue
	NC							

Program manager

Select the program manager with the "Program" softkey or "Program Manager" key.

You can move around within a directory using the "Cursor up" and "Cursor down" keys.

Use the "Cursor right" key to open a directory.

Use the "Cursor left" key to move up to the next-higher directory level.

Use the "Cursor right" or "Input" key to open the process plan for a program.



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Process plan

The process plan provides an overview of the separate machining steps of a program.



Process plan



You can move between the program blocks in the process plan using the "Cursor up" and "Cursor down" keys.

Use the "Help" key to switch between the process plan and the programming graphics.

The programming graphics display a dynamic broken-line top view of the workpiece. The program block selected in the process plan is color-highlighted in the programming graphics.



Programming graphics

Programming graphics

Use the "Cursor right" key to open a program block in the process plan. The appropriate parameterization mask complete with programming graphics is then displayed.

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Parameter screen with programming graphics

The programming graphics in a parameterization screen form show the contour of the current machining step in broken-line graphics complete with the parameters.





Parameter screen with programming graphics

Use the cursor keys to move between the input fields within a parameterization screen form.

Use the "Help" key to switch between the programming graphics and the help display.



The help display in the parameterization screen form explains the parameters of the machining step individually.



Parameter screen with help display

The colored symbols in the help displays have the following meaning: Yellow circle = reference point Red arrow = tool traveling at rapid traverse

Green arrow = tool traveling at machining feedrate

On setting up the machine and during programming, you must enter values in the white fields for various parameters.

Parameters that have a gray input field are automatically calculated by ShopMill.



Parameterization screen form

Selecting a parameter



Entering a parameter

Some parameters require you to select from a number of options in the input field. Fields of this type do not allow you to type in a value.

Press the "Alternat." softkey or the "Select" key until the required setting is displayed.

The "Alternat." softkey is only visible when the cursor is positioned on an input field that presents a choice of options. The "Select" key is also only active in this situation.

For the remaining parameters, enter a numerical value in the input field using the keys on the operator panel.

- Enter the desired value.
- > Press the "Input" key to terminate entry.

If you do not want to enter a value, i.e. not even "0", press the "Backspace" or "Del" key.



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1

Selecting the unit	For certain parameters, you can choose between different units.
AlternatOr-	Press the "Alternat." softkey or the "Select" key until the required unit is displayed.
	The "Alternat." softkey is only visible when you have a choice of units for this parameter. The "Select" key is also only active in this situation.
Deleting a parameter	If an input field contains an invalid value, you can delete it completely.
BACKSPACE -or-	Press the "Backspace" or "Del" key.
Changing or calculating parameters	If you only want to change individual characters in an input field rather than overwriting the entire entry, switch to insert mode. In this mode, the pocket calculator is also active. You can use it during programming to calculate parameter values.
	Press the "Insert" key.
INSERT	Insert mode and the pocket calculator are activated.
	You can move around within the input field using the "Cursor left" and "Cursor right" keys. Use the "Backspace" or "Del" key to delete individual characters.
	For more information on the pocket calculator, see Sec. "Pocket calculator".
Accepting a parameter	When you have correctly entered all the necessary parameters in the parameterization screen form, you can close the screen form and save the parameters.
Accept -or-	Press the "Accept" softkey or the "Cursor left" key. If there are several input fields in a line and you want to use the "Cursor left" key to accept the parameters, you must position the cursor in the leftmost input field.
	You cannot accept the parameters if they are incomplete or obviously erroneous. In this case, you can see from the dialog line which parameters are missing or were entered incorrectly.

1.4 Fundamentals

1.4.1 Plane designation

A plane is defined by means of two coordinate axes. The third coordinate axis (tool axis) is perpendicular to this plane and determines the infeed direction of the tool (e.g. for 2½-D machining).

When programming, it is necessary to specify the working plane so that the control system can calculate the tool offset values correctly. The plane is also relevant to certain types of circular programming and polar coordinates.



Working planes are defined as follows:

Plane	Tool axis
X/Y	Z
Z/X	Y
Y/Z	Х

1.4.2 Polar coordinates

The rectangular coordinate system is suitable in cases where dimensions in the production drawing are orthogonal. For workpieces dimensioned with arcs or angles, it is better to define positions using polar coordinates. This is possible if you are programming a straight line or a circle (see Section "Programming simple path motions").

Polar coordinates have their zero point in the "pole".

Example:

Points P1 and P2 can then be described – with reference to the **pole** – as follows:

 ${\tt P1}$: radius =100 plus angle =30°

 ${\tt P2:} radius$ =60 plus angle =75°



1.4.3 Absolute dimensions

With absolute dimensions, all the positional data refer to the currently valid zero point. Applied to tool movement this means:

The absolute dimensions describe the position to which the tool is to travel.

Example:

The positional parameters for points P1 to P3 in absolute dimensions **relative to the zero point** are the following:

- P1: X20 Y35
- P2: X50 Y60
- P3: X70 Y20



1.4.4 Incremental dimensions

In the case of production drawings in which dimensions refer to some other point on the workpiece rather than the zero point, it is possible to enter an incremental dimension.

With incremental dimension input, each item of positional data refers to a point programmed beforehand.

Example:

The positional data for points P1 to P3 in incremental dimensions are:

P1: X20 Y35 ;(relative to the zero point)
 P2: X30 Y20 ;(relative to P1)
 P3: X20 Y -35 ;(relative to P2)





1.4.5 Pocket calculator function



Precondition





Function

The cursor is positioned on a parameter field.

Press the "Insert" key

or

Equals key

to switch to pocket calculator mode.

Once you have pressed this key, enter one of the basic arithmetic operators (+, -, *, /), then enter a value,

then press "Input", and then enter a second value to obtain the result of the arithmetic operation.

Example:

Suppose we want to add a tool wear of + 0.1 in length L for a tool.

- Place the cursor in the appropriate parameter setting field,
- Press the Equals key to open the parameter field and
- Add the new wear value to the existing value, e.g. 0.5 + 0.1
- Complete the calculation by pressing the "Input" key. Result: 0.6

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2.1 Switching on and off

There are different ways of switching the control and the entire system on and off.

Please refer to the machine manufacturer's instructions.

After power ON, the main "Machine Manual" display appears on the screen

🗹 MANUAL			
🖉 Reset			G function
WCS	Position [mm]	T,F,S	Auxiliaru
х	5.000	Т	D1 function
Y	10.000	F 0.000 0.000 m	- 100% All G functions
८ А С	0.000 0.000 0.000	S 0.000 0.000	90% Run- I times
_		0% 8	0% 100%
			Act. val. Mach(MCS)
Т , S, M	20 Set 10 Meas.	Meas. Swivel T Posi-	Face mill.

Main "Machine Manual" display

2.2 Reference point approach



The "Ref Point" function ensures that the control and machine are synchronized after power ON.

Various reference point approach methods may be employed.

Please refer to the machine manufacturer's instructions.

- Reference point approach can only be performed by machine axes. The actual value display does not match the real position of the axes when the control is switched on.
- Reference point approach is necessary on machines without an absolute measuring system!



Operation 2.2 Reference point approach





The machine is synchronized as soon as the reference point is reached. The actual value display is set to the reference point value. The display is the difference between the machine zero and the slide reference point. From now on path limits, such as software limit switches, are active.

End the function via the machine control panel by selecting operating mode "Machine Auto" or "Machine Manual".

- You can reference all axes simultaneously (depending on the PLC program supplied by the machine tool manufacturer).
- The feedrate override is operative.

The machine manufacturer can define the order in which the axes will be referenced.

Only when all axes with a defined reference point have reached this point will you be able to start with the "Cycle Start" key in "Machine Auto".







2.2.1 User agreement in Safety Integrated



If you are using Safety Integrated (SI) on your machine, you will need to confirm that the current displayed position of an axis corresponds to its actual position on the machine when you reference an axis. Your confirmation is the precondition for the availability of other Safety Integrated functions.

You can only give your user agreement for an axis after it has approached the reference point.

The displayed axis position always refers to the machine coordinate system (MCS = machine).

User agreement with Safety Integrated is only possible with a software option.

For more information on user agreement, please refer to: **References:** /FBSI/, Description of Functions SINUMERIK Safety Integrated

- Select "Machine Manual" mode.
- > Press the "Ref Point" key on the machine control panel.
- Select the axis to be traversed.
- Press the "+" or "-" key.

The selected axis moves to the reference point and stops. The coordinate of the reference point is displayed. The axis is marked $\textcircled{\bullet}$.

> Press the "User agreement" softkey.

The "User agreement" window opens.

It shows a list of all machine axes with their current and SI positions.

- Position the cursor in the "Agreement" field for the axis in question.
- Give your agreement by pressing the "Alternat." softkey or the "Select" key.

The selected axis is marked with a cross meaning "safely referenced" in the "Agreement" column.

Pressing the "toggle keys" again removes your agreement.







2.4 Settings for the machine

2.4.1 Switching over the unit (millimeter/inch)



This function enables you to switch between the metric and inch dimension systems depending on the dimension units used in your production drawing.

Every dimension system switchover applies to the entire machine, i.e. all relevant measurement data are automatically converted to the new dimension system, e.g.

- Positions
- Tool offsets
- Work offsets
- Open the extended horizontal softkey bar in "Machine Manual" \geq mode.
- Press the "ShopM. sett." softkey. \geq

> Press the "Inch" softkey to switch to Inch.

The "Inch" softkey is active.

confirm switchover.

> Press the "Inch" softkey to switch to **metric**.

The "Inch" softkey is not active. When you press the "Inch" softkey, a box appears asking you to

The dimension system is adjusted accordingly if you confirm with the "OK" softkey.



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2.4.2 Switching over the coordinate system (MCS/WCS)



The machine coordinate system (MCS) is the original system of your machine. Unlike the workpiece coordinate system (WCS), it does not allow for tool offsets, work offset, scalings, etc.

You can switch between the machine and workpiece coordinate systems by following the sequence below.

> Press the "WCS MCS" key on the machine control panel

-or-

- > Select "Machine Manual" or "Machine Auto" mode.
- > Press the "Actual value MCS" softkey to switch to MCS.

The "Actual value MCS" softkey is active.

Press the "Actual value MCS" softkey to switch from MCS to WCS.

The "Actual value MCS" softkey is not active.



Operation 2.5 Setting a new position value



2.5 Setting a new position value

You can use the "Set work offset" function to enter a new position value for each individual axis in the actual value display. The difference between the position value in the machine coordinate system **MCS** and the new position value in the workpiece coordinate system **WCS** is saved in the currently active work offset or in the basic offset.

Please refer to the machine manufacturer's instructions.

If the values are stored in the active work offset, they are stored in the coarse offset and existing values in the fine offset are deleted. The currently active work offset is displayed under the position window for the axes.

- Move the machine axes to the desired position (e.g. workpiece surface).
- > Select the "Set WO" menu in "Machine Manual" operating mode.

🗹 MANUAL							
∥ Reset							X=0
WCS	Position	ı [mm]		T,F,S			
Х	5.0	00		Т		员172	Y=0
Y 7	10.0	00 00		F	0.000 0.000	100% / mm/rev	Z=0
2 А С	0.001 0	.000 .000		S	0.000 0.000	90% I	A=0
_	_	_	_	0%	_	80% 100%	C=0
							Delete
							X=Y=Z=0
	_				_	$\mathbf{\Sigma}$	« Back
🖡 т,s,м	₩0 ₩0	Meas.	Meas. tool 📌 Se	wivel	Posi- tion	Face mill.	

Base offset menu





2

	Setting a position value	 Enter the new position values with the keyboard. You can use the cursor keys to switch between positions.
		Press the "Input" key to complete your entry.
		 -or- Press softkeys "X=0", "Y=0", and "Z=0", to set the position values to zero.
	Resetting an offset	
	Delete	Press the "Delete" softkey.
		The offset is canceled again.
F		The work offsets (WO1 etc.) are based on the base offset.



L

2.6 Measuring workpiece zero

		 The reference point for programming a workpiece is always the workpiece zero. You can determine the workpiece zero on the following workpiece elements: Edges Corner Pocket/hole Spigot Plane
-?		You can measure the workpiece zero either manually or automatically.
	Manual measurement	To measure the zero point manually, you need to traverse your tool manually up to the workpiece. You can use edge probes, sensing probes, or dial gauges with known radii and lengths. You can also use any other tool of which you know the radius and length. The tools used for measuring must not be of type 3D probe.
	Automatic measurement	For automatic measurement always use electronic 3D measuring probes, which you must first calibrate. When measuring automatically, first position the tool manually. As soon as you start the process with the "Cycle Start" key, the probe automatically approaches the workpiece at measuring feedrate and then returns to the starting position at rapid traverse.
F		For automatic workpiece zero measurement, the machine manufacturer must have first set up the measuring cycles. This includes defining the measuring feedrate in the machine data.
		Please refer to the machine manufacturer's instructions.
		To obtain the desired measuring results, you must keep to the measuring point sequence shown in the help displays. You can reject measuring points and then measure them again. This is done by pressing the softkey that is currently active (measured value). In manual measurement, you can reset values in any order but in automatic measurement, only in reverse order.



2

Measurement only	If you "only" want to measure the workpiece zero, the measured values are merely displayed without changing the coordinate system.
Work offset	You usually store the measured workpiece zero in a work offset. With ShopMill you can measure rotations and offsets. If necessary, you may first have to measure the rotations of your workpiece to align your workpiece and then define the zero point by measuring the offsets.
Aligning	Alignment can be performed either by rotating the coordinate system or by rotating the workpiece with a rotary axis. If your machine is equipped with two rotary axes and the "swivel" function is set up, you can also align an inclined plane.
Zero point	The measurement values for the offsets are stored in the coarse offset and the relevant fine offsets are deleted. If the zero point is stored in a non-active work offset, an activation window is displayed with which you can activate this work offset directly.
Rotary axes	 If your machine has rotary axes, you can include these rotary axes in the measurement and setup procedure. If you store the workpiece zero in a work offset, rotary axis positioning may be necessary in the following cases. Correcting the work offset requires you to position the rotary axes to align the workpiece parallel with the coordinate system, e.g. with "Align edge". Correcting the work offset rotates the workpiece coordinate system, which should align the tool perpendicular to the plane, e.g. for "Align plane".
	You are supported by one or two activation windows when you position the rotary axes (see Sec."Corrections after measuring the zero point").
	You can only select "Rotary axis A, B, C" for the "Angle corr." parameter, if your machine has rotary axes. They must also be assigned to geometry axes in the machine data.
	Please refer to the machine manufacturer's instructions.



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Sequence of operations	 To measure the workpiece zero, the tool must always be perpendicular to the machining plane (e.g. with "Align plane"). In some measuring methods, the workpiece must first be aligned parallel to the coordinate system (set edge, distance 2 edges, rectangular pocket, rectangular spigot). To do this, it may be necessary to perform the measurement in several stages. 1. "Align plane" (to align the tool perpendicular to the plane) 2. "Align edge" (to align the workpiece parallel with the coordinate system) 3. "Set edge", "Distance 2 edges", "Rectangular pocket", or "Rectangular spigot" (to determine the zero point) Or
	 "Align plane" (to align the tool perpendicular to the plane) "Corner", "Holes", or "Spigots" (to align the tool parallel with the coordinate system and define the zero point)
Prepositioning	If you want to preposition a rotary axis before measuring with "Align edge", move the rotary axis so that your workpiece is already approximately parallel to the coordinate system. Set the relevant rotary axis angle to zero with "Set WO" Measurement with "Align edge" will then correct the value for rotary axis offset or include it in the coordinate rotation and align the workpiece edge precisely.
	If you want to preposition your workpiece with "Align edge" prior to measurement, you can set the angle values under "Manual swivel". With "Set zero plane" you transfer the resulting rotations into the active work offset. The measurement with "Align edge" will then correct the value for the coordinate rotations and align the workpiece precisely.
	If the function "Swivel" is set up on your machine, we recommend effecting a swivel motion to zero before starting measurement. In that way, you will ensure that the rotary axis positions comply with the current coordinate system.
Examples	Two typical examples are given below that demonstrate the interaction between and the use of "Measure workpiece" and "Manual swivel" when measuring and aligning workpieces:



Example 1:

Remachining on a cylinder head with 2 holes on an inclined plane.

- 1. Clamp the workpiece
- 2. Insert probes T, S, M and activate the required work offset.
- Preposition workpiece rotate rotary axes manually until the inclined surface is almost perpendicular to the tool axis.
- Manual swiveling Select "direct" swiveling, "Teach rotary axes", and press "Cycle start".
- Manual swiveling Apply "Set zero plane" to store the resulting rotations in the work zero.
- 6. Measure workpiece Apply "Align plane" to correct the alignment of the workpiece.
- 7. Measure workpiece Apply "2 holes" to define the rotation and offset in the XY plane.
- Measure workpiece Apply "Set edge Z" to define the offset in Z.
- 9. Start part program to remachine in AUTO. Start the program with swivel zero.

Example 2:

Measuring workpieces in swiveled position. The workpiece is to be probed in the X direction even though the probe cannot approach the workpiece in the X direction because of an obstructing edge. But with a swivel movement, the measurement in the X direction can be replaced by a measurement in the Z direction.

- 1. Clamp the workpiece
- 2. Insert probes T, S, M and activate the required work offset.



Operation 2.6 Measuring workpiece zero

- Swivel manually With "direct" swiveling enter the required rotary axis positions or with "axis by axis" the required rotations (e.g. Y=-90) and "cycle start".
- Measure the workpiece Apply "Apply edge Z": The measured offset in Z is converted and entered as an X value in the chosen work offset.
- Swivel manually Execute swivel to zero in order to rotate the coordinate system to its initial position.

2.6.1 Measuring an edge



The following options are available to you when measuring an edge:

• Set the edge

The workpiece lies parallel to the coordinate system on the work table. You measure one reference point in one of the axes (X, Y, Z).

Align the edge

The workpiece lies in any direction, i.e. not parallel to the coordinate system on the work table. By measuring two points on the workpiece edge you determine the angle with the coordinate system.

• Distance 2 edges

The workpiece lies parallel to the coordinate system on the work table. You measure distance L of two parallel workpiece edges in one of the axes (X, Y, or Z) and determine its center.



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.	Setting an edge manually	1. Attach any	tool for scratching to the spindle.
	Meas.	2. In "Machine	e Manual" mode, select the "Meas. workp." softkey.
		3. Press the " The "Edge" wi	Edge" softkey. ndow opens with new vertical softkeys.
	°	4. Press the "	Set edge" softkey.
		5. Select "Mea measured v	asurement only", if you only want to display the values.
		 Select "We the zero p 	ork offset" and the work zero in which you want to store oint (e.g. base reference).
		- OR -	
	Work offset	Press the	"Work offset" softkey.
		The "work offs	et list" is displayed.
		Place the	cursor on the chosen work offset (e.g. base reference).
	In manual	Press the	"In manual" softkey.
	X Z	6. Use the so approach tl	tkeys to select in which axis direction you want to ne workpiece first.
		7. Select the workpiece i	measuring direction (+ or -) you want to approach the n.
		8. Specify the approachin	setpoint position of the workpiece edge you are g.
		specificatio	ns of the workpiece edge from the workpiece drawing.
		9. Traverse th	e tool to the workpiece edge.
	Set WO -Or-	10.Press the "	Set WO" or "Calculate" softkey.
		The position o The set positio when "Set WC	f the workpiece edge is calculated and displayed. on of the workpiece edge is stored as the new zero point " is pressed. The tool radius is automatically included in
		Example:	Reference point workpiece edge X1 = -50
			Approach direction: +
			Tool radius = 3 mm
			\Rightarrow vvoik onset X = 53
		11.Repeat the	measurement procedure (steps 6 to 10) for the two

other axes, if necessary.



Operation 2.6 Measuring workpiece zero





Setting an edge automatically



- 1. Attach a 3D probe type tool to the spindle.
- 2. Prepare the measurement (as described under "Setting the edge manually", steps 2 to 8).
- 3. Move the tool up close to the workpiece edge you want to measure.
- 4. Press the "Cycle Start" key.

This starts the automatic measuring process. The position of the workpiece edge is measured.

The position of the workpiece edge is calculated and displayed. The set position of the workpiece edge is stored as the new zero point if you have selected "work offset". The tool radius is automatically included in the calculation.

5. Repeat the measurement procedure (steps 3 to 4) for the two other axes, if applicable.







Operation 2.6 Measuring workpiece zero

Ì	Aligning an edge automatically	1. Attach a 3D probe type tool to the spindle.
		 Prepare the measurement (as described under "Aligning the edge manually", steps 2 to 9). Move the tool up close to the workpiece edge along which you want to measure. Press the "Cycle Start" key.
	Cycle Start	This starts the automatic measuring process. The position of measuring point 1 is measured and stored. The "P1 stored" softkey becomes active".
		5. Repeat the measurement procedure (steps 3 to 4) to measure the second point.
		The position of measuring point 2 is measured and stored. The "P2 stored" softkey becomes active".
	Set WO	6. Press the "Set WO" or "Calculate" softkey.
		The angle between the workpiece edge and reference axis is calculated and displayed. With "Set WO", the workpiece edge now corresponds to the setpoint angle. The calculated rotation is stored in the work offset.
\sim	Measuring the distance	1. Attach any tool for scratching to the spindle.
	between two edges manually	
	between two edges manually	2. In "Machine Manual" mode, select the "Meas. workp." softkey.
	between two edges manually	 In "Machine Manual" mode, select the "Meas. workp." softkey. Press the "Edge" softkey. The "Edge" window opens with new vertical softkeys.
	between two edges manually	 In "Machine Manual" mode, select the "Meas. workp." softkey. Press the "Edge" softkey. The "Edge" window opens with new vertical softkeys. Press the "Distance between 2 edges" softkey.
	between two edges manually	 In "Machine Manual" mode, select the "Meas. workp." softkey. Press the "Edge" softkey. The "Edge" window opens with new vertical softkeys. Press the "Distance between 2 edges" softkey. Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Setting the edge manually", step 5).
	between two edges manually Meas. Meas. Workp. Alternat.	 In "Machine Manual" mode, select the "Meas. workp." softkey. Press the "Edge" softkey. The "Edge" window opens with new vertical softkeys. Press the "Distance between 2 edges" softkey. Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Setting the edge manually", step 5). In "Measuring direction P1", select the measuring direction (+ or -) and the measuring axis in which you first want to approach the workpiece.
	between two edges manually Meas. Meas. Workp. Alternat.	 In "Machine Manual" mode, select the "Meas. workp." softkey. Press the "Edge" softkey. The "Edge" window opens with new vertical softkeys. Press the "Distance between 2 edges" softkey. Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Setting the edge manually", step 5). In "Measuring direction P1", select the measuring direction (+ or -) and the measuring axis in which you first want to approach the workpiece. In "Measuring direction P2" select the measuring direction (+ or -) for the 2nd measuring point. The axis selected in "Measuring direction P1" is displayed
	between two edges manually Meas. Meas. Workp. Alternat.	 In "Machine Manual" mode, select the "Meas. workp." softkey. Press the "Edge" softkey. The "Edge" window opens with new vertical softkeys. Press the "Distance between 2 edges" softkey. Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Setting the edge manually", step 5). In "Measuring direction P1", select the measuring direction (+ or -) and the measuring axis in which you first want to approach the workpiece. In "Measuring direction P2" select the measuring direction (+ or -) for the 2nd measuring point. The axis selected in "Measuring direction P1" is displayed. Specify the setpoint position of the center line between the two workpiece edges.

9. Traverse the tool to the first measuring point.

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	Save P1	10. Press the "Save P1" softkey.
	Save P2	11. Reposition the tool, approach the second measuring point and store the second point.
	Set WO -or-	12. Press the "Set WO" or "Calculate" softkey.
		The distance between the two workpiece edges and the center line are calculated and displayed.
		With "Set WO", the center line now corresponds to the position setpoint.
		The calculated offset is stored in the work offset.
,	Measuring the distance between two edges automatically	1. Attach a 3D probe type tool to the spindle.
	Cycle Start	 Prepare the measurement (as described under "Measuring the distance between two edges manually", steps 2 to 8). Move the tool up close to the workpiece edge along which you want to measure. Press the "Cycle Start" key. This starts the automatic measuring process. The position of measuring point 1 is measured and stored. The "P1 stored" softkey becomes active".
		5. Repeat the measurement procedure (steps 3 to 4) to measure the second point.The position of measuring point 2 is measured and stored. The "P2 stored" softkey becomes active".
	Set WO -OF-	6. Press the "Set WO" or "Calculate" softkey.
		The distance between the two workpiece edges and the center line are calculated and displayed. With "Set WO", the center line now corresponds to the position setpoint.

The calculated offset is stored in the work offset.



2.6.2 Measuring a corner



You can measure workpieces with a 90° angle or with any other angle.

- Measuring a right-angled corner
 The workpiece has a 90° corner and is in any orientation on the
 work table. By measuring three points you can determine the
 corner point in the working plane (X/Y plane) and angle α
 between the reference edge on the workpiece (line through P1
 and P2) and the reference axis (always the 1st axis in the working
 plane).
 - Measuring any corner The workpiece has any corner (not right-angled) and is in any orientation on the work table. By measuring four points you can determine the corner point in the working plane (X/Y plane), angle α between the reference edge on the workpiece (line through P1 and P2) and the reference axis (always the 1st axis in the working plane), and angle β in the corner.
- 1. Attach any tool for scratching to the spindle.
- 2. In "Machine Manual" mode, select the "Meas. workp." softkey.
- 3. Press the "Corner" softkey.

The "Corner" window opens with new vertical softkeys.

4. Press the "right-angled corner" softkey, if you want to measure a right-angled corner.

- OR -

- Press the "any corner" softkey, if you want to measure a corner not equal to 90°.
- Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Measuring an edge manually", step 5).
- 6. Under "Corner", select the type of corner you want to measure (e.g. outside corner) and its position (e.g. position 1).
- 7. Specify the setpoint of the workpiece corner (X0, Y0) you want to measure.
- 8. Traverse the tool to the first measuring point P1 as shown in the help display.


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	Save P1 Save P2 Save P3	 9. Press the "Save P1" softkey. The coordinates of the first measuring point are measured and stored. 10. Reposition the spindle holding the tool each time, approach measuring points P2 and P3 and press the "Save P2" and "Save P3" softkeys.
	Save P4	11. Repeat the procedure to measure the fourth measuring point when you measure "any corner".
	Set WO	12. Press the "Set WO" or "Calculate" softkey.
		The corner point and angles α and β are calculated and displayed. With "Set WO", the corner point now corresponds to the position setpoint. The calculated offset is stored in the work offset.
. ,	Measuring a right- angled/any corner automatically	1. Attach a 3D probe type tool to the spindle.
		 Prepare the measurement (as described under "Measuring a right-angled/any corner manually", steps 2 to 7). Move the tool up close to measuring point P1. Press the "Cycle Start" key.
	Cycle Start	This starts the automatic measuring process. The position of measuring point 1 is measured and stored. The "P1 stored" softkey becomes active".
	Set WO	 Repeat the measurement procedure (steps 3 to 4) to measure points P2 and P3. If you are measuring a corner not equal to 90°, repeat the procedure to measure and store point P4. Press the "Set WO" or "Calculate" softkey.
	` .	The corner point and angles α and α are calculated and displayed. With "Set WO", the corner point now corresponds to the position setpoint. The calculated offset is stored in the work offset.



2.6.3 Measuring a pocket and hole



You can measure rectangular pockets and one or more holes and then align the workpiece.

- Measuring a rectangular pocket The rectangular pocket must be aligned at right-angles to the coordinate system. By measuring four points inside the pocket you can determine the length, width, and center point of the
- Measuring 1 hole

The workpiece is in any orientation on the work table and has one hole. You can determine the diameter and center point of the hole with four measuring points.

Measuring 2 holes

The workpiece is in any orientation on the work table and has two holes. 4 points are automatically measured in both holes and the hole centers are calculated from them. Angle α is calculated from the connecting line between both center points and the reference axis, and the new zero point that corresponds to the center point of the 1st hole is determined.

Measuring 3 holes

The workpiece is in any orientation on the work table and has three holes. 4 points are automatically measured in the three holes and the hole centers are calculated from them. A circle is placed through the three center points. The circle center point and diameter are determined from it. If an angle offset is selected, base angle of rotation α can also be found.

Measuring 4 holes

The workpiece is in any orientation on the work table and has four holes. 4 points are automatically measured in the four holes and the hole centers are calculated from them. Two hole center points are diagonally connected in each case. The point of intersection between the two lines is determined from this. If an angle offset is selected, base angle of rotation α can also be found.

You can only measure 2, 3, and 4 holes automatically.





The length, width, and center point of the rectangular pocket are calculated and displayed.

The set position of the center point is stored as the new zero point if you have selected "work offset". The tool radius is automatically included in the calculation.

Operation 2.6 Measuring workpiece zero



Measuring a hole manually Meas. Jog Jog Meas. J



Measuring a hole automatically



- 1. Attach any tool for scratching to the spindle.
- 2. In "Machine Manual" mode, select the "Meas. workp." softkey.
- 3. Press the "Pocket/Hole" softkey.

The "Pocket/Hole" window opens with new vertical softkeys.

- 4. Press the "1st hole" softkey.
- Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Measuring a rectangular pocket manually", step 5).
- 6. Specify the position setpoints (X0, Y0) of the hole center point.
- 7. Traverse the tool to the first measuring point.
- 8. Press the "Save P1" softkey.

The point is measured and stored.

- 9. Repeat steps 8 and 9 to measure and store measuring points P2, P3, and P4.
- 10.Press the "Set WO" or "Calculate" softkey.

The diameter and center point of the hole are calculated and displayed.

The set position of the center point is stored as a new zero point with "Set WO". The tool radius is automatically included in the calculation.

- 1. Attach a 3D probe type tool to the spindle.
- 2. Move the tool until it is positioned approximately at the center of the hole.
- 3. Prepare the measurement (as described under "Measuring a hole manually", steps 2 to 6).
- Enter a "Øhole" and the approximate diameter. This limits the area for rapid traverse. If no diameter is entered, travel starts from the starting point at measurement feedrate.
- Enter an angle under "Probe angle".
 With the probe angle you can turn the travel direction of the probe any angle.
- 6. Press the "Cycle Start" key.

The tool automatically contacts 4 points in succession around the inside wall of the hole. When measurement has been successfully completed, the "P0 stored" softkey becomes active.

The diameter and center point of the hole are calculated and displayed.

The set position of the center point is stored as the new zero point if you have selected "work offset". The tool radius is automatically included in the calculation.



Measuring two holes automatically



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- 1. Attach a 3D probe type tool to the spindle.
- 2. Move the tool until it is positioned approximately at the center of the first hole.
- 3. In "Machine Manual" mode, select the "Meas. workp." softkey.
- 4. Press the "Pocket/Hole" softkey.
- The "Holes" window opens with new vertical softkeys.
- 5. Press the "2 holes" softkey.
- Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Measuring an edge manually", step 5).
- 7. Enter the approximate diameter in "Øhole" (see step 4, "Measuring two holes manually".
- 8. Under "Angle offs.", select the "Coor. Rotation" entry. OR -
- > Under "Angle offs.", select the "Rotary axis A, B, C" entry.
- 9. Enter the setpoint angle.
- 10.Specify the position setpoints (X1/Y1) for the center point of the first hole.

X1 and Y1 are only active, if the "Coor. Rotation" entry is selected. 11.Press the "Cycle Start" key.

The tool automatically contacts 4 points in succession around the first inside wall of the hole. When measurement has been successfully completed, the "P1 stored" softkey becomes active.

12. Then move the tool approximately to the center of the hole and press the "Cycle Start" button.

The tool automatically contacts 4 points in succession around the second inside wall of the hole. When measurement has been successfully completed, the "P2 stored" softkey becomes active.

13.Press the "Set WO" or "Calculate" softkey.





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With "Set WO", the center point of the first hole now corresponds to the position setpoint. The calculated rotation is stored in the work offset.



Measuring three holes automatically









- 1. Attach a 3D probe type tool to the spindle.
- 2. Move the tool until it is approximately at the center of first the hole.
- 3. In "Machine Manual" mode, select the "Meas. workp." softkey.
- 4. Press the "Pocket/Hole" softkey.

The "Pocket/Hole" window opens with new vertical softkeys.

- Press the "3 holes" softkey.
- Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Measuring an edge manually", step 5).
- 6. Enter the approximate diameter in "Øhole" (see step 4, "Measuring two holes manually").
- 7. Under "Angle offs.", select entry "No".
- OR -
- Under "Angle offs." select entry "Yes", if you want alignment to be performed with coordinate rotation.
- 8. Enter the setpoint angle.

The angle entered here refers to the 1st axis of the working plane (X/Y plane). This input field only appears if you specified "Yes" for "Angle offs."

9. Specify setpoint positions X0 and Y0.

These determine the center point of the circle on which the center points of the three holes are to lie.

10.Press the "Cycle Start" key.

The tool automatically contacts 4 points in succession around the first inside wall of the hole. When measurement has been successfully completed, the "P1 stored" softkey becomes active.

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Operation**2.6** Measuring workpiece zero







 Specify setpoint positions X0 and Y0. These determine the point of intersection of the lines connecting the hole center points.

10.Press the "Cycle Start" key.

The tool automatically contacts 4 points in succession around the first inside wall of the hole. When measurement has been successfully completed, the "P1 stored" softkey becomes active.

11. Then move the tool approximately to the center of the second, third, and fourth hole and press the "Cycle Start" key.

The tool automatically contacts 4 points in succession around the inside walls of the holes. When measurement of P2, P3, and P4 has been successfully completed, the "P2 stored", "P3 stored", and "P4 stored" softkeys become active.

12. Press the "Set WO" or "Calculate" softkey.

The hole center points are connected diagonally and the intersection point of the two connecting lines calculated and displayed If you selected entry "Yes" for "Angle offs.", angle α is additionally calculated and displayed.

With "Set WO", the intersection point now corresponds to the position setpoint. The calculated rotation is stored in the work offset.

2.6.4 Measuring a spigot



You can measure and align rectangular spigots, and one or more circular spigots.

- Measuring a rectangular spigot
 The rectangular spigot must be aligned at right-angles to the coordinate system. By measuring four points inside the spigot you can determine the length, width, and center point of the spigot.
- Measuring 1 circular spigot
 The workpiece is in any orientation on the work table and has one spigot. You can determine the diameter and center point of the spigot with four measuring points.
- Measuring 2 circular spigot
 The workpiece is in any orientation on the work table and has two
 spigots. 4 points are automatically measured at the two spigots
 and the spigot centers are calculated from them. Angle α is
 calculated from the connecting line between both center points
 and the reference axis, and the new zero point that corresponds
 to the center point of the first spigot is determined.

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The workpiece is in any orientation on the work table and has three spigots. 4 points are automatically measured at the three spigots and the spigot centers are calculated from them. A circle is placed through the three center points and the circle center and circle diameter are determined.

If an angle offset is selected, base angle of rotation α can also be found.

Measuring 4 circular spigot The workpiece is in any orientation on the work table and has two spigots. 4 points are automatically measured at the four spigots and the spigot centers are calculated from them. Two spigot center points are each connected diagonally and the intersection point of the two lines is then determined. If an angle offset is selected, base angle of rotation α can also be found.

You can only measure 2, 3, and 4 circular spigots automatically.



- 2. In "Machine Manual" mode, select the "Meas. workp." softkey.
- 3. Press the "Spigot" softkey.
- 4. Press the "Rectangular spigot" softkey.
- 5. Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Measuring an edge manually", step 5).
- 6. Specify the position setpoints (X0/Y0) of the spigot center point P0.
- 7. Traverse the tool to the first measuring point.
- 8. Press the "Save P1" softkey.

The point is measured and stored.

9. Repeat steps 7 and 8 to measure and store measuring points P2, P3, and P4.

10.Press the "Set WO" or "Calculate" softkey.

The length, width, and center point of the rectangular spigot are calculated and displayed.

The set position of the center point is stored as a new zero point with "Set WO". The tool radius is automatically included in the calculation.

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spigot manually		
M M Jog	Meas.	
°Õ°		



Operation 2.6 Measuring workpiece zero



⇒	Measuring a rectangular spigot automatically	1. Attach a 3D probe type tool to the spindle.
	Cycle Start	 Move the tool until it is approximately at the center of the spigot. Prepare the measurement (as described under "Measuring a rectangular spigot manually", steps 2 to 6). Enter the infeed value in "DZ" to determine the measuring depth. In field "L" enter the length (1st axis of the working plane) and in "W" (2nd axis of the working plane) enter the width of the spigot, if the measuring stroke would not reach the edges. Press the "Cycle Start" key. The tool automatically contacts 4 points in succession around the outside wall of the spigot. The length, width, and center point of the rectangular spigot are calculated and displayed. The set position of the center point is stored as the new zero point if you have selected "work offset". The tool radius is automatically included in the calculation.
3	Measuring a circular spigot manually	1. Attach any tool for scratching to the spindle.
	Meas. Jog	2. In "Machine Manual" mode, select the "Meas. workp." softkey.
	ŵ	3. Press the "Spigot" softkey.
	• ् •	4. Press the "1 circular spigot" softkey.
		 Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Measuring an edge manually", step 5).
		 Enter the infeed value in "DZ" to determine the measuring depth. Specify the position setpoints (X0 and Y0) of the spigot center point P0
		 8. Traverse the tool to the first measuring point on the spigot outside wall.
	Save P1	9. Press the "Save P1" softkey.
	Save P2 Save P4	10.Repeat steps 8 and 9 to measure and store measuring points P2, P3, and P4.







11.Press the "Set WO" or "Calculate" softkey.

The diameter and center point of the spigot are calculated and displayed.

The set position of the center point is stored as a new zero point with "Set WO". The tool radius is automatically included in the calculation.

- 1. Attach a 3D probe type tool to the spindle.
- 2. Move the tool until it is approximately at the center of the spigot.
- 3. Prepare the measurement (as described under "Measuring a circular spigot manually", steps 2 to 7).
- In "Øspigot", enter the approximate diameter of the spigot.This limits the area for rapid traverse. If no diameter is entered, Travel starts from the starting point at measurement feedrate.
- 5. Enter an angle in "Probing angle" (see step 5, "Measuring one hole automatically").
- 6. Press the "Cycle Start" key.

The tool automatically contacts 4 points in succession around the outside wall of the spigot. When measurement has been successfully completed, the "P0 stored" softkey becomes active.

The diameter and center point of the spigot are calculated and displayed.

The set position of the center point is stored as the new zero point if you have selected "work offset". The tool radius is automatically included in the calculation.

- 1. Attach a 3D probe type tool to the spindle.
- 2. Move the tool until it is approximately at the center of the first spigot.
- 3. In "Machine Manual" mode, select the "Meas. workp." softkey.
- 4. Press the "Spigot" softkey.
- 5. Press the "2 circular spigots" softkey.
- Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Measuring an edge manually", step 5).



Operation 2.6 Measuring workpiece zero







() Alternat.







Set WO		Calculate
	-or-	
	•••	

- Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Measuring an edge manually", step 5).
- Enter the approximate diameter of the spigot in "Øspigot" (see step 4, "Measuring one spigot automatically").
- 7. Enter the infeed value in "DZ" to determine the measuring depth.
- 8. Under "Angle offs." select entry "No".
- OR -
- Under "Angle offs." select entry "Yes" if you want alignment to be performed with coordinate rotation.
- 9. Enter the setpoint angle.

The angle entered here refers to the 1st axis of the working plane (X/Y plane). This input field only appears if you specified "Yes" for "Angle offs."

10.Specify setpoint positions X0 and Y0.

These determine the center point of the circle on which the center points of the three spigots are to lie.

11.Press the "Cycle Start" key.

The tool automatically contacts 4 points in succession around the first outside wall of the spigot. When measurement has been successfully completed, the center of the spigot is determined and the "P1 stored" softkey becomes active.

12. Then move the tool approximately to the center of the second and third spigot and press the "Cycle Start" button.

The tool automatically contacts 4 points in succession around the spigot outside walls. After successful completion of measurement, measured values P2 and P3 are stored and the softkeys "P2 stored" and "P3 stored" become active.

13.Press the "Set WO" or "Calculate" softkey.

The center point and the diameter of the circle on which the three spigot center points lie are calculated and displayed. If you have selected "Yes" in "Coor. rot.", angle α is additionally calculated and displayed.

With "Set WO", the center point of the circle now corresponds to the position setpoint. The calculated rotation is stored in the work offset.





The tool automatically contacts 4 points in succession around the spigot outside walls. After successful completion of measurement, measured values P2, P3, and P4 are stored and the softkeys "P2 stored", "P3 stored", and "P4 stored" become active.





13. Press the "Set WO" or "Calculate" softkey.

The spigot center points are connected diagonally and the intersection point of the two connecting lines calculated and displayed If you have selected "Yes" in "Coor. rot.", angle α is additionally calculated and displayed.

With "Set WO", the intersection point now corresponds to the position setpoint. The calculated rotation is stored in the work offset.

You can measure an inclined plane of a workpiece in space and determine rotations α and β . By subsequently performing coordinate rotation, you can align the tool axis perpendicular to the workpiece

In order to determine the position of the plane in space, three different

To align the tool axis in the perpendiculary you require a swiveling

In order to be able to measure the plane, the surface must be flat.

2.6.5 Aligning the plane



R



Aligning a plane manually

Save P1

Save P2

0 Meas. Sworkp 1. Attach any tool for scratching to the spindle.

points are measured along the tool axis.

- 2. In "Machine Manual" mode, select the "Meas. workp." softkey.
- 3. Press the "Align plane" softkey.

plane.

table or swivel head.

- Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Measuring an edge manually", step 5).
- 5. Traverse the tool to the first measuring point that you want to determine.
- 6. Press the "Save P1" softkey.
- 7. Then move the tool to the second and third measuring point and press the "Save P2" and "Save P3" softkeys.

Save P3



Operation 2.6 Measuring workpiece zero





8. Press the "Set WO" or "Calculate" softkey.

Angles α and β are calculated and displayed. With "Set WO" the angle offset is stored in the work offset memory.

- 1. Attach a 3D probe type tool to the spindle.
- 2. Traverse the tool to near the point you want to determine first.
- 3. In "Machine Manual" mode, select the "Meas. workp." softkey.
- 4. Press the "Align plane" softkey.
- Specify whether you want "Measurement only" or in which work offset you want to store the zero point (as described under "Measuring an edge manually", step 5).
- 6. Press the "Cycle Start" key.

When measurement has been successfully completed, the measured value is stored and the "P1 stored" softkey becomes active.

7. Then move the tool so that it is approximately above the second and then the third measuring point and press the "Cycle Start" button.

When measurement is complete, the "P2 stored" and "P3 stored" softkeys becomes active.

8. Press the "Set WO" or "Calculate" softkey.

Angles α and β are calculated and displayed. With "Set WO" the angle offset is stored in the work offset memory.



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2.6.6 Corrections after measurement of the zero point

	 If you store the workpiece zero in a work offset, changes to the coordinate system or axis positions might be necessary in the following cases. Correcting the work offset causes the workpiece coordinate system to rotate, after which the tool can be aligned perpendicularly to the plane. Correcting the work offset necessitates positioning of the rotary axis in order to align the workpiece parallel with the coordinate system Activation windows help you to adapt the coordinate system and the axis positions.
Activating work offset Set WO Image: Constraint of the set wo	You stored the workpiece zero in a work offset that was not active during measurement. When you press the "Set WO" softkey, the activation window opens asking whether you want to "Activate work offset xxx now?". ➤ Press the "OK" softkey to activate the corrected work offset.
Aligning and retracting the tool	 Rotating the workpiece coordinate system makes it necessary to realign the tool to the plane. The activation window asking whether you want to "Position measuring probe perpendicular to plane?" is displayed. > Select "Yes" if you want to swivel into the plane.
O Alternat.	 The query "Positioning by swiveling! Retract?" appears. Select the retract method you want to use. Press the "Cycle Start" key. When the axis has been retracted the tool is realigned with the help of
	Activating work offset Set WO Set WO Aligning and retracting the tool Aliternat. Alternat.

You can now measure again.



Positioning a rotary axis and entering a feedrate	Once you have measured the workpiece zero you must reposition the rotary axis.
	axis X to align?" is displayed.
O Alternat.	 Select "Yes" if you want to position the rotary axis.
	An input field for the feedrate and the softkey "Rapid traverse" are displayed.
Rapid traverse	Press the "Rapid traverse" softkey to enter the feedrate in rapid traverse.
	- OR -
	Enter the desired offset in input field "F".
\bigcirc	Press the "Cycle Start" key.
Cycle Start	The rotary axis is repositioned.
	Positioning a rotary axis and entering a feedrate

2.6.7 Calibrating an electronic measuring tool



When the electronic measuring tools are attached to the spindle, clamping tolerances often occur. This can lead to measurement errors.

In addition, you need to determine the trigger point of the measuring tool relative to the spindle center (trigger point).

Therefore, you need to calibrate the electronic measuring tool. The radius is calibrated in a hole, the length is calibrated on a surface. For the hole, you can use a hole in the workpiece or use a ring gauge. The radius of the measuring tool must be contained in the tool list.



Calibrating a radius



- 1. Attach a 3D probe type tool to the spindle.
- 2. Move the tool into the hole and position it in the approximate center of the hole.
- 3. In "Machine Manual" mode, select the "Meas. workp." softkey.
- 4. Press the "Calibration probe" and "Radius" softkeys.



Cycle Start



6. Press the "Cycle Start" key.

Calibration starts. First the exact hole center point is determined. Then the 4 trigger points on the inside wall of the hole are approached.

Calibrating a length



- 1. Attach a 3D probe type tool to the spindle.
- 2. Position the tool above the surface.
- 3. In "Machine Manual" mode, select the "Meas. workp." softkey.
- 4. Press the "Calibration probe" and "Length" softkeys.
- 5. Specify reference point Z0 of the surface, e.g. of the workpiece or the machine table.
- 6. Press the "Cycle Start" key.

Calibration starts. The length of the measuring tool is calculated and entered in the tool list.

M M Jog	Meas.
Calibration probe	Length

\Diamond	
Cycle Start	



2.7 Measuring a tool

The various tool geometry parameters must be referenced while the program is running. These are stored as so-called tool offset data in the tool list. Each time the tool is called, the control considers the tool offset data.

You can determine the tool offset data, i.e. the length and radius or diameter, either manually or automatically (per measuring probe).

2.7.1 Measuring a tool manually

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For manual measurement, move the tool manually to a known reference point to determine the tool length and the radius and diameter. ShopMill then calculates the tool offsets from the position of the toolholder reference point and the reference point.

When measuring the tool length you can either use the workpiece or a fixed point in the machine coordinate system, e.g. a mechanical test socket or a fixed point in combination with a distance gauge as the reference point.

You can enter the position of the workpiece during measurement. The position of the fixed point on the other hand must be specified before you start measurement (see Section "Adjusting the fixed point").

When determining the radius/diameter, the workpiece is always the reference point.

Depending on the setting in a machine data, you can measure the radius or the diameter of the tool.

Please refer to the machine manufacturer's instructions.



Measuring length Workpiece reference point



- > Attach the tool you want to measure to the spindle.
- Select the "Measure tool" softkey in "Machine Manual" mode.
- > Press the "Length manual" softkey.
- Select the tool cutting edge D and the duplo number DP for the tool.



> Select the "Workpiece" reference point.



Measuring the tool length on the edge of the workpiece

- Approach the workpiece in the Z direction and perform scratching with a rotating spindle (see Sec. "Traversing the Machine Axes").
- > Specify the setpoint position Z0 of the workpiece edge.
- > Press the "Set length" softkey.

The tool length is calculated automatically and entered in the tool list.

If you want to determine the tool length not with a workpiece, but with a test socket instead, no work offset may be selected, or the basic work offset must be zero.

- Attach the tool you want to measure to the spindle.
- > Select the "Measure tool" softkey in "Machine Manual" mode.
- > Press the "Length manual" softkey.
- Select the tool cutting edge D and the duplo number DP for the tool.
- > Select the "fixed point" reference point.

Set length

Н

⇒

point

₩ N Jog	Meas.
Length manual >]

Measuring length Fixed point reference





Measuring the tool length on the measuring edge

 If you are measuring with a test socket, enter 0 for offset value "DZ" and approach the fixed point in the Z direction (see Sec."Traversing the machine axes").

Approach is performed with a rotating spindle in the opposite direction of rotation. The test socket automatically displays a reading when the precise position is reached.

- OR -

If you are using a distance gauge, travel as close to the fixed point as possible, measure the gap with the distance gauge and enter the value in "DZ".

Approach to the distance gauge is performed with a stationary spindle.

Press the "Set length" softkey.

The tool length is calculated automatically and entered in the tool list.



- > Select the "Measure tool" softkey in "Machine Manual" mode.
- > Press the "Radius manual" or "Dia. manual" softkey.
- Select the tool cutting edge D and the duplo number DP for the tool.

Set length

Measuring a radius/diameter



W M Jog	Meas.
Jog	tool

 Jog
 I
 tool

 Radius manual
 > or
 Dia. manual
 Approach the workpiece in the X or Y direction and perform scratching with the spindle rotating in the opposite direction (see Sec. "Traversing the machine axes").



Measuring radius/diameter

- > Specify the setpoint position X0 or Y0 of the workpiece edge.
- Press the "Set radius" or "Set diameter" softkey.

The tool radius or diameter is calculated automatically and entered in the tool list.

2.7.2 Calibrating a fixed point

If you want to use a fixed point as the reference point in manual measurement of the tool length, you must first determine the position of the fixed point relative to the machine zero.

You can use a mechanical test socket as the fixed point, for example. Mount the test socket on the machine table in the machining space of the machine. Enter zero as the distance.

But you can also use any fixed point on the machine in combination with a distance gauge. Enter the thickness of the plate in "DZ".

To calibrate the fixed point either use a tool of known length (i.e. the tool length must have been entered in the tool list) or the spindle directly.

The position of the fixed point may have already been determined by the machine manufacturer.

Please refer to the machine manufacturer's instructions.





Operation 2.7 Measuring a tool



- > Traverse the tool or spindle to the fixed point.
- > Select the "Measure tool" softkey in "Machine Manual" mode.

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Press the "Calibrate fixed point" softkey.

Enter an offset value for "DZ".

If you have used a distance gauge, enter the thickness of the plate used.

Press the "Calibrate" softkey.

The distance dimensions between machine zero and fixed point is calculated and entered in the machine data.

2.7.3 Measuring a tool with measuring probe

For automatic measurement, you determine the length and radius or diameter of the tool with the aid of a measuring probe (table probe system). ShopMill uses the known positions of the tool carrier reference point and measuring probe to calculate the tool offset data.

Before you measure a tool automatically, you must enter the approximate tool geometry data (length and radius or diameter) in the tool list and calibrate the probe.

Depending on the setting in a machine data, you can measure the radius or the diameter of the tool.

Please refer to the machine manufacturer's instructions.

You can consider a lateral or longitudinal offset V when measuring. If the maximum length of the tool is not at the outer edge of the tool or the maximum width is not at bottom edge of the tool, you can store this difference in the offset.





Longitudinal offset

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10.04

If measuring shows that the length of the tool diameter is greater than the probe diameter, measurement is automatically performed with a turning spindle rotating in the opposite direction. The tool is not traversed across the center of the probe but with the outside edge of the tool along the center point of the measuring probe.

Measuring length

- \geq Attach the tool you want to measure to the spindle.
- \triangleright Position the tool near the measuring probe so that it can be approached without collision.









Measuring tool length

- Select the "Measure tool" softkey in "Machine Manual" mode. ≻
- Press the "Length Auto" softkey. \triangleright
- \triangleright Select the tool cutting edge D and the duplo number DP for the tool.
- If necessary, enter the lateral offset V. \triangleright
- Press the "Cycle Start" key. \triangleright

This starts the automatic measuring process. The tool length is calculated automatically and entered in the tool list.

The measuring process depends on settings made by the machine manufacturer.

Please refer to the machine manufacturer's instructions.



Measuring radius/ diameter

- > Attach the tool you want to measure to the spindle.
- Position the tool near the measuring probe so that it can be approached without collision.





Mea	asuring radius/diameter
\triangleright	Select the "Measure tool" softkey in "Machine Manual" mode.

- > Then press the softkey "Radius Auto" or "Dia. Auto".
- Select the tool cutting edge D and the duplo number DP for the tool.
- > Enter the longitudinal offset V, if necessary.
- Press the "Cycle Start" key.

This starts the automatic measuring process. Measurement is performed with a spindle rotating in the opposite direction. The tool radius or diameter is calculated automatically and entered in the tool list.

The measuring process depends on settings made by the machine manufacturer.

Please refer to the machine manufacturer's instructions.

\Diamond
Cycle Start

2.7.4 Calibrating a measuring probe



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Mechanical tool measuring probes are typically shaped like a cube or a cylindrical disk. Install the probe in the working area of the machine (on the machine table) and align it relative to the machining axes.

You must use a mill-type calibration tool to calibrate the measuring probe. You must enter the length and radius/diameter of the tool in the tool list beforehand.

- Move the calibration tool until it is approximately over the center of the measuring surface of the probe.
- > Select the "Measure tool" softkey in "Machine Manual" mode.
- > Press the "Calibrate measuring calipers" softkey.
- Choose whether you want to calibrate the length or the length and the diameter.





Comparing length and diameter

Calibrating length only

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Press the "Cycle Start" key.

Calibration is automatically executed at the measuring feedrate. The distance measurements between the machine zero and measuring probe are calculated and stored in an internal data area.

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Cal. meas.

calipers >

Meas. tool





In manual mode you can:

- 1. Synchronize the measuring system of the control with the machine (reference point approach),
- 2. Set up the machine, i.e. activate manually controlled motions on the machine using the keys and handwheels provided on the machine control panel.
- 3. Activate manually controlled motions on the machine using the keys and handwheels provided on the machine control panel while a part program is interrupted.

2.8.1 Selecting a tool and attaching it to the spindle



For the preparatory work in manual mode, tool selection is performed centrally in a screenform.





> Select the "T, S, M" softkey in "Machine Manual" mode.

The cursor is positioned on the input field of tool parameter "T":

Enter the name or the number of the tool T.

T D1

- -OR-
- Call up the tool list by pressing the "Tools" softkey or the "Offset" key.
- > Place the cursor on the required tool in the tool list.

-AND-

> Press the "In manual" softkey.

The tool is transferred to the "T, S, M... window" and displayed in the field of tool parameter "T".

- > Select tool edge D or enter the number directly in field "D".
- > Press the "Cycle Start" key.

The tool is attached to the spindle.

2.8.2 Entering a tool in the list and attaching it to the spindle

10.04

Preparing for loading



Select the "T, S, M" softkey in "Machine Manual" mode.

The cursor is positioned on the input field of tool parameter "T".

Entering tool in tool list



- > Press the "Offset" or "Tools" softkey to open the tool list.
- > Enter a new tool (as described in Sec. "Tools and tool offsets").
- > Press the "In manual" softkey.

You automatically return to function "T,S,M, \dots ". The tool name is now entered in the input field of tool parameter "T".

Performing a tool change





Press the "Cycle Start" key.

Tool change is enabled. The loaded tool is marked by a spindle symbol in the tool list.

Now load the tool manually into the spindle as described in the machine manufacturer's instruction manual.

Operation 2.8 Manual mode

2.8.3 Entering a new tool in the list and loading it in the magazine



Setting the spindle speed



- > Select the "T, S, M" softkey in "Machine Manual" mode.
- Enter the spindle speed value of your choice in the "Spindle" input field.



Press the "Cycle Start" key.

If the spindle is already running the new speed is accepted. If the spindle is stationary, the value is stored as the setpoint speed. The spindle remains stationary.



Starting the spindle.



T.S.M

T,S,M



Jog

SELECT



The spindle is started according to the preselected spindle speed and the current spindle override weighting. You can stop the spindle again by pressing the "Spindle Stop" key.

- OR -

 \geq

- Select the "T, S, M" softkey in "Machine Manual" mode
- > In "Spindle M Fct.", select spindle direction of rotation





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Jog

)

Cycle Start

SELECT

The spindle rotates.

- > Select the "T, S, M" softkey in "Machine Manual" mode.
- In "Spindle M Fct.", select "Off".
- > Press the "Cycle Start" key.

Press the "Cycle Start" key.

The spindle stops.

Positioning the spindle

Stopping the spindle





The spindle position is specified in degrees.

- Select the "T, S, M" softkey in "Machine Manual" mode.
- Select "Spindle M Fct." Stop Pos.".

Input field "Stop Pos." appears."

> Enter the desired spindle stop position.

The spindle position is specified in degrees. The spindle is turned to the selected position when you press "Cycle

Start".

You can use this function to position the spindle at a specific angle, e.g. during a tool change.

- A stationary spindle is positioned via the shortest possible route.
- A rotating spindle is positioned as it continues to turn in the same direction.



	Changing the spindle speed	
		Set the spindle speed with the spindle override switch. You can select 50 to 120% of the value that last applied.
		- OR - (on operator panel OP032S):
		Press the "Spindle Dec." or "Spindle Inc." key.
	Spindle Dec. Spindle Inc.	The programmed spindle speed (100%) is increased or decreased.
	100%	Press the "100%" key.
		The spindle speed is reset to the programmed spindle speed.
2.8.5	Traversing axes	
		You can traverse the axes in manual mode via the Increment and Axis keys or handwheels. During a traverse initiated from the keyboard, the selected axis moves by a specified increment with the programmed setup feedrate.
3*	Traversing the axes using the keyboard	By pressing the increment keys, you can move the selected axis in defined increments in the appropriate direction every time you press an "Axis key" in manual mode. The axes themselves traverse at the programmed setup feedrate.
	Presetting increments	
	1 1 10000	 Press keys [1], [10],, [10000] to move the axes through a defined increment. The numbers on the keys indicate the traverse path in micrometers or micro-inches. Example: For an increment of 100 μm (= 0.1 mm), press the "100" key.
		-or-
	The second secon	Open the extended horizontal softkey menu in "Machine Manual" mode.
	IŸ ShopM.	Press the "ShopM sett." softkey.
	UN SELL.	The settings menu opens.





Traversing axes usingPleasethe handwheelsthe sele

Please note the machine manufacturer's instructions with regard to the selection and mode of operation of handwheels.



2.8.6 Positioning axes



2.8.7 Swiveling



In "Machine Manual", you can move the axes to certain positions for the purpose of performing simple machining operations.

- Select the "Position" softkey in "Machine Manual" mode.
- Select the axis or axes to be traversed with the "cursor up" and "cursor down" keys.
- Select the axis or axes to be traversed and enter the target position(s).
- > Enter a feedrate in field "F".

- OR -

Press the "Rapid traverse" softkey if the axes are to be traversed in rapid traverse.

The rapid traverse is displayed in field "F".

- Press the "Cycle Start" key.
 - The axes are moved to the specified target position.

The axes are moved to the specified target position.

Manual swiveling provides functions that make setup, measuring, and machining of workpieces with inclined surfaces considerably easier.

If you want to create or correct an inclined position, the required rotations of the workpiece coordinate system around the geometry axes (X, Y, Z) are automatically converted to suitable positions of the swivel axes (A, B, C).

If you use manual swiveling, you can program the swivel axes of the machine directly and generate a matching coordinate system for those swivel axis positions.

If the swivel plane is active, the "Workpiece zero" function is operative but not the "Measure tool" function.

The swiveled coordinates are retained in reset state and even after power ON, i.e. you can still retract from an inclined hole by retracting in +Z direction.

Please refer to the machine manufacturer's instructions.



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	Moving clear	The following provides an explanation of the most important parameters for swiveling: Before swiveling the axes you can move the tool to a safe retraction position. The retraction options available to you are defined when setting up the swivel data block in the "retraction position" parameter.
\triangle		Warning
		You must select a retraction position that does not cause the tool and workpiece to collide in a swivel action.
	Swivel methods	 Swiveling can be axis by axis or direct. Axis-by-axis swiveling is based on the coordinate system of the workpiece (X, Y, Z). The coordinate axis sequence can be selected freely. The rotations are applied in the selected order. ShopMill calculates the rotation of the rotary axes (A, B, C) based on those values. In direct swiveling, the positions of the rotary axes are specified. ShopMill calculates a suitable new coordinate system based on those values. The tool axis is aligned in the Z direction. You can derive the resulting direction of the X and Y axis by traversing the axes.
H		The positive direction of each rotation for the different swivel methods is shown in the help displays.
	Direction	In swivel systems with 2 rotary axes, a particular plane can be reached in two different ways. You can choose between these two different positions in the "Direction" parameter. +/- refers to the larger or smaller value of a rotary axis. This may affect the working area. When setting up the swivel data block, the entries you make in the "Direction" parameter determine for which rotary axis you can choose between the two settings.
		Please refer to the machine manufacturer's instructions.
	Fixing the tool tip	If one of the two positions cannot be reached for mechanical reasons, the alternative position is automatically selected irrespective of the setting in the "Direction" parameter. To avoid collisions, you can use the 5-axis transformation (software option) to retain the position of the tool tip during swiveling. This function must be enabled when you set up "Swivel" in the "Correction T" parameter.
		Please reter to the machine manufacturer's instructions.



Zero plane

You can use the "Manual swiveling" function both for machining and for setting up, to compensate for workpiece rotations when they are being clamped (base angle of rotation).

If you want to use the current swiveled plane as the reference plane for setting up your workpiece, you must define this plane as the zero plane.

With "Set zero plane" the current swivel plane in the active work offset is stored as the zero plane. As a result, the rotations in the active work offset are overwritten.

With "Delete zero plane", the active zero plane is deleted from the work offset. This sets the rotations in the active work offset to zero. The overall coordinate system does not change with "Set zero plane" or "Delete zero plane".

You can also use manual swivel in conjunction with "Align plane" to measure a workpiece.



- > Select the "Swivel" softkey in "Machine Manual" mode.
- > Enter values for the parameters.
- > Press the "Cycle Start" key.

The "Swivel" cycle is started.

- Press the "Delete values" to restore the initial state, i.e. to reset the values to 0.
 Perform this step, for example, to swivel the coordinate system back to its original position.
- Press the "Set zero plane" softkey to set the current swivel plane to the new zero plane.
- Press the "Delete zero plane" softkey to delete the current swivel plane.
- Select the "Teach rotary axis" softkey to accept the current positions of the rotary axes during direct swiveling.
2

2

10.04

	Parameters	Description		Unit
	тс	Name of the swivel data block		
		O: Remove swivel head, deselect swivel data block		
		No entry: No change to set swivel data block		
Move clear No: Do not retract tool before swiveling				
	Z: Move tool axis to retraction position before swiveling		ling	
		Z, X, Y: Move machining axes to retraction position	before swiveling	
		Tool max: Retract tool in tool direction to software lin	mit switch	
		Tool inc: Retract tool incrementally in tool direction I	by the entered value	
	Swivel plane	Swivel new: Define new swivel plane		
Swivel additive: Place swivel plane on last swivel plane Swivel method Axial: Swivel coordinate system axially Direct: Position rotary axes directly		ane		
		Direct: Position rotary axes directly		
	X Axis angle (swivel axially) The sequence of axes		The sequence of axes	Degr.
	Y	Axis angle (swivel axially)	can be changed to any order	Degr.
	Z	Axis angle (swivel axially)	with "Alternat.".	Degr.
	A	Axis angle (swivel directly)		
	В	Axis angle (swivel directly)		
	Direction	Preferred direction of rotation given 2 alternatives		
		+: Larger angle of axis on scale for swivel head/table		
		-: Smaller angle of axis on scale for swivel head/table		
	Fix tool tip	Follow-up: The position of the tool tip is maintained	during swiveling.	
		No follow-up: The position of the tool tip changes du	iring swiveling.	

Face

mill.



You can use this cycle to face mill any workpiece. A rectangular surface is always machined.

For further information about the cycle, see Sec. "Programming - Face milling".

- > Select the "Face mill." softkey in "Machine Manual" mode.
- Press the relevant softkey to specify the lateral limitations of the workpiece.
- Place the cursor in "Machine" and with the "Select" key choose a machining type (e.g. roughing).
- > Place the cursor in "Direction" and select the machining direction.
- > Enter all other parameters in the input screen.

Please also note instructions regarding face milling in Sec. "Programming - Face Milling".

> Press the "OK" softkey to confirm your entries.

Return to the program view in the Manual area.

🗂 MANUAL				
∥ Reset				
WCS	Position [mm		TES	
X	5.000		Т	ä1z ;×
Y Z	10.000		F 1.000	100%? mm/tooth
A C	0.000 0.000		S 0.000 0.000	■ 90% / I
			0%	80% 100%
⊊ Face mill	ling ⊽ T=FA	ING TOOL F1/t Y	22M X0=44 Y0=25	Z0=0
				Abort
, т,ѕ,м	Set VO Weas.	Tool 👌 S	wivel Posi- tion	Face mill.

Example of face milling in the program view

Press the "Cycle Start" key to start the "Face milling" cycle.

You cannot use the "Repos" function while face milling.



Cycle Start



2.8.9 Settings for manual mode







Selecting a gear stage





For manual mode, you can select the central machine functions and work offsets and set the unit of measurement.

Machine functions (M functions) are functions that are additionally provided by the machine manufacturer.

Please refer to the machine manufacturer's instructions.

In manual mode, you can display the axis positions and distancedefining parameters either in "mm" or "inches". However, tool offsets and work offsets remain in the original unit of measurement in which the machine was set (see Sec. "Switching over the unit of measurement millimeter/inch").

If your machine has a separate gear unit for spindles, you can select a gear stage.

- > Select the "T, S, M" softkey in "Machine Manual" mode.
- > Position the cursor in the "Gear stage" field.
- Select the gear stage you want to use (e.g. "auto").

This gear stage will be active the next time you press the "Cycle Start" key.

Selecting an M function



- > Select the "T, S, M" softkey in "Machine Manual" mode.
- Enter the number of the desired M function in the "Misc M fct." parameter field.

Refer to the machine manufacturer's table for the correlation between the meaning and number of the function.

The M function will be active the next time you press the "Cycle Start" key.

Selecting a work offset



- Select the "T, S, M" softkey in "Machine Manual" mode.
- > In the "Work offset" field, enter a work offset (e.g. base).

- OR -

> Press the "Work offset" softkey to open the work offset list.

Operation 2.8 Manual mode

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In manual	Place the cursor on the required zero point and press the "In manual" softkey.
	The work offset will be active the next time you press the "Cycle Sta key.
Setting the unit of measurement	The selected unit of measurement affects the actual value display at distance-defining parameters. The setting applies to the Manual are and remains valid until you switch to the other unit. In Automatic mode, the unit of measurement displayed in the program header is always activated.
₩ М Јод Т, S, M	Select the "T, S, M" softkey in "Machine Manual" mode.
SELECT	Select a unit of measurement from the "Unit of measurement" box.
	The unit of measurement will be active in manual mode the next time you press the "Cycle Start" key.
Selecting a tool axis	If your machine has a swivel-mounted work spindle, you can select the machining plane in the "Tool axis" selection field in menu "T, S, M".
[₩] ₩ Јα Т, 5, м	 This parameter is relevant for all screenforms in the Manual area, i.e it influences the parameter displays for face milling or measurement. In addition, the plane setting determines how tool offsets are calculated in workpiece and tool measurements. Select the "T, S, M" softkey in "Machine Manual" mode.
SELECT	 Select an axis from the "Tool axis" box.
	That tool axis will be active in manual mode the next time you press the "Cycle Start" key.

For instructions on how to swivel the spindle, please refer to the machine manufacturer's instructions.

- S, M" softkey in "Machine Manual" mode.
- measurement from the "Unit of measurement"

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.	Changing the default settings	
		Select the "Expand" softkey in "Machine Manual" mode to expand the softkey bar.
	∥∀ ShopM. ∎⊖ sett.	Press the "ShopM. sett." softkey.
		The ShopMill settings menu opens.
	Retraction plane	In the "Retraction plane" box enter the retraction position above the workpiece to be approached during face milling in rapid traverse in manual mode.
	Safety clearance	 In the "Safety clearance" box, enter the position to which the axis is to traverse in rapid traverse. The safety clearance is the distance between the tool tip and the workpiece surface. As soon as the safety clearance is reached, the programmed face milling cycle is executed at machining feedrate.
	Setup feedrate	In the "setup feedrate" box enter the feedrate with which you want to traverse the axes in manual mode.
	Variable increment	In the "variable increment" box enter an increment for traversing the axes in manual mode not at a fixed increment but at a variable increment.
	K Back	Press the "Back" softkey.
FI		The "ShopMill settings" menu box closes. These settings remain valid until you change them. These settings are made for the programs in the program header.

You can write and execute programs block by block in G code in "MDI" (Manual Data Input) mode. To do this, you enter specific movements as individual program blocks in the control via the keyboard.

The "MDI" program view displays position, feedrate, spindle and tool values as well as the contents of the MDI program.

Reset	G
	function
WCS Position [mm] T,F,S	
Х 5.000 T	function
Y 10.000 F 9 999 1997	A11 G
7. 100.000 mm/min	functions
A 8.000 C 9.000 90%	Run- times
0% 30% 100%	
MDI H	Delete MDI prog.
	5
m32] ==eof==	
f	Act. val. Mach(MCS)

Example of a program in the "MDI" program view

- Press the "MDI" key. \geq
- \geq Enter a G code in the working window.

The control executes the blocks you have entered when you press the "Cycle Start" key.

Deleting the program

Starting the program

Delete MDI prog. Programs written in MDI mode are automatically deleted as soon as they have finished running. Alternatively, you can delete them by selecting softkey "Delete MDI prog.".



 $\langle \hat{} \rangle$

Cycle Start

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2.10 Automatic mode

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Requirements for execution

In the "Machine Auto" operating mode, you can execute machining programs and monitor the progress of the current machining operation online on the screen.

- You have already synchronized the control measuring system with the machine (i.e. "approached" reference points).
- You have already written the relevant machining program.
- You have checked or entered the necessary offset values, such as work offsets or tool offsets.
- 近 AUTO /_N_WKS_DIR/_N_GROEZI_WPD 🖉 Reset G function COUNTER WCS Position [mm] T,F, Auxiliary function х 5.000 т ä↓z Y 10.000 All G function F 100% mm/min RAPID Z 100.000 S 90% Run-times 0.000 0.000 0.000 0.000 A C 80% 100% Basic block Р NS COUNTER Work offs 1 G54 Т N10 T=FRAESER_10 S1000U N15 ; Start mit Eilgang anfahren G N20 RAPID X0 Y0 Z5 Act. val. Mach(MCS) G N25 ; Tiefenzustellung mit Vorschub N30 F200/min Z-5 N35 G64 ; Bahnsteuerbetrieb G Invalid tool name: FRAESER_10 NC Prog. NC Block 2 Over-Real-Prog.
- The required safety interlocks are already active.

Example of program view in "Machine Auto"

Sequential control programs produced with an earlier version of ShopMill can also be executed in the current sequential control version. If an older sequential control program is executed once in the current sequential control version, it is reclassified as being in the current sequential control version.

You can also execute a Version-6.3 sequential control program in ShopMill 6.2, provided that you consider the following points:

- If the machining type "Edge finishing" is programmed for a longitudinal groove in ShopMill 6.3, the parameter is replaced by "Roughing" in ShopMill 6.2.
- The functions "Deep drilling" and "Circumferential slot" programmed under ShopMill 6.3 only run in ShopMill 6.2 if you check the function parameters again in ShopMill 6.2 and confirm these.



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When a ShopMill program with Version 6.3 is executed in ShopMill 6.2, it is deemed to be a Version-6.2 program.

While the workpiece is being machined, if you want to know, for example, whether the tool tip radius compensation is currently active

2.10.1 Switchover between "T, F, S", "G functions" and "Auxiliary functions" displays

		or which unit of measurement is being used, you can activate display of the G functions or auxiliary functions.
=?	G functions	16 different G groups are displayed under "G function". Within a G group, only the G function currently active in the NC is displayed.
		As an alternative, all G groups with all associated G functions are listed in "All G Func.".
	Auxiliary functions	Auxiliary functions include M and H functions preprogrammed by the machine manufacturer, which pass parameters to the PLC to trigger reactions defined by the manufacturer.
		Please refer to the machine manufacturer's instructions. A maximum of five M functions and three H functions are displayed.
П		When executing a sequential control program, you can display the G functions currently active in the NC too, as the ShopMill functions are converted to G code internally.
•	G function	Press the "G function" softkey in "Machine Manual" or "Machine Auto" mode.
		Instead of parameters T, F and S, the currently active G functions within a G group will be displayed. If you press the "G Function" softkey again, the "T, F, S" status display reappears.
		- OR -
	All	Press the "All G func." softkey.
		Instead of parameters T, F and S, all G groups with G functions are now listed. If you select the "All G func." softkey again, the "T, F, S" status display reappears.
		- OR -

 \triangleright Press the "Auxiliary function" softkey.

Instead of parameters T, F and S, the currently active auxiliary functions will be displayed. If you press the "Auxiliary function" softkey again, the "T, F, S" status display reappears.

Auxiliary

function

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2.10.2 Selecting a program for execution



> Press the "Program" softkey or the "Program Manager" key.

The directory overview is displayed.

- Place the cursor on the directory containing the program that you want to select.
- > Press the "Input" or "Cursor right" key.

The program overview is displayed.

- Place the cursor on the required program.
- Press the "Execute" softkey.

ShopMill automatically changes to "Machine Auto" operating mode and uploads the program.

- OR -

> Press the "Program" softkey or the "Program Manager" key.

The directory overview is displayed.

- Place the cursor on the directory containing the program that you want to select.
- Press the "Input" or "Cursor right" key.

The program overview is displayed.

- > Place the cursor on the required program.
- > Press the "Input" or "Cursor right" key.

The selected program is opened in the "Program" operating area. The machining plan of the program is displayed.

- Place the cursor on the program block at which the program run must begin.
- Press the "Execute" softkey.

ShopMill automatically changes to "Machine Auto" manual mode, loads the program and conducts a block search until it reaches the selected program block (see Sec. "Entering a program at any selected point"). When you select a program for the first time for execution, that contains the cycles "Stock removal towards contour" or "Contour pocket", the individual stock removal steps or solid machining steps for the contour pocket are calculated automatically. This process may take several seconds depending on the complexity of the contour.

2.10.3 Starting/stopping/aborting a program

		Shows how to start/stop programs that are loaded in "Machine Auto" operating mode and resume program execution after abnormal program termination.
		Once the program is loaded in "Machine Auto" mode, and "Automatic" mode is also activated on the machine control panel, you can start the program whatever your current operating area, even if you are not in "Machine Auto" mode. This start option must be enabled in a machine data code.
		Please refer to the machine manufacturer's instructions.
	Precondition	No alarms are pending. The program is selected. Feedrate enable is active. Spindle enable is set.
_ →	Starting execution	
	\bigcirc	Press the "Cycle Start" key.
	Cycle Start	The program is started and executed from the start or from the selected program block onwards.
	Stopping the program	
		Press the "Cycle Stop" key.
	Cycle Stop	Machining stops immediately, individual blocks do not finish execu- tion. At the next start, execution is resumed at the same location where it stopped.
	Aborting execution	
		Press the "Reset" key.
	Reset	Execution of the program is interrupted. When it is started again, it will execute from the beginning.



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Starting program execution from an operating area The program is loaded in "Machine Auto" mode and "Automatic" mode is activated on the machine control panel.

Press the "Cycle Start" key.

The program is started and executed from the beginning. However, the interface of the previously selected operating area remains on the screen.

2.10.4 Interrupting a program



Retracting from a contour



Repositioning







(e.g. in order to take a measurement on the workpiece and correct the tool wear values or after tool breakage), you can retract the tool from the contour in "Machine Manual" mode. In such cases, ShopMill stores the coordinates of the interruption point and displays the differences in distance traveled by the axes in "Machine Manual" mode as a "Repos" (= Reposition) offset in the actual value window. For details of how to traverse machine axes, please refer to Sec. "Traversing machine axes".

The "Repos" function repositions the tool on the workpiece contour after traversal of the machine axes during a program interruption in

After you have interrupted a program ("NC Stop") in Automatic mode

Automatic mode.

Select "Machine Manual" mode.

Move the axes away from the point of interruption.

- Press the "Repos" key.
- > Select the axis to be traversed.
- Press the "+" or "-" key.

It is not possible to overtravel the point of interruption. The feedrate override is active.

Warning

The rapid traverse override switch is active.

Non-adjusted Repos offsets are adjusted with program advance and linear interpolation on switchover to Automatic mode followed by start with the "Cycle start" key.



2.10.5 Starting execution at a specific point in the program





If you only want to execute a particular section of a program on the machine, there is not obligation to start execution of the program from the beginning, you can also start processing from a specific program block or text string.

The point in the program at which you wish to start machining is called the "target".

ShopMill distinguishes between three different target types:

- ShopMill cycle
- Other ShopMill block or G code block
- Any text

For the "Other ShopMill block or G code block" target type, you can again define the target in three different ways:

- Position cursor on target block This is ideal for straightforward programs.
- Choose point of interruption Machining resumes at the point at which it was interrupted earlier. This is especially convenient in large programs with multiple program levels.
- Specify target directly This option is only possible if you know the precise data (program level, program name etc.) of the target.

Once the target has been specified, ShopMill calculates the exact starting point for program execution.

With "ShopMill cycle" and "Any text" target types, the calculation is always based on the end of the block. When calculating the starting point of all other ShopMill blocks and G code blocks, you can choose between four options.

1. Calculation to end point:

During a block search, ShopMill makes the same calculations as when executing a program. The program is executed from the end of the target block or from the next programmed position of the target block.

2. Without calculation

ShopMill performs no calculations during block search, i.e. the calculation is skipped up to the target block. The parameters within the control contain the values valid before the block search. This option is only available for programs that exclusively comprise G code blocks.

2

	3. Externa This mer point, ex the calcu executed calculati This help	I - without calculation thod is performed in the same way as calculation to end ccept that subroutines called via EXTCALL are skipped in ulation. In the same way, with G code programs that are d entirely by external drives (disk drive/network drive), on is skipped until the target block is reached. ps to speed up the calculation process.
	Notice Modal funct calculated a executed. In – without ca which all the	tions included in the part of the program that is not are not taken into account for the part of the program to be n other words, with the "Without calculation" and "External alculation" methods, you should choose a target block after e information needed for machining is included.
Specifying a target directly	With the "O enter the ta Each line of number of le program. Le other levels You must e to the progr target is loc program, you The specifie example tha different pla (main progr	ther ShopMill block or G code block" target type, you can rget directly in the "Search pointer" screen form. If the screen form represents one program level. The actual evels in the program depends on the nesting depth of the evel 1 always corresponds to the main program and all correspond to subroutines. Inter the target in the line of the screen form corresponding ram level in which the target is located. For example, if the stated in the subroutine called directly from the main but must enter the target in program level 2. This means for at if the subroutine is called in the main program in two aces, you must also specify a target in program level 1 ram).
	The parame following m	eters in the "Search pointer" screen form have the eaning:
	Program:	Number of program level Subroutine is in NC working memory Program name Example: subrt1 Subroutine is not in NC working memory Path + program level Example: c:\subrt1 or \\r1638\shopmill\subrt1 (the name of the main program is automatically entered.)
	Ext: P:	File extension Continuous counter (if part of a program is repeated several times, you can specify the repetition number at which you wish machining to be resumed.)



		Line: Type: Search target:	 Parameter is assigned by ShopMill " Search target is ignored on this level N no. Block number Marker Jump marker Text Character string Sub-r. Subprogram call Line Line number Point in the program at which machining is to start 		
	Selecting ShopMill cycle				
		 Load a pro "Selecting 	gram in "Machine Auto" operating mode (see Sec. a program for execution").		
		Position the cursor on the desired target block.			
	NC Block Start	Press the "Block search" and "Start search run" softkeys.			
	search run	 Where changes select the of The promp 	ined program blocks have several technology blocks, desired technology block in the "Search run" window. It does not appear in the case of single program blocks.		
	· · ·	Press the '	'Accept" softkey.		
	Accept	 For chaine starting po The promp 	d program blocks, enter the number for the desired sition. It does not appear in the case of single program blocks.		
	Accept	Press the '	'Accept" softkey.		
	\bigcirc	Press the '	'Cycle Start" key.		
	Cycle Start	ShopMill carrie	es out all necessary default settings.		
	\bigcirc	Press the '	'Cycle Start" key again.		
	Cycle Start	The new startir machined from	ng position is approached. The workpiece is then the beginning of the target block.		
-	Reset	You can abort	the search by pressing the "Reset" key.		



Select other ShopMill block or G code block

Position cursor on target block

- Load a program in "Machine Auto" operating mode (see Sec.
 "Selecting a program for execution").
- > Position the cursor on the desired target block.
- > Press the "Block search" softkey.
- > Select a calculation technique.
- > Press the "Cycle Start" key.

ShopMill carries out all necessary default settings.

> Press the "Cycle Start" key again.

The new starting position is approached. The program executes from the beginning or end of the target block, depending on the calculation technique.

You can abort the search by pressing the "Reset" key.

Select point of interruption

Program execution must have been interrupted by pressing the "Reset" key. (ShopMill automatically remembers this point of interruption.)

- Switch back to "Machine Auto" mode.
- > Press the "Block search" and "Search pointer" softkeys.
- > Press the "Interr. point" softkey.

ShopMill inserts the saved point of interruption as the target.

- > Select a calculation technique.
- > Press the "Cycle Start" key.

ShopMill carries out all necessary default settings.

Press the "Cycle Start" key again.

The new starting position is approached. The program executes from the beginning or end of the target block, depending on the calculation technique.

You can abort the search by pressing the "Reset" key.









The prompt does not appear in the case of single program blocks.

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Specify target directly

- \geq Load a program in "Machine Auto" operating mode (see Sec. "Selecting a program for execution").
- Press the "Block search" and "Search pointer" softkeys. \triangleright
- \triangleright Specify the desired target.
- Select a calculation technique. \triangleright
- Press the "Cycle Start" key. \geq

ShopMill carries out all necessary default settings.

Press the "Cycle Start" key again. \geq

The new starting position is approached. The program executes from the beginning or end of the target block, depending on the calculation technique.

You can abort the search by pressing the "Reset" key.

Search for any text

- Load a program in "Machine Auto" operating mode (see Sec. "Selecting a program for execution").
- Press the "Block search" and "Search" softkeys.
- Enter the text string that you want to locate.
- Select whether the search is to commence at the start of the \geq program or the current cursor position.
- Press the "Search" softkey.

The program block that contains the text string is marked.

- > Press the "Continue search" softkey, if you want to continue the search.
- Press the "Abort" and "Start search run" softkeys. \geq

Where chained program blocks have several technology blocks, select the desired technology block in the "Search run" window and press the "Accept" softkey.



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- For chained program blocks, enter the number for the desired starting position and press the "Accept" softkey.
 The prompt does not appear in the case of single program blocks.
- > Press the "Cycle Start" key.

ShopMill carries out all necessary default settings.

> Press the "Cycle Start" key again.

The new starting position is approached. The workpiece is then machined from the beginning of the target block.

You can abort the search by pressing the "Reset" key.

2.10.6 Controlling the program run

Prog Cntrl

Program. stop

Cycle Start





- Press the "Prog. Cntrl." softkey.
- > Press the "Program. stop" softkey.
- > Press the "Cycle Start" key.

Execution of the program starts. The program run stops at every block for which "programmed stop" was defined (see Sec. "Miscellaneous Functions").



Operation		
2.10 Automatic mode		



\bigcirc	Press the "Cycle Start" key again each time.
Cycle Start	Execution of the program is continued.
Program. stop	Press the "Program. stop" softkey again if you want the program to be executed without a programmed stop. (The softkey is deactivated again.)
Skipping G code blocks	
	 Load a program in "Machine Auto" operating mode (see Sec. "Selecting a program for execution").
№ Prog. Cntrl.	Press the "Prog. Cntrl." softkey.
Skip	Press the "Skip" softkey.
	Press the "Cycle Start" key.
Cycle Start	Execution of the program starts. G code blocks with the "/" character (slash) in front of the block number are not executed.
Skip	Press the "Skip" softkey again if you want the marked G code blocks to be executed again during the next run. (The softkey is deactivated again.)
Allowing DRF offset	Load a program in "Machine Auto" mode (see Sec. "Starting/ stopping program execution").
NC Prog. ■ Cntrl.	Press the "Prog. Cntrl." softkey.
DRF offset	Press the "DRF offset" softkey.
	 Press the "Cycle Start" key.
Cycle Start	Execution of the program starts. Offsets with the handwheel affect the machining process directly.
DRF offset	Press the "DRF offset" softkey again if you no longer want to allow handwheel offsets during machining. (The softkey is

deactivated again.)

2.10.7 Overstore





	The blocks you have entered are stored. You can observe execution of the blocks in the "Overstore" window. After the entered blocks have been executed, you can append blocks again.
Stopping overstore	Press the "Back" key to exit "Overstore".
Duck	The window closes.
	You can switch modes now.
	After you have pressed "Cycle Start" again, the selected program continues before overstore.
Tooting o program	
	Stopping overstore Back

2.10.8 Testing a program



To prevent incorrect machining of the workpiece during the first pass of the program on the machine, first test the program without moving the machine axes.

ShopMill will then check the program for the following errors:

- Geometric incompatibility
- Missing data
- Non-executable instruction sequences and jumps
- Violation of working area

ShopMill automatically detects syntax errors when it loads a program in "Machine Auto" operating mode.

Whether ShopMill executes auxiliary functions (M functions and H functions) of not during the program test depends on the settings made by the machine manufacturer.

Please refer to the machine manufacturer's instructions.

The following functions can be used during the program test:

- Stop execution with "Programmed Stop" (see Sec. "Controlling the program run")
- Graphic display on screen (see Sec. "Simultaneous recording before machining").





- Load a program in "Machine Auto" operating mode (see Sec.
 "Selecting a program for execution").
- > Press the "Prog. Cntrl." softkey.
- > Press the "Program test" softkey.
- > Press the "Cycle Start" key.

The program is tested without traversing of the machine axes.

Press the "Program test" softkey again to deactivate test mode on completion of the program. (The softkey is deactivated again.)

2.10.9 Simultaneous recording before machining

Image: A start of the start		In automatic mode you can display your program graphically in the "Program test" function before machining, without traversing the machine axes. Simultaneous recording is a software option.
		The graphic displays a workpiece as if it were being machined with a cylindrical tool.
	Status displays	 The status display in the graphic contains the following information: Current axis coordinates Block currently being processed. The processing time (in hours/minutes/seconds) indicates the approximate time that would actually be required to execute the machining program on the machine (incl. tool change). The timer is stopped if the program is interrupted.
,		 Select the program in "Machine Auto" mode.
	Program test	 Press the "Prog. Cntrl." and "Program test" softkeys. Also activate the "Dry run feedrate" softkey.
	Dry run feedrate	The programmed feedrate is replaced by a dry run feedrate defined via machine data.

Press the "Real-sim" softkey.

Real-



Operation 2.10 Automatic mode

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For more information on the principles and operation, please refer to Sec. "Simulation".



2.10.10 Simultaneous recording during machining



You can track the current machining operation on the machine tool simultaneously by monitoring the graphic display on the control screen. Program test and dry run feedrate must not be selected.

Simultaneous recording is a software option.

Press the "Real-sim" softkey and

start the program with "Cycle Start".

The "simultaneous recording" function can be switched on at any time during machining.

An explanation of the functions available under "Simultaneous recording" can be found in Secs. "Simultaneous recording before machining" and "Simulation".



2.11 Trial program run

2.11.1 Single block

Standard setting	 If this function is active, execution is interrupted after every block that triggers a function on the machine (calculation blocks are not affected). The following defaults apply: for drilling, the entire machining procedure and for pocket milling, the machining of a single plane is combined in a single block.
Select with softkey	Single block fine
"Single block fine" active	When the "Single block fine" function is active, each individual drill infeed and pocket milling motion is executed as a separate block. Also, execution is stopped at the contour after every single contour element.
Select with softkey	Single block fine
Single block via machine control panel	
Single Block	Activate the "Single block" key in "Machine Auto" mode. It will allow you to process a program block by block. If single block is activated, the associated LED on the machine control panel lights up.
	 If single block mode is active, the message "Stop: block in single block ended" is output in the channel mode message line (in the interrupt state). the current block of the program is not executed until you press the "Cycle Start" key, if machining stops after a block has been processed, you can start execution of the next block by pressing key "Cycle Start" again.
Deselecting a single block	
Single Block	You can deselect the function by pressing the "Single block" key again.

2.11.2 Displaying the current program block





If you want precise information about axis positions and key G functions during a trial run or execution of the program, you can show the basic block display.

You can use the basic block display both in test mode and when machining the workpiece on the machine. All G code commands that initiate a function on the machine are displayed in the "Basic block" window for the currently active program block:

- Absolute axis positions
- G functions for the first G group
- Other modal G functions
- Other programmed addresses
- M functions

The basic block display function must be set up by the machine manufacturer.

Please refer to the machine manufacturer's instructions.

- Load a program in "Machine Auto" operating mode (see Sec. "Selecting a program for execution").
- Press the "Basic block" softkey.
- Press the "Single Block" key if you wish to execute the program block by block.
- Start program execution.

The precise axis positions, modal G functions, etc., are displayed in the "Basic block" window for the currently active program block.







2.11.3 Correcting a program



As soon as the control detects a syntax error in the program, it interrupts the program and displays the syntax error in the alarm line. If an error occurs (Stop state), you can edit the program in the program editor.

> Select a program in "Machine Auto" mode.

The program status must be either "Stopped" or "Reset".Press the "Prog. corr." softkey.

The program editor opens.

If an error has occurred, the errored block is marked. Press the "Input" key and then correct the block.

- Press the "Accept" softkey to transfer the correction to the current program.
- Continuing machining



> Press the "Execute" softkey followed by the "Cycle Start" key.

Execution of the program is continued.

- Cycle Stop status: You can only modify blocks that have not yet been executed or read in by the NC.
- Reset status: All blocks can be edited.



2.12	Run times						
		To provide you with an overview of the most important machine run times, ShopMill features a status window that displays the following operating times.					
	Program	Measurement of the program run time starts as soon as you press the "Cycle Start" key and stops on NC Stop or NC Reset. If you start a new program, timing starts again from the beginning.					
H		Timing continues if dwell time is active, or during program runs with program test or dry run feedrate. Timing stops with NC Stop or feedrate override = 0.					
	Workpiece	The current repetition and the programmed number of program repetitions (e.g. Workpiece: 15/100) are displayed. The number is only displayed in ShopMill programs and only when the number of programmed repetitions N is greater than 1. As from a programmed repetition of 100000 there is only enough room to display the current program repetition (e.g. Workpiece: 15). If no information is yet available about the current program repetition, only two dashes are displayed (e.g. Workpiece:/100).					
	Time	The current time is displayed here.					
	Date	Today's date is displayed.					
	Machine	The machine run time displays how much time has elapsed since the control was last switched on.					
	Machining	The machining time displays the total run time of all programs executed since the control was last switched on.					
	Machine utilization	The system calculates the actual machine utilization from the timed machining time and the current machine run time. The ratio of machining time to machine run time is displayed as a percentage.					
		A setting in the machine data determines which run times are displayed.					
		Please refer to the machine manufacturer's instructions.					
_	M ∫og Jog - Or -	Select "Machine Manual" or "Machine Auto" mode.					
	Run times	Press the "Run times" softkey.					
		The T,F,S display window turns into the "Run times" window.					

Pressing the "Run times" softkey again, takes you back to the T,F,S display window.



Operation 2.13 Tools and tool offsets

2.13 Tools and tool offsets



You can manage tools with ShopMill. The following lists are available to you for this function

- Tool list
- Tool wear list
- Magazine list

Enter the tools, their offset data and wear monitoring data in the tool list or tool wear list. You will be able to identify in the magazine list which magazine locations are disabled or not.

Depending on individual requirements, a tool list might consist of the following:

- A tool changer comprising
 - a spindle without dual gripper
 - or a spindle with dual gripper
- at least one tool magazine
- and tools that are not assigned to any tool magazine.

For details of the functionality of your tool management system, please refer to the machine manufacturer's instructions. The different lists can be adapted by the machine manufacturer, if necessary.

The tool list displays all tools and their offset data stored as a tool data block in the NC, irrespective of whether or not they are assigned to a magazine location. The tool list offers you all commonly used tools. You can assign geometric and technological tool data to tool types. Various different examples of each tool might exist to which you can assign the various offset data of the tool being used.

Depending on the tool type used, different tool offset data will be required.



Tool list

=?

2





Mill

Face mill



Angle head cutter













3D probe

You can load and unload tools to and from a magazine via the tool list. When a tool is loaded, it is moved from its storage location to a magazine location. When it is unloaded, it is removed from the magazine and taken back to a storage location.

The loading and unloading of tool magazines is defined in a machine data.

Please refer to the machine manufacturer's instructions.

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OFFSE	T										
Tool	lis	t									0
Loc	Тур	Tool name	DP	1st cutt:	ing edge			₽	⇒	-5	Alternat.
				Length	ø		Ν		1	2	
₽	÷	EDGE_TRACER	1	112.000	10.000			2			Tool measure
1	Ø	DRILL_10	1	114.560	10.000	118.0		2	x		
2		CUTTER_8	1	106.980	8.000		2	2			Delete tool
З	Ø	DRILL_15	1	119.251	15.000	118.0		2	х		
4	Ø	DRILL_20	1	116.067	20.000	118.0		2	х		Unload
5	≝	CUTTER_25	1	121.912	25.000		4	2	х		Uniteda
6	U	CENTERDRILL	1	130.440	12.000	90.0		2			
7	₫	CUTTER_20	1	118.462	20.000		3	2	х		Details
8	\Box	MILL_TAPER	1	124.354	12.000		2	2			
9	Ŷ	3D_PROBE	1	134.842	5.000			2			Cutting edges
10	V	DIEMILL_TAPER_10	1	120.062	10.000		2	2	x		
11	₫	CUTTER_30	1	133.870	30.000		5	2			Sort
12	Ø	DRILL_3	1	123.330	3.000	115.0		2			
13	≝	CUTTER_35	1	142.560	35.000		4	2	x		
										\sum	
	Tool list	Tool wear		Maga V zin	a- e t of	lork fset	R	va	R ri		

Example of a tool list with variable location assignment

The main display of the "Tools" operating area shows the current tool list with the following data:

Loc.	 Location number The following designations/symbols are used for: The spindle location The locations for gripper 1 and gripper 2 (applies only when a spindle with dual gripper is used) The magazine location numbers If the configuration includes more than one magazine, the location number is specified first followed by the magazine number in the magazine: e.g. 10/1 = Location number 10 in magazine 1 5/2 = Location number 5 in magazine 2 Tools that are not assigned to a magazine in the tool list are stored in a location without location number. This allows management of tools that are not actually contained in the tool magazine.
Туре	Tool type Depending on the tool type (represented by a symbol), only certain tool offset data are enabled.
Tool name	A tool is identified by its name and duplo number of the tool. You can enter the name as text or a number (see Sec. "Changing tool names").
DP	Duplo number of twin tool (replacement tool)



Tool offset data	
(D No.) edge	Tool offset data for the selected cutting edge of a tool (D No.)
Length	Tool length You can determine this value using the "Measure tool" function (see Sec. "Measuring the tool manually"). If the tool is measured externally, you can enter the value here.
Radius or \varnothing	Radius or diameter of the tool You can also enter the diameter for milling cutters and drills. A machine data code is used to switch from radius to diameter specification.
Angle	Angle of tool tip on a drill. If you want to insert a drill down to the shank, and not just to the tool tip, the control also takes the angle of the drill tip into account.
Н	The "H" column is displayed only if ISO dialects are set up. Every H number of an ISO dialect program must be assigned to a tool offset data record.
N Lead	Number of teeth for a milling cutter Thread lead of a tap in mm/rev or turns/" if the inch system is set up on the machine.
Tool-specific functions	Spindle rotation
т)	Coolant supply 1 and 2 can be activated/deactivated (e.g. internal and external cooling)
Tool-spec. fct 14	Other tool-specific functions such as additional coolant supply, monitoring functions for speed, tool breakage, etc.
	Please refer to the machine manufacturer's instructions.
	The "Details" softkey displays the additional parameters "Rounding radius" or "Angle" for 3D tapered milling tools. For the facing tool, an additional outside radius and tool angle, and for angle head cutter, additional lengths and wear lengths are displayed under "Details.



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Tool wear list

Tool magazine

You can adapt the tool geometry (length and radius/diameter) to the wear-induced geometry in the tool wear list.

The following monitoring modes can also be selected for a tool.

- Monitoring of the effective operating time (tool life)
- Monitoring of number of tool load operations (quantity)
- Monitoring of wear
- Other tool status data (disable tool, tool in fixed location, oversized tool)

OFFSE	T									
Tool	wea	r						Prewarr	n. limit	
Loc	Тур	Tool name	DP	1st cut	ting edg	е				
				∆Length	∆ø	T C	Prewarn Limit	Tool lf		
₽	ę.	EDGE_TRACER	1	0.000	0.000					
1	Ø	DRILL_10	1	0.000	0.000					
2		CUTTER_8	1	0.000	0.000	т	25.0	30.0	в	
з	Ø	DRILL_15	1	0.000	0.000					
4	Ø	DRILL_20	1	0.000	0.000					
5	₫	CUTTER_25	1	0.000	0.000					
6	U	CENTERDRILL	1	0.000	0.000					
7	₫	CUTTER_20	1	0.000	0.000					
8	\Box	MILL_TAPER	1	0.000	0.000				в	
9	Ŷ	3D_PROBE	1	0.000	0.000					Cutting edges
10	V	DIEMILL_TAPER_10	1	0.000	0.000					
11	₫	CUTTER_30	1	0.000	0.000					Sort
12	Ø	DRILL_3	1	0.000	0.000					
13	ding the second	CUTTER_35	1	0.000	0.000					
									\sum	
	Tool list	Tool wear		H Ma	ga-	Wo	fset R	R vari.		

Example of a tool wear list with variable location allocation

The magazine locations with tools are specified in the magazine list. The list also indicates whether the magazine location is disabled (location disable) and the properties (tool status) assigned to the tools.

Fixed/variable location
assignmentYou can set a machine data to determine whether all tools must have
a variable or fixed location assignment in the magazine.
If you select a variable location assignment, the tools are taken to the
next available space in the magazine after a tool change. With a fixed
location assignment, the tools are always taken back to the location
assigned specifically to them.Please refer to the machine manufacturer's instructions for details

about location assignments in the tool magazine.



Graphical display of tools and magazine locations

In addition to the list of tools, you can also display the tools and magazine locations in a dynamic graphic display. The tools are displayed in the order in the list with the correct proportions. You can show or hide the graphical display with the "Help" key. The graphical display must be set up by the machine manufacturer.

Please refer to the machine manufacturer's instructions.



Graphical display of tools and magazine locations

The following applies for the graphical display:

- Small milling tools and 3-D tools are displayed as end mills, large ones as hobs.
- If a tool is too long for the display, the maximum possible length is shown.
- Oversized tools are truncated on the left and right sides.
- Tools that are not located in the magazine are displayed without toolholder.
- Disabled tools or magazine locations are marked as follows:

Disabled tool:

Disabled magazine location:

 The data of the relevant tool nose selected are used for the display.

If there is no tool nose for a tool in the selected view, the data of the first tool nose are used.

2.13.1 Creating a new tool

You can enter tools and the associated compensation data directly into the tool list or simply read existing tool data outside the tool management (see Section "Backup/restore tool/zero data").

If you want to enter a new tool directly into the tool list, ShopMill offers a range of conventional tool types. The tool type determines which geometry data are required and how they will be computed. The following common tool types are available:

Ø	DRILL
U	CENTERDRILL
趟	CUTTER
Ŷ	3D_PROBE
為	FACING TOOL
趟	ANGLE HEAD
Ĥ	EDGE_TRACER
\$	Tap
U	DIEMILL_CYL
U	BALL_END_MILL
U	MILL_CORN_RAD.
U	MILL_TAPER
V	MILL_TAPER_CRAD

U DIEMILL_TAPER





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Operation 2.13 Tools and tool offsets

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- Attach the new tool to the spindle. \geq
- Change operating area with "Menu Select" and press "Tools WO".

The tool list opens.

- Place the cursor on the location in the tool list that the tool occupies in the spindle. The location must still be vacant in the
- Press the "New tool" softkey.
- > Select the tool type with the relevant softkey. Additional tool types are available via the "More" softkey.

The new tool is created and automatically assumes the name of the selected tool type.

- Enter a unique tool name. \succ
- \triangleright Enter the offset data of the tool.

In the case of facing tools, angle head cutters, and 3D tools, you must define parameters in addition to the geometry data in the tool list.

Press the "Details" softkey and enter the additional parameters. \triangleright The "Details" softkey is only active when a tool is selected for which additional information is required.

Name	Additional parameters
Angle head cutter	Length2, Length3, Δ Length2, Δ Length3
Facing tool	Outside diameter, tool angle

3D tools

Details

Туре	Name	Additional parameters
110	Cylindrical die mill	-
111	Ball end mill	Smoothing radius
121	End mill with corner rounding	Smoothing radius
155	Bevel cutter	Angle for conical tools
156	Bevel cutter with corner rounding	Rounding radius, angle of conic. tools
157	Tapered die mill	Angle for conical tools

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2.13.2 Setting up more than one edge per tool



In the case of tools with more than one cutting edge, a separate set of offset data is assigned to each cutting edge. You can set up a total of 9 edges for each tool.

There must be no gaps between the edges, i.e. if 3 edges are required for a tool, these must be edges 1 to 3.

In the case of ISO programs (e.g. ISO dialect 1) you must specify an H number. This corresponds to a particular tool offset set.



New cutting Cutting edges edge > Delete cutting edge D No. + D No. -

Follow the instructions given above to set up tools with more than one edge in the tool list and enter the offset data for the 1st edge.

Then select the "Cutting edges" and "New cutting edge" softkeys. \triangleright

Instead of the input fields for the first cutting edge, the offset data input fields for the second cutting edge are displayed.

- \triangleright Enter the offset data for the second cutting edge.
- Repeat this process if you wish to create more tool edge offset \triangleright data.
- > Select the "Delete cutting edge" softkey if you want to delete the tool edge offset data for an edge. You can only delete the data for the edge with the highest edge number.

By selecting softkey "D No. +" or "D No. -", you can display the offset data for the edge with the next highest or next lowest edge number respectively.



2.13.3 Changing the tool name

Ľ		Ì	

A tool that has just been created in the tool list is automatically assigned the name of the selected tool group. You can change this name as often as you want to

- a tool name, e.g. "Facing tool_120mm", or
- a tool number, e.g. "1".

The tool name must not exceed 17 characters in length. You can use letters, digits, the underscore symbol (_), periods (".") and slashes ("/").

2.13.4 Creating a replacement tool



A replacement tool is one that can be employed to perform the same machining operation as a tool that already exists (e.g. as a replacement after tool breakage).

When you create a tool as a replacement, you must give it the same name as an existing comparable tool.

Confirm the name with the "Input" key. The duplo number of the replacement tool will automatically be incremented by 1.

The order in which replacement tools are attached to the spindle is determined by duplo number **DP**.

2.13.5 Manual tools



Manual tools are tools which are required during machining, but are only available in the tool list but not in the tool-holding magazine. These tools must be attached/detached manually to/from the spindle.

The "manual tool" function must be set up by the machine manufacturer.

Please refer to the machine manufacturer's instructions.



2.13.6 Tool offsets

Why use tool offsets?

You do not have to take tool diameters and lengths into account when writing machining programs.

You can program workpiece dimensions directly, e.g. as specified in the production drawing.

When machining a workpiece, the tool paths are controlled according to the tool geometry such that the programmed contour can be machined using any tool.



The control corrects the travel path

Enter the tool data separately in the "Tool list" and "Tool wear" tables. When writing the program, you only need to call the tool you require. While the program is being processed, the control fetches the offset data it requires from the tool table and corrects the tool path individually for different tools.





What type of tool offsets are available?

The offset memory of a tool includes the following:

- Tool type The tool type determines which tool data are required and how they must be calculated (e.g. drill, centering tool, mill).
- Total size: Length, radius, angle (drill) These comprise several components (geometry, wear). The control performs calculations on the components to obtain a final size (e.g. total length, total radius). The relevant total dimension becomes valid as soon as the offset memory is activated.



Tool length offset

This value compensates for the differences in length between the tools used.

The tool length is interpreted to be the distance between the toolholder reference point and the tool tip. This measured length is entered in the tool list.

The control uses this measurement and the wear values to calculate travel movements in the infeed direction.



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Tool radius compensation

The contour and tool path are not identical. The cutter or tool nose radius center must travel along a path that is equidistant from the contour.

For this purpose, the programmed tool center point path is automatically displaced by the control – as a function of radius and machining direction – in such a way that the tool edge travels exactly along the programmed contour.

The tool radius must be entered in the tool list. The control fetches the required radii during program execution and calculates the tool path from these values.





Infeed	Geometry in plane	Radius
Z	Length in Z	
Y	Length in Y	Angle
x	Length in X	Length ► F - Toolholder reference point

Offset values are used in the simulation display and programming graphic for the following tools:

• Drill:

•

- Angle and radius/diameter
- Centering tool: Radius/diameter

milling tool (example)

Offset values drill (example)

Offset values



2.13.7 Miscellaneous functions for a tool

	You can assign other functions to tool types in the tool list.						
Number of teeth N Specify the number of teeth in this parameter. Parameter dependent and can be applied only for milling tools. The system calculates feedrate F internally if the feed is set the program.							
	₽	Using the "Alternat." softkey, you ca spindle direction of rotation (CCW/C	in activate and de CW) in parameter	eactivate the "Spindle".			
		The spindle rotates clockwise.	$\widehat{}$	Selection with softkey			
		The spindle rotates counterclockwise.	dle rotates lockwise. dle is stopped.				
		The spindle is stopped.	X				
	<u>т</u>	Use parameters "coolant 1" and "coolant 2" if you want to supply coolant for the tool, e.g. for internal and external cooling.					
		Switch coolant ON:	Selection w	vith softkey			
		Do not switch on Coolant:	Alternat.				
	Tool-specific functions	You can also assign another four machine-specific actions to a tool. You can switch these tool-specific functions on and off with the "Alternat." softkey. Tool-specific functions might be, for example, 3rd coolant application or tool breakage monitoring. Please refer to the machine manufacturer's instructions.					



2.13.8 Entering tool wear data



Tools that are in use for long periods are subject to wear. You can measure this wear and enter it in the tool wear list. ShopMill then takes this information into account when calculating the tool length or radius compensation. This ensures a consistent accuracy in workpiece machining.

When you enter the wear data, ShopMill checks that the values do not exceed an incremental or absolute upper limit. The incremental upper limit indicates the maximum difference between the previous and new wear value. The absolute upper limit indicates the maximum total value that you can enter.

The upper limits are set in a machine data code.

Please refer to the machine manufacturer's instructions.



> Select the "Tool wear" softkey in the "Tools WOs" operating area.

OFFSE	T									
Tool	wear	r						Prewarn	n. limit	
Loc	Тур	Tool name	DP	1st cut	ting edg	э				
				∆Length	∆ø	T C	Prewarn Limit	Tool lf		
₽	ę.	EDGE_TRACER	1	0.000	0.000					
1	Ø	DRILL_10	1	0.000	0.000					
2		CUTTER_8	1	0.000	0.000	т	25.0	30.0	в	
З	Ø	DRILL_15	1	0.000	0.000					
4	Ø	DRILL_20	1	0.000	0.000					
5		CUTTER_25	1	0.000	0.000					
6	Ų	CENTERDRILL	1	0.000	0.000					
7		CUTTER_20	1	0.000	0.000					
8	\Box	MILL_TAPER	1	0.000	0.000				в	
9	Ŷ	3D_PROBE	1	0.000	0.000					Cutting edges
10	V	DIEMILL_TAPER_10	1	0.000	0.000					P
11		CUTTER_30	1	0.000	0.000					Sort
12	Ø	DRILL_3	1	0.000	0.000					
13		CUTTER_35	1	0.000	0.000					
									\sum	
	Tool list	Tool wear		Mag 10 zi	ga- 🔶	We	fset R	R vari.		

Example of a tool wear list with variable location allocation

- > Place the cursor on the tool whose wear data you want to enter.
- > Enter the differences for length (Δ Length X, Δ Length Z) and radius/diameter (Δ Radius/ $\Delta \emptyset$) in the appropriate columns.



The wear data entered is added to the radius but subtracted from the tool length. A positive differential value for the radius therefore corresponds to an oversize (e.g. for subsequent grinding).

2.13.9 Activating tool monitoring

		ShopMill allows you to monitor the tool life of the tools automatically to ensure constant machining quality.
		You can also disable tools that you no longer want to use, identify them as oversize or assign them permanently to a magazine location.
		Tool monitoring can be activated via a machine data code.
Ξŕ		Please refer to the machine manufacturer's instructions.
	Tool life (T)	With the tool life T (Time), the service life for a tool with machining feedrate is monitored in minutes. When the remaining tool life is $= 0$, the tool is set to "disabled". The tool is not put into operation on the next tool change. If a replacement tool is available, it is inserted in its place. Tool life is monitored on the basis of the selected tool cutting edge.
	Count (C)	With the count C, on the other hand, the number of times a tool is attached to a spindle is counted. The tool is also disabled in this case, when the remainder reaches "0".
	Wear (W)	With wear W, the greatest value in the wear parameters Δ Length X, Δ Length Z, or Δ Radius or $\Delta \emptyset$ in the wear list is monitored. Here, too, the tool is disabled if one of the wear parameters reaches the value for wear W.
		The wear monitoring function must be set up by the machine manufacturer.
	Prewarning limit	Please refer to the machine manufacturer's instructions. The prewarning limit specifies a tool life, workpiece count or wear at which the first warning is displayed. The value for output of a warning due to the wear stage reached is calculated from the difference between the maximum wear and the warning limit entered.
	Disabled (G)	Individual tools can also be disabled manually if you no longer want to use them for workpiece machining.



Oversize (U)	In the case of oversize tools, neighboring magazine locations (left and right adjacent location) are only reserved alternately, i.e. you can only insert the next tool in the next magazine location but one. (This can also contain an oversize tool.)
Coded for fixed location (P)	You can assign tools to a fixed location, i.e., the tool can only be used in its present magazine location. After machining, the tool always returns to its old magazine location.

Monitoring tool use



- > Select the "Tool wear" softkey in the "Tools WOs" operating area.
- > Position the cursor on the tool that you want to monitor.
- In the column "T/C" select the parameter that you wish to monitor (T = Tool life, C = Count, W = Wear).
- > Enter a prewarning limit for the tool life, count, or wear.
- Enter the scheduled service life for the tool, the scheduled number of workpieces to be machined or the maximum permissible wear.

The tool is disabled when the tool life, count, or wear is reached.

Entering tool statuses



- > Select the "Tool wear" softkey in the "Tools WOs" operating area.
- Place the cursor on a tool.
- Select the option "G" in the first field of the last column if you want to disable the tool for machining.

-or-

Select the option "U" in the second field of the last column if you want to mark the tool as oversize.

-or-

Select the option "P" in the third field of the last column if you want assign the tool to a fixed magazine location.

The tool properties you have set become active immediately.

2.13.10 Magazine list





All magazine locations are listed in the magazine list. The list shows whether a magazine location is free, disabled, or occupied by a tool.

From the "Tool status" column, you can also see whether a tool is disabled (G) or oversize (U) or allocated to a fixed location. You can change the tool status settings in the tool wear list (see Sec. "Activating tool monitoring")-

If a magazine location is defective, or an oversize tool requires more than half the adjacent location, you can disable the magazine location to code a tool for the fixed location. It is no longer possible to assign any tool data to a disabled magazine location.



Tools 🌄 Maga-WOs 🛛 📆 zine > Select the "Magazine" softkey in the "Tools WOs" operating area.

OFFSE	T									
Magaz	ine						Block	magazine	loc.	0
Loc	Тур	Тоо	l name	DP	Loc. disabl	Tool State				Alternat.
₽	ę.	EDG	e_tracer	1						
1	Ø	DRI	LL_10	1	1.1					
2		CUT	TER_8	1						
З	Ø	DRI	LL_15	1						
4	Ø	DRI	LL_20	1						
5		CUT	TER_25	1						
6	U	CEN	TERDRILL	1						
7		CUT	TER_20	1						
8	\Box	MIL	l_taper	1		B				
9	Ŷ	3D_I	PROBE	1						
10	\cup	DIE	MILL_TAPER_10	1						
11		CUT	TER_30	1						
12	Ø	DRI	LL_3	1						
13		CUT	TER_35	1						
									\triangleright	
	Tool list	1	Tool wear		प्रमुख यहा ट	aga- Work ine offset	R.	R ari.		

Example of magazine with variable assignment



10.04

Disabling a machine location	Magazine locations can be reserved or disabled for tools, e.g. for oversized tools.
	 Place the cursor on the relevant empty magazine location in the "Location disable" column.
Alternat.	Press the "Alternat." softkey until a "G" (=disabled) appears in the field.
Tool status	 The location is now disabled. A tool can no longer be loaded into this magazine location. In the column "Tool status", you can see which properties have been assigned to the active tool: G: Tool is disabled U: Tool oversized P: Tool at a fixed location

2.13.11 Deleting a tool

Tools can be deleted from the tool list.



Delete tool

- > Select the tool of your choice with the cursor keys.
- Press the "Delete tool" softkey.
- > Confirm with "Delete".

The tool data for the selected tool are deleted. The magazine location in which the tool was stored is enabled.

2.13.12 Changing the tool type



In the tool list you can change a tool type into another tool type.



O Alterna



Press the "Alternat." softkey until the tool type you are looking for appears.

The input fields for the new tool type are displayed.



Operation 2.13 Tools and tool offsets

2.13.13 Loading/unloading a tool into/out of the magazine



You can unload tools in the magazine that you are not using at present. ShopMill then automatically saves the tool data in the tool list outside the magazine. Should you want to use the tool again later, simply load the tool with the tool data into the corresponding magazine location again. Then the same tool data does not have to be entered more than once.

Loading and unloading of tools into and out of magazine locations must be enabled in a machine data code.

Please refer to the machine manufacturer's instructions.

When you are loading a tool, ShopMill automatically suggests an empty location. The magazine in which ShopMill searches for an empty location first is stored in a machine data code.

Please also refer to the machine manufacturer's instructions.

You can also specify an empty magazine location directly when loading a tool, or define the magazine ShopMill should search for an empty location.

If your machine has only one magazine, you simply need to enter the location number you require when loading the tool, not the magazine number.

You can also attach or detach a tool to or from the spindle directly. You can disable loading and unloading with machine data. Please refer to the machine manufacturer's instructions.



Loading a tool into the magazine







- > Select the "Tool list" softkey in the "Tools WOs" operating area.
- Place the cursor on the tool that you want to load into the magazine (if the tools are sorted according to magazine location number you will find it at the end of the tool list).
- Press the "Load" softkey.

The "Empty location" window appears. The "Location" field is initialized with the number of the first empty magazine location.

Press the "OK" softkey to load the tool into the suggested location.

10.04



Unloading an individual tool from the magazine

Unload



> Select the "Tool list" softkey in the "Tools WOs" operating area.

- Position the cursor on the tool that you want to unload.
- Press the "Unload" softkey.

The tool is unloaded from the magazine.





If your machine has just one magazine, you only need to enter the location number you require, not the magazine number.

If a spindle location is shown in the tool list, you can also attach or detach a tool directly to or from the spindle.

Please refer to the machine manufacturer's instructions.



Specifying an empty location



- > Select the "Magazine" softkey in the "Tools WOs" operating area.
- Place the cursor on the tool that you wish to relocate to a different magazine location.



Press the "Relocate" softkey.

The "Empty location" window appears. The "Location" field is initialized with the number of the first empty magazine location.

- Press the "OK" softkey to relocate the tool to the suggested
- Enter the location number you require and press the "OK" softkey.
- Press the "Spindle" and "OK" softkeys to load a tool into the

The tool is relocated to the specified magazine location.

- Select the "Magazine" softkey in the "Tools WOs" operating area.
- Place the cursor on the tool that you wish to relocate to a different magazine location.
- Press the "Relocate" softkey.

The "Empty location" window appears. The "Location" field is initialized with the number of the first empty magazine location.

- Enter the magazine number and a "0" for the location number if you wish to search for an empty location in a particular magazine.
- Enter a "0" for the magazine number and location number if you wish to search for an empty location in all magazines.
- Press the "OK" softkey.

An empty location is suggested.

Press the "OK" softkey.

The tool is relocated to the suggested magazine location.



Operation 2.13 Tools and tool offsets

2.13.15 Positioning a location



Positioning a magazine

location	
Vos Tools	Maga-
Position- ing	

You can position magazine locations directly on the loading point.

- > Select the "Magazine" softkey in the "Tools WOs" operating area.
- Place the cursor on the magazine location that you want to position on the loading point.
- Press the "Position" softkey.

The magazine location is positioned on the loading point.

2.13.16 Sorting tools

When you are working with large magazines or several magazines, it is useful to display the tools sorted according to different criteria. Then you will be able to find a specific tool more easily in the lists.

Tools can be sorted in the tool list or tool wear list according to magazine assignment, tool name (alphabetic), tool type, or numerically according to T number. When you sort according to magazine assignment, the empty locations in the magazine are also displayed.



or

or

or

to

to name

to type

to T number

magazine

"Select the "Tool List" or "Tool wear" softkey in the "Tool WOs" operating area.

The tool list or tool wear list opens.

Press the "Sort" softkey.

A new vertical softkey menu is displayed.

 Activate one of the softkeys to choose the sort criteria for the tools.

The tools are listed in the new order.

2.14 Work offsets

Following reference point approach, the actual value display for the axis coordinates is based on the machine zero (M) of the machine coordinate system (MCS = machine). The program for machining the workpiece, however, is based on the workpiece zero (W) of the workpiece coordinate system (WCS = work).

The machine zero and workpiece zero are not necessarily identical. The distance between the machine zero and workpiece vary in accordance with the type of tool and how it is clamped. This work offset is taken into account during execution of the program and can be a combination of different offsets.

In ShopMill, the position actual value display refers to the settable zero system. The position of the active tool relative to the workpiece zero is displayed.

The offsets are summated as follows:



Work offsets

When the machine zero is not identical to the workpiece zero, at least one offset (base offset or work offset) exists in which the position of the workpiece zero is saved.

The base offset is a work offset that is always active. If you have not defined a base offset, its value will be zero. You determine the base offset via "Workpiece zero" (see Sec."Measurement workpiece zero") or "Set work offset" (see Sec. "Setting a new position value").

Base offset

Work offsets	Every work offset (G54 to G57, G505 to G599) consists of a coarse offset and a fine offset. You can call the work offsets from any sequential control program (coarse and fine offsets are added together). You can save the workpiece zero, for example, in the coarse offset, and then store the offset that occurs when a new workpiece is clamped between the old and the new workpiece zero in the fine offset.				
	Fine offsets must be set up by the machine manufacturer.				
	Please refer to the machine manufacturer's instructions.				
	For instructions on specifying and calling work offsets, see Secs. "Defining work offsets" and "Calling work offsets".				
Coordinate transformations	 You always program coordinate transformations for a specific sequential control program. They are defined by: Offset Rotation Scaling Mirroring (See Sec. "Defining the coordinate transformations") 				
Total offset	The total offset is calculated from the sum of all offsets and coordinate transformations.				



2.14.1 Defining work offsets

		Enter work offsets (coarse and fine) directly in
		Fine offsets must be set up by the machine n The number of possible work offsets is define
		Please refer to the machine manufacturer's in
_ →	Vork WOs Vork	Press the "Work offset" softkey in the "To area.
		The work offset list appears.
		 Position the cursor on the coarse or fine define.
		Enter the desired coordinates for the axis the cursor keys to switch between axes.
		-or-
	Set X Set Z	Press the "Set X", "Set Y" or "Set Z" soft value of an axis from the position display
		-or-
	Set all	Press the "Set all" softkey to accept the p from the position display for a coarse offs
		The new coarse offset is set. The values from included in the calculation and then deleted.
	Delete WO	Press the "Delete WO" softkey to delete a values at the same time.
E	Additional axes	With the "Additional axes" softkey, you can directly axes and determine their offset. These activated via machine data.
		Please refer to the machine manufacturer's ir

n the work offset list.

nanufacturer. ed by a machine data. nstructions.

- ools WOs" operating
- offset that you wish to
- s in question You can use
- key to accept the position for a coarse offset.
- position values of all axes set.

n the fine offset are

the coarse and fine offset

isplay two additional additional axes must be

nstructions.



The individual work offsets as well as the total offset are all displayed in the work offset list. The currently active work offset is displayed on a gray background. The work offset list also includes the current axis positions in the machine and workpiece coordinate systems.

OFFSET Work of	fset	_	_	_	Basic	ref. (G500)
WCS			MCS				
Х		5.000	, m	<1	0.	000 _{mm}	
Y		10.000		/1	0.	000	ln manual
Z	10	00.000	mm mm	Z1	0.	000 mm	Further
	x	Y	Z	хõ	Y 2 :	ΣQ	axes
Base ref	-9.000	-10.000	-100.000	0.000	0.000	0.000	flear
WO 1	51.904	44.410	55.766	0.000	0.000	0.000	Offset
	0.000	0.000	0.000				
WO 2	-26.553	6.201	378.635	0.000	0.000	0.000	Position set X
	0.000	0.000	0.000				
WO 3	4.000	0.000	70.000	0.000	0.000	0.000	Position
F	0.000	0.000	0.000				set Y
Program	0.000	0.000	0.000	0.000	0.000	0.000	Deside
Scale	1.000	1.000	1.000				set Z
Mirror							
Total	-5.000	-10.000	-100.000	0.000	0.000	0.000	Position
						\sum	Set all
Tool list	Tool wear		Maga-	Work offse	t R var:	i.	
Work offs	et list					1	1

Base offset Basic reference

Work offsets

NPV1 ... NPV3

PAGE DOWN The coordinates of the base offset appear. You can change these here in the list.

The coordinates of the individual work offsets (1st line Coarse offset, 2nd line Fine offset) and the angle with which the coordinate system may be rotated about an axis if necessary, are listed. You can change this data here in the list (see Sec. "Defining work offsets"). Fine offsets must be set up by the machine manufacturer.

Please refer to the machine manufacturer's instructions.

You can display more work offsets with the "Page Down" key.

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	Coordinate transformations	
	Program	The active coordinates of the "Offset" transformation are displayed as well as the angle set in the "Rotation" transformation by which the coordinate system rotates. You cannot edit these values here.
	Scale	The active scaling factor for the "Scaling" transformation is displayed for the respective axis. You cannot edit these values here.
	Mirror	The mirror axis that was defined by means of the "Mirroring" transformation is displayed. You cannot edit these values here.
	Total offset	
	Total	The total offset resulting from the base offset and all active work offsets and coordinate transformations appears.
61	Additional axes	With the "Additional axes" softkey, you can display two additional rotary axes and determine their offset. These additional axes must be activated via machine data.
		Please refer to the machine manufacturer's instructions.
\$	Vork WOs Work	Press the "Work offset" softkey in the "Tools WOs" operating area.
		The work offset list appears.



2.14.3 Selecting/deselecting the work offset in the Manual area



2.15 Switching to CNC-ISO mode



You can switch from the ShopMill interface to the CNC ISO standard operator interface of the SINUMERIK 840D or 840D/840Di/810D system by pressing the "CNC ISO" softkey.

Softkey "CNC ISO" will work only if the machine manufacturer has implemented the function internally via the PLC interface.

Please refer to the machine manufacturer's instructions.

If the "CNC ISO" softkey is active, the following basic display of the CNC ISO operator interface appears on your screen:

Machine			Jog				
Channel re	eset						AUTO
≛ <u>∡</u> ± WCS	Positior	n Repo:	5 offset	Master	spindle	S1	MDA
+ X	0.000	ð mm	0.000	Act. +	0.00	Ю грм	
+ Y	0.000	ð nn	0.000	Set	0.00	Ю грм	JOG
+ 🔼	0.000	ð mm	0.000	Pos	0.00	00 deg	
+	0.000	ð mm	0.000		0.00	10 × 01	REPOS
				Power EX			
				Feedrate	nn∕nin		REF
				Act.	0.000	0.000 %	
				381 T1	0.000	_	
				1001	_	4	
				Preselect	ed tool:		
				•			
							Single block
Machine	Parameter	Program	Services	Diagnosis	Startup	ShopMill	

ShopMill

If you wish to return to the ShopMill operator interface, press the "ShopMill" softkey.

If you are working in the CNC ISO operator interface, please **read** the User Documentation for the SINUMERIK 840D/840Di/810D system (see Appendix, List of References).



2.16 ShopMill Open (PCU 50)

The ShopMill software is available for the PCU 50 in two versions, ShopMill Classic and ShopMill Open. ShopMill Classic is the software package previously marketed under the name ShopMill.

The difference between ShopMill Open and ShopMill Classic is that the Open variant has a basic menu bar or extended basic menu bar. ShopMill Open does not offer the option of switching to the CNC ISO user interface. Instead, the HMI Advanced operating areas "Services", "Diagnosis", "Start-up", and "Parameters" (without tool management and work offsets), are located directly on the extended horizontal softkey bar.



For a detailed description of the integrated HMI Advanced operating areas, please refer to:

References: /BAD/, Operator's Guide HMI Advanced SINUMERIK 840D/840Di/810D

Some of the softkeys in the basic menu or extended menu bars may be assigned to other operating areas by the machine manufacturer.

Please refer to the machine manufacturer's instructions.

2.17 Remote diagnostics

Remote diagnosis

The control system can be operated from an external PC by means of a remote diagnostic function. You can use a modem to link the control system and the external PC.

The remote diagnostics function is activated on the CNC ISO operator interface in the Diagnosis operating area.

Remote Diagnosis is a software option.

For further information about remote diagnosis, please refer to: **References:** /FB/, Description of Functions Extended Functions, F3

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3.1 Basics of programming

Important	Please pay particular attention to the following fundamental principles when writing programs for your machine tool!
Axes	The 3 main axes on milling machines are designated as X, Y and Z. Axis Z is normally the tool axis.
Dimensions in metric or inch	The control system can process both metric and inch dimensions. Depending on the basic setting you choose, the control interprets all geometric values as either metric or inch dimensions. Irrespective of the basic setting, you can set metric or inch dimensions in the program header (define blank). All dimensions stated in this section are metric.
Absolute dimensioning	With the absolute dimensioning method, dimensions refer to the zero point of the coordinate system of the total offset.
Incremental dimensioning	With the incremental dimensioning method, the programmed positional numerical value corresponds to the path to be traversed. The sign indicates the traversing direction.
Tool T	A tool must be programmed for every cutting operation. With the ShopMill machining cycles, a tool selection is already integrated in every parameterization screenform. Exception: You must select a tool before programming simple straight lines and circles. Tool selection is modal with straight line/circle, i.e. if several machining steps with the same tool occur in succession, you only need to program the tool for the 1st straight line/circle.
Tool length compensation	Tool length compensations take effect immediately the tool is loaded into the spindle. Different tool offsets can be assigned to each tool with multiple cutting edges. The tool length compensation of the spindle tool remains active even after the program has been executed (RESET).

Tool radius compensation	The tool radius compensation is automatically included in the cycles except for path milling. You can machine with or without radius compensation in conjunction with the "Path milling" and "Line" functions. In the case of the "Line" function, the tool radius compensation has a modal action, i.e. it is not automatically deactivated again.	
Spindle speed	The spindle speed (S) determines the number of spindle rotations per minute. The CW/CCW setting is made in the tool list in ShopMill.	
	Programming: The spindle speed is input when a new tool is loaded into the spindle. As an alternative to spindle speed, a cutting rate (V) can be specified in m/min.	
	Spindle start/spindle stop: The spindle is started directly after a new tool has been loaded. It is stopped on Reset, end of program or tool change.	
Cutting rate	Peripheral speed at which the tool cutting edge machines the workpiece. Cutting rates (V) are specified in m/min.	

Cutting rate



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Traversing at rapidThe programmed path is traversed along a straight line at the fastesttraversepossible velocity without the workpiece being machined. Rapidtraverse is a non-modal command, i.e. if you want the axis to traverserapidly in the next block, then you must enter "Rapid traverse" asfeedrate (F) again.

If you do not program a feedrate or rapid traverse, the axis is automatically traversed at the last programmed feed value (machining feedrate).

Traversing at feedrate
(machining feedrate)The tool travels at the programmed feedrate F along a straight line or
on a circle to the programmed end point and then machines the
workpiece. Machining feedrates (F) are specified in mm/min, mm/rev
or mm/tooth. The feedrate for milling cycles is automatically converted
on switchover from mm/min to mm/rev and vice versa.

With milling cycles, the feedrate for rough cutting is relative to the milling tool center point. This also applies to finish cutting, with the exception of concave curves where the feedrate is relative to the cutting edge (contact point between milling tool and workpiece).

Feedrate in mm/tooth

Mills are multi-edged tools. For this reason, a value must be found which guarantees that each cutting edge can machine the workpiece under the best possible conditions. Feed per tooth corresponds to the linear path traversed by the mill when a tooth is engaged. Feed per tooth is also the effective distance covered by the table feed between the engagement of two successive cutting edges.



Feedrate in mm/tooth

The machining feedrate is modal, i.e. even if the machining process changes, you need not enter a new feedrate if the feedrate programmed in the preceding block is still appropriate. This applies even if you have programmed a rapid traverse command in between.



The program is divided into 3 subsections: Program header, program blocks and program end. These sub-areas form a machining plan.



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3.3 Creating a sequential control program



For sequential control programs that you create directly at the machine, you require a software option.

3.3.1 Creating a new program; defining a blank

New programs are set up in the "Program Manager" area. Select with softkey Pro-Programs New ShopMill NC gram Program > Entering the program Enter a program name. name Program names may be a maximum of 24 characters in length. You can use any letters, digits or the underscore symbol (). ShopMill automatically changes lower case to upper case. "Periods" are not permitted in program names because such programs cannot be deleted again. Confirm the program name by pressing DK softkey or with the "Input" key INPUT the The screenform for setting the "Program header" parameters then appears. Parameterizing the PROGRAM program header NEU Work offs 0 Program header Alternat WO Basic ref.G500 mm Work offset Blank: Corner point1 XØ YØ -20.000 abs -100.000 abs ZØ 0.000 abs 20 Corner point 2 X1 Y1 abs abs **Z1** e abs Tool axis Z Retract plane: -20 100.000 abs RP Safety distance:



Set program header parameters

Drilling

-60

-40

-20

Milling å

20

-40

Z †

Strai.

Parameter settings in the program header are valid throughout the entire program.

Cont mill × Abort

Accept

Execute

1.000 inc

ſi

Simu-

Machining sense: Down-cut

Retract pos.-patt.: Optimized

SC

Various Parameters for input of a blank

- Work offset (WO) in which the workpiece zero is stored. You can select the work offset with the "Work Offset" softkey in the tool list or delete the default setting of the parameter if you do not want to state a work offset.
- Define the unit of measurement for the program [mm or inch].
- Workpiece corner point 1 (X0, Y0, Z0): Workpiece corner point 1 is the reference point for the blank dimensions. It must be entered as an absolute value.
- Workpiece corner point 2 or dimensions (X1, Y1, Z1 or L, W, H):

Workpiece corner point 2 is opposite workpiece corner point 1. It must be entered as an absolute value. The deviations are the length, width and height of the blank.





Workpiece corner points 1 and 2

Workpiece corner point 1 and dimensions

- Tool axis: The tool length is calculated in the set axis.
- Retraction plane (RP) and safety clearance (SC): Planes above the workpiece.

During machining the tool travels in rapid traverse from the tool change point to the return plan and then to the safety clearance. The machining feedrate is activated at this level. When the machining operation is finished, the tool travels at machining feedrate away from the workpiece onto the safety clearance level. It travels from the safety clearance to the retraction plane and then to the tool change point in rapid traverse.

The retraction plane is entered as an absolute value.

The safety clearance must be entered as an incremental value (without sign).

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Retraction plane (RP) and safety clearance (SC)



Safety clearance for varying workpiece heights

• Machining direction:

When machining a pocket, a longitudinal slot, or a spigot, ShopMill takes the machining direction (down-cut or up-cut) and the spindle direction in the tool list into account. The pocket is then machined in a clockwise or counterclockwise direction.



Machining pockets in climb or conventional milling operation with CW spindle rotation

During path milling, the programmed contour direction determines the machining direction.

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Retraction with position patterns:

When working with **optimized retraction**, the tool travels in relation to the contour across the workpiece at machining feedrate and safety clearance (SC). On retraction **to RP**, the tool is retracted to the retraction plane when the machining step is complete and infeeds at the new position. Collisions with workpiece obstacles are thus prevented when the tool is retracted and fed in, e.g. when holes in pockets or grooves are machined at different levels and positions.



Storing parameters

Select with the Accept softkey.

The parameters you have entered are stored. The machining plan is then displayed.

Program end

ShopMill has automatically defined the program end.

clear a default field, the "Accept" softkey disappears from the display!

3

3.3.2 Programming new blocks

	Creating new program blocks	Once you have defined the blank, you can define machining operations, feedrates and positions in individual program blocks. You will be supported by "Help" displays for individual machining operations.
		A large amount of memory is available for one program.
		However, depending on the storage space required, you can only program a limited number of blocks.
		 PCU 20 You can program up to 1000 blocks with the "Straight" function or up to 600 blocks with the "Mill pocket" function. PCU 50 You can program up to 3500 blocks with the "Straight" function or up to 2100 blocks with the "Mill pocket" function.
8		In the case of multiple clampings, a program can easily contain more than the permissible number of program blocks. If a message tells you that too many blocks are present, group together machining operations with the same tool in a subroutine. That way, you can open and execute the program.
Ť	Note	New programming blocks are always inserted after the selected block. You cannot program blocks before the program header or after program end.
	Parameter input fields	
		Feedrate: If you do not program a value for feedrate (F) (empty field), the system uses the last programmed feedrate.
		Clear an input field: Use the DEL key (or Backspace key) to clear an input field, i.e. to delete the programmed value.
		Preset (default) or empty parameter fields: You must always enter a value in fields with a preset default. If you

"Alternat." softkey and toggle key:

If the cursor is positioned on an input field with various setting options, the "Alternat." softkey is automatically displayed on the vertical softkey bar (see "Alternat." softkey in Sec. "Important softkeys for operation and programming").

Roughing/finishing:

Every cycle can be programmed with roughing or finishing. If you wish to rough cut the workpiece first and then finish cut it, you must call the cycle a second time. The programmed values do not change if you call the cycle again.

Some cycles offer roughing and finishing as a **complete machining** operation, i.e. you need only call the cycle once.

Approaching a cycle

- Approach the programmed cycles with ShopMill
 - Tool is above the retraction plane (RP):
 Positioning of the tool is performed at rapid traverse in the X/Y plane and then in the Z direction to the retraction plane (RP)



Approach to cycle above the retraction plane

- or tool is below the retraction plane (RP):
Positioning of the tool is performed at rapid traverse first in the Z direction to the retraction plane (RP) and then at rapid traverse in the X/Y plane



Approach to cycle below the retraction plane

- Tool axis travels in rapid traverse to safety clearance (SC)
- The cycle is then processed at the programmed machining feedrate
- On completion of machining, the tool travels to the cycle center in the X/Y plane at machining feedrate and then moves away from the workpiece with the tool axis until it reaches safety clearance
- The tool axis then retracts to the retraction plane in rapid traverse
- The tool change point is approached from the retraction plane in rapid traverse

3.3.3 Changing program blocks



- You can optimize the parameters in the programmed ShopMill blocks later or adapt them to new situations, e.g. if you want to increase the feedrate or change a position. In this case, you can change all the parameters in every program block directly in the associated parameterization screen form.
- Press the "Program" softkey.

The directory overview is displayed.

- Place the cursor on the directory that contains the program that you want to open.
- > Press the "Input" or "Cursor Right" key.

All the programs in this directory are displayed.

- > Select the program that you want to change.
- > Press the "Input" or "Cursor Right" key.

The machining plan of the program is displayed.

► -or- Accept Place the cursor on the desired program block in the machining plan.

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> Press the "Cursor Right" key.

The parameter screen for the selected program block appears.

- > Make the desired changes.
- Press the "Accept" softkey or the "Cursor left" key.

The changes are accepted in the program.

3.3.4 Program editor





You use the program editor when you want to change the sequence of program blocks within a program, delete program blocks or copy program blocks from one program to another.

The following functions are available in the program editor:

Select

You can select several program blocks simultaneously, for example, for cutting and pasting them subsequently.

- Copy/paste You can copy and paste program blocks within a program or between different programs.
- Cut

You can cut and therefore delete program blocks. However, the program blocks remain in the buffer, so you can still paste them in somewhere else.

• Search

You can search for a specific block number or any character string in a program.

Rename

You can rename a contour in the program editor, e.g. if you have copied the contour.

• Number

If you insert a new or copied program block between two existing program blocks, ShopMill automatically generates a new block number. This block number may be higher than the one in the following block. You can use the "Numbering" function to number the program blocks in ascending order.



3

,	Opening the program editor	۶	Select a program.
			Press the "Expansion" key.
			e softkeys for the program editor are displayed in the vertical ftkey bar.
	Selecting a program block		Place the cursor in the machining plan on the first or last block you want to select.
	Mark		Press the "Mark" softkey.
			Use the cursor keys to select any further program blocks.
		Th	e program blocks are marked.
	Copying a program block		Select the program block(s) in the machining plan.
	Сору		Press the "Copy" softkey.
		Th	e program blocks are copied into buffer memory.
	Cutting a program block		Select the program block(s) in the machining plan.
	Cut		Press the "Cut" softkey.
		Th in l	e program blocks are removed from the machining plan and stored buffer memory.
	Pasting a program block		Copy or cut the desired program blocks in the machining plan.
		۶	Place the cursor on the line after which the program block(s) is (are) to be inserted.
	Insert		Press the "Insert" softkey.
		Th pro	e program blocks are inserted in the machining plan of the ogram.



Search	
Search	Press the "Search" softkey.
	 Enter a block number or text.
	Select whether the search is to commence at the start of the program or the current cursor position.
Search	Press the "Search" softkey.
	ShopMill searches the program. The cursor highlights the search hit.
Continue search	Press the "Continue search" softkey if you want to continue the search.
Renaming a contour	Place the cursor on a contour in the machining plan.
Rename	Press the "Rename" softkey.
	Enter a new name for the contour.
	Press the "OK" softkey.
OK	The name of the contour is changed and displayed in the machining plan.
Numbering program blocks Renumber	 Press the "Renumber" softkey. The program blocks are renumbered in ascending order.
Closing the program editor Back	Press the "Back" softkey to close the program editor.



3.4	Programming the tool, offset value and spindle speed
-----	--

General information	When you program cycles, you will find the tool displayed in the screenform. When you program a line or a circular arc, you will have to select a tool beforehand.		
	Select with softkey:		
Programming a tool (T)	Select parameter field "T". ShopMill allows you to enter tools in several different ways:		
	Method 1:Enter the name or number of a tool via the keyboard.Method 2:Press area the "Tool, offset" key, select a tool with the cursor keys and press theImage: to programsoftkey.The tool is copied into the parameter field.		
Cutting edge (D)	You can select/specify for each programmed tool whether you want to apply cutting edge offset values D. The offsets are stored in the tool list. You must program the correct tool edge number D for the different tools (counterbore with spigot, stepped drill, etc.) to avoid risk of collisions (see also Secs. "Programming examples for drilling" and "Tools and tool offsets").		
Spindle speed (S) or Cutting rate (V)	 In ShopMill you can program either the spindle speed (S) or the cutting rate (V). You can toggle between them using the "Alternat." key. In the milling cycles, the spindle speed is automatically converted to the cutting rate and vice versa. Spindle speed and cutting rate remain valid until you program a new tool. Spindle speeds are programmed in rev/min. Cutting rates are programmed in m/min You can set the direction of rotation of a tool in the tool list. 		

3



	Allowance (DR)	You can program an allowance on the tool radius in this parameter input field. A finishing allowance is then left when the contour is machined (see also Sec. "Tools and tool offsets"). The DR parameter is active until a ShopMill cycle (drilling, missing, contour missing) is programmed.
	Example	You want to leave a finishing allowance of 0.5 mm on a contour. DR must then be programmed with 0.5 mm. With a setting of DR=0, the programmed contour is cut without a finishing allowance.
3.5	Contour milling	
		The "Contour milling" function is used when you want to mill simple and complex contours. You can define open contours or closed contours (pockets, islands, spigots) and machine them with path milling or milling cycles.
=?		A contour comprises separate contour elements, whereby at least two and up to 250 elements result in a defined contour. You can also program chamfers, radii or tangential transitions between the contour elements.
		The integrated contour calculator calculates the intersection points of the individual contour elements taking into account the geometrical relationships, which allows you to enter incompletely dimensioned elements.
		With contour milling, you must always program the geometry of the contour before you program the technology. You have the option of machining contours of any type by path milling, stock removal from pockets with or without islands, or clearing spigots.
	Freely-definable contours	The machining of freely-definable open or closed contours is generally programmed as follows:
		 Enter contour You build up the contour gradually from a series of different contour elements. Path milling (roughing) The contour is machined taking into account various approach and retract strategies. Path milling (finishing) If you programmed a finishing allowance for roughing, the contour is machined again. Path milling (chamfer) If you have planned edge breaking, chamfer the workpiece with a
		special tool.

3

Contours for pockets or islands	Contours for pockets or islands must be closed, i.e. the start point and end point of the contour are identical. You can also mill pockets that contain one or more islands. The islands can also be located partially outside the pocket or overlap each other. ShopMill interprets the first contour specified as a pocket contour and all others as islands.
	The machining of contour pockets with islands is generally programmed as follows:
	 Enter contour for the pocket You build up the contour pocket gradually from a series of different contour elements.
	 Enter contour for the island You enter the contour for the island after the contour for the pocket
	 Centering predrilling of the contour pocket If you want to predrill the contour pocket, you can center the drill hole first to prevent the drill slipping.
	 Predrill contour pocket If you want the cutter to plunge into the material vertically and if a milling cutter with an end tooth is not available, you can predrill the pocket.
	 Remove stock from contour pocket with island (roughing) The stock is removed from the contour pocket complete with island taking into account various insertion strategies.
	 Remove residual material (roughing) During stock removal from the pocket, ShopMill automatically detects residual material that has been left. A suitable tool will allow you to remove this without having to machine the complete pocket again.
	 Finish contour pocket with island (finish edge/base) If you programmed a finishing allowance for the edge/base when you programmed roughing, the pocket edge/base will be machined again.

All machining steps involved in the contour milling operation are shown in the machining plan in square brackets.

MI	MILLING				
Ρ		N5	MILLING		
\sim	٦	N10	CONTOURPOCKET		
\sim	-	N15	CONTOURISLAND		
т.	+	N2Ø	Centering		
79 79-77.	+	N25	Rough drilling		
Ø.	+	N3Ø	Mill pocket ⊽		
52	+	N35	Pocket res.mat. ⊽		
Ø.		N40	Mill pocket 👘 🛷 w		
END			Program end		

Example: Removing stock from a contour pocket

Contours for spigots

Contours for spigots must be closed, i.e. the start point and end point of the contour are identical. You can define multiple spigots, which can also overlap. ShopMill interprets the first contour specified as a blank contour and all others as spigots.

The machining of contour spigots is generally programmed as follows:

1. Enter the blank contour

i.e. the outer limits of the material. The tool moves at rapid traverse outside this area. Material is then removed between the blank contour and spigot contour.

- Enter contour for the spigot
 You enter the contour for the spigot after the blank contour.
- 3. Clear contour spigot (roughing) The contour spigot is cleared.
- Remove residual material (roughing)
 As it mills the spigot, ShopMill automatically detects residual material that has been left behind. A suitable tool will allow you to remove this without having to machine the complete spigot again.
- Finish contour spigot (edge/base finishing)
 If you programmed a finishing allowance for roughing, the spigot edge/base is machined again.





Symbolic representation



ShopMill represents a contour as one program block in the machining plan. If you open this block, the individual contour elements are listed symbolically and displayed in broken-line graphics.



The individual contour elements are represented by symbols adjacent to the graphics window. They appear in the order in which they were entered.

Contour element	Symbol	Meaning
Start point	\oplus	Start point of contour
Straight line up	Ť	Straight line in 90° matrix
Straight line down	Ļ	Straight line in 90° matrix
Straight line left	←	Straight line in 90° matrix
Straight line right	→	Straight line in 90° matrix
Straight line in any direction	>	Straight line with any gradient
Arc Right	\sim	Circle
Arc Left	\sim	Circle
Finish contour	END	End of contour definition

The different color of the symbols indicates their status:

Foreground	Background	Meaning
-	red	Cursor on new element
black	red	Cursor on current element
black	white	Normal element
red	white	Element not currently evaluated
		(element will only be evaluated when
		it is selected with the cursor)

Graphical representation

The progress of contour programming is shown in broken-line graphics while the contour elements are being entered.



Graphical presentation of the contour during contour milling

When the contour element has been created, it can be displayed in different line styles and colors:

- Black: Programmed contour
- Orange: Current contour element
 - Green dashed: Alternative element
- Blue dotted: Partially defined element

The scaling of the coordinate system is adjusted automatically to match the complete contour.

The position of the coordinate system is displayed in the graphics window.



3.5.2 Creating a new contour



Enter the individual contour elements (see Sec. "Creating contour elements").



Polar starting point	
Pole	Press the "Pole" softkey.
	Enter the pole position in Cartesian coordinates.
	Enter the starting point for the contour in polar coordinates.
	Enter any additional commands in G code format, as required.
Accept	Press the "Accept" softkey.
	 Enter the individual contour elements (see Sec. "Creating contour elements").

A	Parameters	Description	Unit
	Tool axis	Select Z as the tool axis, if the starting point/pole is in X / Y	
		Select X as the tool axis, if the starting point/pole is in Y / Z	
		Select Y as the tool axis, if the starting point/pole is in X / Z	
		The coordinates also change for contour elements	
		Cartesian:	
	Х	Start point in X direction (abs.)	mm
	Y	Start point in Y direction (abs.)	mm
		Polar:	
	Х	Pole position in X direction (abs.)	mm
	Y	Pole position in Y direction (abs.)	mm
	L1	Distance between pole and start point for contour (abs.)	mm
	φ1	Polar angle between pole and start point for contour (abs.)	Degr.
	Additional	Any additional command in G code format	
	command		



3.5.3 Creating contour elements



10.04

When you have created a new contour and specified the start point, you can define the individual elements that the contour comprises.

The following contour elements are available for the definition of a contour:

- Horizontal line
- Vertical line
- Diagonal line
- Circle / arc

For each contour element, you must parameterize a separate screen form. The coordinates for a horizontal or vertical line are entered in Cartesian format; however, for the contour elements Diagonal line and Circle/arc you can choose between Cartesian and polar coordinates. If you wish to enter polar coordinates you must first define a pole. If you have already defined a pole for the start point, you can also relate the polar coordinates to this pole. In this case there is therefore no need to define another pole.

Cylinder surface
transformationFor contours (e.g. slots) on cylinders, the angle data for lengths are
specified. If the 'cylinder surface transformation' function is activated
via the "Alternat." softkey, you can also define the lengths of contours
(in the circumferential direction of the cylinder envelope) with angle
data. In that case, instead of X, Y and I, J, you will enter Xa, Ya and
Ia, Ja (see also Sec. "Cylinder surface transformation").

Please refer to the machine manufacturer's instructions.

Parameter inputParameter entry is supported by various "help displays" that explain
the parameters.

If you leave certain fields blank, ShopMill assumes that the values are unknown and attempts to calculate them from other parameters.

Conflicts may result if you enter more parameters than are absolutely necessary for a contour. In such a case, try entering less parameters and allowing ShopMill to calculate as many parameters as possible.

3

Machining direction	In the case of path milling, the contour is always machined in the
	programmed direction. By programming the contour in the clockwise
	direction or counterclockwise direction, you can determine whether
	the contour is machined with down-cut milling or up-cut milling (see
	the following table).

Outside contour			
Required direction of	CW spindle rotation	CCW spindle rotation	
rotation for machining			
Down-cut	Programming in clockwise direction	Programming in counterclockwise	
	CCW cutter radius compensation	direction, CW cutter radius compensation	
Up-cut	Programming in counterclockwise	Programming in clockwise direction	
	direction, CW cutter radius compensation	CCW cutter radius compensation	

Inside contour			
Required direction of rotation for machining	CW spindle rotation	CCW spindle rotation	
Down-cut	Programming in counterclockwise direction, CCW cutter radius compensation	Programming in clockwise direction CW cutter radius compensation	
Up-cut	Programming in clockwise direction CW cutter radius compensation	Programming in counterclockwise direction, CCW cutter radius compensation	

Contour transition elements	As a transition between two contour elements, you can choose a radius or a chamfer. The transition is always appended to the end of a contour element. The contour transition is selected in the parameterization screen form of the contour element.
	You can use a contour transition element whenever there is an intersection between two successive elements which can be calculated from input values. Otherwise you must use the "Straight/Circle" contour elements.
	That means that for a closed counter, you can also program a transition element from the last to the first element of the contour. The contour starting point is outside the contour after you have programmed the transition.
Additional commands	For each contour element, you can enter any additional commands in G code format. For example, you can program "G9" deceleration, exact stop for the circle contour element. You can enter the additional commands (max. 40 characters) in the extended parameterization screen form ("All parameters" softkey).

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Additional functions

The following additional functions are available for programming a contour:

- Tangent to preceding element You can program the transition to the preceding element as a
- If two different possible contours result from the parameters entered thus far, one of the options must be selected.
- From the current position, you can close the contour with a straight
- > Enter all the data available from the workpiece drawing in the input form (e.g. length of straight line, target position, transition to
- Repeat the procedure until the contour is complete.

The programmed contour is transferred to the machining plan.

If you want to display further parameters for certain contour elements, e.g. to enter additional commands, press the "All parameters" softkey.

If you wish to enter the contour elements Diagonal line and Circle/arc in polar coordinates, you must first define a pole.

The pole is defined. You can now choose between "Cartesian" and "Polar" in the input screen form for the Diagonal line and Circle/Arc



Tangent to preceding element	When entering data for a contour element you can program the transition to the preceding element as a tangent.	
Tangent to	Press the "Tangent to prec. elem." softkey.	
	The angle to the preceding element $\alpha 2$ is set to 0°. The "tangential" selection appears in the parameter input field.	
Selecting a dialog	When entering data for a contour element, there may be two different contour options, one of which you have to select.	
Select dialog	Press the "Select dialog" softkey to switch between the two different contour options.	
	The selected contour appears in the graphics window as a solid black line and the alternative contour appears as a dashed green line.	
Accept dialog	Press the "Accept dialog" softkey to accept the chosen alternative.	
Closing the contour	A contour always has to be closed. If you do not wish to create all contour elements from starting point to starting point, you can close the contour from the current position to the starting point.	
Continue Close contour	Press the "Continue" and "Close contour" softkeys.	

ShopMill inserts a straight line between your current position and the starting point.

A	Parameters	Description for contour element "straight line"	Unit
U			
		Cartesian:	
	x	End point in the X direction (abs. or inc.)	mm
		Incremental dimensions: The plus/minus sign is evaluated.	
	Y	End point in the Y direction (abs. or inc.)	mm
		Incremental dimensions: The plus/minus sign is evaluated.	
	L	Length of line	mm
	α1	Starting angle to X axis	Degr.
	α2	Angle to preceding element	Degr.
		Tangential transition: α 2=0	
		Polar:	
	L1	abs: distance between pole and end point	mm
		inc: distance between final point and end point	mm
		Incremental dimensions: The plus/minus sign is evaluated.	
	φ1	abs: polar angle between pole and end point	Degr.
		inc: polar angle between final point and end point	Degr.
		Incremental dimensions: The plus/minus sign is evaluated.	



L	Length of line	mm
α1	Starting angle to X axis	Degr.
α2	Angle to preceding element	Degr.
	Tangential transition: α 2=0	
Transition to	FS: Chamfer as transition element to next contour element	mm
following	R: Radius as transition element to next contour element	mm
element		
Additional	Any additional command in G code format	
command		

ê	Parameters	Description for contour element "circle"	Unit
	Direction of	Clockwise rotation	
	rotation		
		Counterclockwise rotation	
	R	Radius of circle	mm
		Cartesian:	
	Х	End point in the X direction (abs. or inc.)	mm
		Incremental dimensions: The plus/minus sign is evaluated.	
	Y	End point in the Y direction (abs. or inc.)	mm
		Incremental dimensions: The plus/minus sign is evaluated.	
	1	Circle center point in X direction (abs. or inc.)	mm
		Incremental dimensions: The plus/minus sign is evaluated.	
	J	Circle center point in Y direction (abs. or inc.)	mm
		Incremental dimensions: The plus/minus sign is evaluated.	_
	α1	Starting angle to X axis	Degr.
	α2	Angle to preceding element	Degr.
		Tangential transition: $\alpha 2=0$	_
	β1	End angle to X axis	Degr.
	β2	Angle of aperture of circle	Degr.
		Polar:	
	L1	abs: distance between pole and end point	mm
		inc: distance between final point and end point	mm
		Incremental dimensions: The plus/minus sign is evaluated.	
	φ1	abs: polar angle between pole and end point	Degr.
		inc: polar angle between final point and end point	Degr.
		Incremental dimensions: The plus/minus sign is evaluated.	
	L2	abs: distance between pole and center of circle	mm
		inc: distance between final point and center of circle	mm
		Incremental dimensions: The plus/minus sign is evaluated.	
	φ2	abs: polar angle between pole and center of circle	Degr.
		inc: polar angle between final point and center of circle	Degr.
		Incremental dimensions: The plus/minus sign is evaluated.	_
	α1	Starting angle to X axis	Degr.
	α2	Angle to preceding element	Degr.
		Tangential transition: $\alpha 2=0$	
	β1	End angle to X axis	Degr.
	β2	Angle of aperture of circle	Degr.
	Transition to	FS: Chamfer as transition element to next contour element	mm
	following	R: Radius as transition element to next contour element	mm
	element		
	Additional	Any additional command in G code format	
	command		
	1		1



3.5.4 Changing a contour



	Changing the selected dialog	If when you entered the data for a contour element there were two different contour options and you chose the wrong one, you can alter your choice afterwards. If the contour is unique as a result of other parameters, the system will not prompt you to make a selection.	
		Open the input screen form for the contour element.	
	Change	Press the "Change selection" softkey.	
	Selection	The two selection options appear again.	
	Select dialog	Press the "Select dialog" softkey to switch between the two different contour options.	
	Accept	Press the "Accept dialog" softkey.	
	dialog	The chosen alternative is accepted.	
	Inserting a contour element	Select the contour in the machining plan.	
		Press the "Cursor Right" key.	
		The individual contour elements are listed.	
		Position the cursor on the contour element after which the new element is to be inserted.	
	t (*)	Select a new contour element via softkey.	
	1 1 1	Enter the parameters in the input screen.	
	Accent	Press the "Accept" softkey.	
		The contour element is inserted in the contour. Subsequent contour elements are updated automatically according to the new contour status.	
1		When you insert a new element into a contour, the remaining contour elements are not interpreted until you select the symbol for the first subsequent element alongside the graphics window using the cursor. The end point of the inserted element may not correspond to the start point of the subsequent element. In this case, ShopMill outputs the error message "Geometrical data contradictory". To rectify the problem, insert an incline without entering parameter values.	



Deleting a contour element	Select the contour in the machining plan.
	Press the "Cursor Right" key.
	The individual contour elements are listed.
	Place the cursor on the contour element that you want to delete.
Delete element	Press the "Delete element" softkey.
	Press the "Delete" softkey.
	The selected contour element is deleted.

3.5.5 Programming examples for freely defined contours



Example 1

Starting point: X=0 abs., Y=5.7 abs. The contour is programmed in the clockwise direction with dialog selection.





Element	Input	Remarks
\frown	CCW rotation, R=9.5, I=0 abs., make dialog selection, transition to following element: R=2	
\sim	α1=-30 degrees	Observe angles in help screen!
	CW rotation, tangent prev. elem.,	
4 7	R=2, J=4.65 abs.	
(CCW rotation, tangent prev. elem.	
4 4	R=3.2, I=11.5 abs., J=0 abs., make dialog selection,	
	Make dialog selection	



\frown	CW direction of rotation, tangent to preced. R=2, J=–4.65 abs., select dialog	
\times	Tangent to previous element Y=–14.8 abs., –1=–158 degrees	Observe angles in help screen!
←•→	All parameters, L=5, select dialog	
ŧ	Y=5.7 abs.	
←=→	X=0 abs.	



Example 2

Starting point: X=0 abs., Y=0 abs.

The contour is programmed in the clockwise direction with dialog selection. It is advisable to display all parameters for this contour by selecting the "All param." softkey.



Workpiece drawing of contour

Element	Input	Remarks
÷	Y=–104 abs.	
(CW rotation, R=79, I=0 abs., make dialog selection,	
4 4	all parameters, β 2=30 degrees	
6	CW rotation, tangent prev. elem.	
4 4	R=7.5, all parameters, β 2=180 degrees	
)	CCW rotation, R=64, X=–6 abs., I=0 abs.,	
4 4	make dialog selection, make dialog selection	
	Transition to following element: R=5	
Ť	All parameters, α1=90 degrees,	Observe angles in help
‡	Transition to following element: R=5	screen!
(Direction of rotation right, R=25, X=0 abs., Y=0 abs. I=0 abs.,	
4 7	make dialog selection, make dialog selection	



Example 3

Starting point: X=5.67 abs., Y=0 abs. The contour is programmed in the counterclockwise direction.



Workpiece drawing of contour

Element	Input	Remarks
\longleftrightarrow	All parameters, α1=180 degrees	Observe angles in help screen!
	X=–43.972 inc, all parameters	Coordinate X in "abs" and in "inc"
← •→	X=–137.257 abs, –1=–125 degrees	Observe angles in help screen!
- K.A	X=43.972 inc	Coordinate X in "abs" and in "inc"
\sim	α 1=–55 degrees	Observe angles in help screen!
\longleftrightarrow	X=5.67 abs	
\sim	CW rotation, R=72, X=5.67 abs., Y=0 abs.,	
4 7	make dialog selection	



3.5.6 Path milling



You can mill along any contour you have programmed with the "Path milling" function. The function operates with cutter radius compensation. Machining can be performed in either direction, i.e. in the direction of the programmed contour or in the opposite direction. The contour does not have to be closed. You can perform any of the following operations:

- Inside or outside machining (on left or right of the contour).
- Machining along center-point path

For machining in the opposite direction, contours must not consist of more than 170 contour elements (incl. chamfers/radii).

Special aspects (except for feed values) of free G code input are ignored during path milling in the opposite direction to the contour.



 \mathbf{b} Press the "Cont. mill." and "Path milling" softkeys.

Path milling on right or left A programmed contour can be machined with the cutter radius on the of the contour

Approach/retraction mode

right or left. You can also select various modes and strategies of approach and retraction from the contour.

The tool can approach or retract from the contour along a quadrant, semi-circle or straight line.

- With a quadrant or semi-circle approach path, you must enter the current center point path.
- With a straight line, you must specify the distance between the cutter outer edge and the contour start or end point.

You can also program a mixture of modes, e.g. approach along quadrant, retract along semi-circle.



Approach and retraction along straight line, quadrant and semi-circle; (L1=approach length, L2=retract length, R1=approach radius, R2=retract radius)

Approach/retraction strategy	You can choose between approach/retraction:	planar approach/retraction and spatial
	Planar approach:	First approach depth in the Z direction then in the XY plane.
	Spatial approach:	Approach in depth and plane simultaneous.
	 Retraction is performe Mixed programming is plane, retract spatially. 	d in reverse order. possible, for example, approach in the
Path milling along the center-point path	A programmed contour ca path if the operation has b x (no radius compensatio is only possible along a st	an also be machined along the center-point been activated under radius compensation n). In this case, approaching and retraction traight line or vertical. Vertical

approach/retraction can be used for closed contours, for example.

Parameters	Description	Unit
T, D, F, S, V	See Sec. "Programming the tool, offset value and spindle speed".	
Radius	Machining to the left of the contour	
compensation	Machining to the right of the contour	
	Machining along the center path	
Machining type	Roughing	
	Finishing	
	Chamfer	
Machining	Forward: machining is performed in the programmed contour direction	
direction	Backward: machining is performed in the opposite direction to the programmed	
	contour	
Z0	Reference plane (abs. or inc.)	
Z1	End depth (abs. or inc.) (not for chamfer)	mm
DZ	Infeed depth (not for chamfer)	mm
FS	Chamfer width (for chamfer only), inc.	mm
ZFS	Insertion depth tool tip (for chamfer only), abs. or inc.	mm
UZ	Finishing allowance base (not for chamfer)	mm

UXY	Finishing allowance on edge (not applicable to center-point path machining	mm
	operations) (not for chamfer)	
Approach	Quadrant: Part of a spiral (only with path milling left and right of the contour)	
mode	Semicircle: Part of a spiral (only with path milling left and right of the contour)	
	Linear: Slope in space	
	Perpendicular: Perpendicular to the path (only with path milling on the center path)	
Approach		
strategy	l [¥] →] planar	
	three-dimensionally (not with perpendicular approach mode)	
P1 or L1	Approach radius (only for path milling on left and right of contour) approach length	mm
Retract mode	Quadrant: Part of a spiral (only with path milling left and right of the contour)	
	Semicircle: Part of a spiral (only with path milling left and right of the contour)	
	Linear: Slope in space	
	Perpendicular: Perpendicular to the path (only with path milling on the center path)	
Retract		
strategy	j planar	
	spatial (not with perpendicular approach mode)	
R2 or L2	Retract radius (only for path milling on left and right of contour), retract length	mm
Retraction	If more than one depth infeed is necessary, specify the retraction height to which the	
mode	tool retracts between the separate infeeds (in the transition from the end of the	
	contour to the beginning).	
	Z0 + safety clearance	
	Safety clearance	
	To retraction plane	
	No retraction	





3.5.7 Predrilling a contour pocket

If a milling tool cannot be inserted in the center to remove stock from contour pockets, it is necessary to rough-drill first.

The number and positions of the required rough drill holes depends on certain conditions, e.g. type of contour, tool, plane infeed, finishing allowances.

The rough-drilling cycle comprises a centering cycle and the actual rough-drilling cycle.

The drilling positions in the contour pocket cycle are determined when the contour pocket is calculated. This calculation generates a special drilling program that is called in the rough drilling cycles (centering and rough drilling).

Contour pocket
Contour island
Rough drilling/centering contour pocket
Rough drilling/rough drilling contour pocket
Solid machining, roughing
Residual material
Solid machining, finishing plane
Solid machining, finishing depth

Example of a chain containing rough drilling (centering and rough drilling) and solid machining

If you mill several pockets and want to avoid unnecessary tool changeover, predrill all the pockets first and then remove the stock. In this case, for centering/predrilling, you also have to enter the parameters that appear when you press the "All parameters" softkey. Then program as follows:

- 1. Contour pocket 1
- 2. Centering
- 3. Contour pocket 2
- 4. Centering
- 5. Contour pocket 1
- 6. Predrilling
- 7. Contour pocket 2
- 8. Predrilling
- 9. Contour pocket 1
- 10.Remove stock
- 11.Contour pocket 2
- 12.Remove stock

If you are doing all the machining for the pocket at once, i.e. centering, rough-drilling and removing stock directly in sequence, and do not set the additional parameters for centering/rough-drilling, ShopMill will take these parameter values from the stock removal (roughing) machining step.

Centering



> Press the "Cont. Mill.", "Predrilling", and "Centering" softkeys.

Call the help display with the





Centering for a contour pocket

Parameters	Description	Unit
T, F, S	See Sec. "Programming the tool, offset value and spindle speed".	
TR	Reference tool for centering	
Z0	Workpiece height (abs.)	mm
Z1	Depth with reference to Z0 (inc.)	mm
DXY	Max. infeed plane Alternatively, you can specify the plane infeed as a %, as the ratio> plane infeed	mm
	(mm) to milling cutter diameter (mm).	%
UXY	Finishing allowance, plane	mm
Retraction mode	 Retraction mode before new infeed If a machining operation requires several insertion points, you can program the retraction height: To retraction plane Z0 + safety clearance On making the transition to the next insertion point, the tool returns to this height. If 	mm mm
	there are no elements larger than Z0 in the pocket area, "Z0 + safety clearance" can be selected as the retraction mode.	



Programming with ShopMill 3.5 Contour milling

2	
	- 4

Predrilling



> Press the "Cont. mill.", "Predrilling", and "Predrilling" softkeys.



Predrilling a contour pocket

Parameters	Description	Unit
T, F, S	See Sec. "Programming the tool, offset value and spindle speed".	
TR	Reference tool for predrilling	
Z0	Workpiece height (abs.)	mm
Z1	Depth with reference to Z0 (inc.)	mm
DXY	Max. infeed plane	mm
	Alternately, you can specify the plane infeed as a %, as the ratio> plane infeed	
	(mm) to milling cutter diameter (mm).	%
UXY	Finishing allowance, plane	mm
UZ	Finishing allowance, depth	mm
Retraction	Retraction mode before new infeed	
mode	If a machining operation requires several insertion points, you can program the	
	retraction height:	mm
	To retraction plane	mm
	• Z0 + safety clearance	
	On making the transition to the next insertion point, the tool returns to this height. If	
	there are no elements larger than Z0 in the pocket area, "Z0 + safety clearance" can be selected as the retraction mode.	



3.5.8 Milling a contour pocket (roughing)



Before you can machine a pocket with islands, you must enter the contour of the pocket and islands (see Sec. "Freely defined contours"). The first contour you specify is interpreted as the pocket contour and all the others as islands.

Using the programmed contours and the input screen form for solid machining, ShopMill generates a program which removes the pockets with islands from inside to outside in parallel to the contour. The direction is determined by the direction of rotation specified in the program header for machining (reverse or synchronous).

The islands can also be located partially outside the pocket or overlap each other.



> Press the "Cont. mill." and "Mill pocket" softkeys.







Help displays for solid machining

A	Parameters	Description	Unit
	T, F, V	See Sec. "Programming the tool, offset value and spindle speed".	
	Machining	Roughing	
	mode		
	Z0	Workpiece height (abs.)	mm
	Z1	Depth with reference to Z0 (abs. or inc.)	mm
	DXY	Max. infeed in X/Y plane.	mm
		Alternately, you can specify the plane infeed as a %, as a ratio \rightarrow plane infeed (mm)	
		to milling cutter diameter (mm).	%
	DZ	Max. infeed depth (abs. or inc.)	mm
	UXY	Finishing allowance, plane	mm
	ZU	Finishing allowance, depth	mm
	Start point	The starting point can be determined automatically or entered manually .	
	Х	Starting point X (abs.), manual input only	mm
	Y	Starting point Y (abs.), manual input only	mm

Insertion	Oscillation: The tool is inserted oscillating with the program. angle (EW).	
	Helical: The tool is inserted along a helical path with the	
	programmed radius (ER) and programmed pitch (EP).	
	Center: For this insertion strategy, a milling cutter is required that cuts in the	
	center. The programmed feed (FZ) is used for insertion.	
EW	Insertion angle (for oscillation only)	Degr.
FZ	Feedrate FZ (for center only)	mm/min
EP	Insertion gradient (for helical only)	mm/rev
	The gradient of the helix may be smaller in some geometric conditions.	
ER	Insertion radius (for helical only)	mm
	The radius must not be larger than the cutter radius, otherwise material will remain.	
	Also make sure the pocket is not violated.	
Retraction	If the machining operation requires several points of insertion, the retraction height	
mode	must be programmed:	
	To retraction plane	mm
	• Z0 + safety clearance (SC)	mm
	On making the transition to the next insertion point, the tool returns to this height.	
	If no elements greater than Z0 are in the pocket area, Z0 + safety clearance (SC)	
	can be programmed as the retraction mode.	

When input manually, the starting point can also be located outside the pocket. This can be useful, for example, when machining a pocket which is open on one side. The machining operation then begins without insertion with a linear movement into the open side of the pocket.

3.5.9 Removing residual material from a contour pocket

If you have removed stock in a pocket (with/without islands) and residual material still remains, ShopMill will detect this automatically. You can use a suitable tool to remove this residual material without having to machine the whole pocket again, i.e. avoiding unnecessary idle motions.

Material that remains as part of the finishing allowance is not residual material.

The residual material is calculated on the basis of the milling cutter used for stock removal.

If you mill several pockets and want to avoid unnecessary tool changeover, remove stock from all the pockets first and then remove the residual material. In this case, for removing the residual material, you also have to enter a value for the "Reference tool TR" parameter that appears when you press the "All parameters" softkey.

Programming with ShopMill 3.5 Contour milling



Then program as follows:

- 1. Contour pocket 1
- 2. Remove stock
- 3. Contour pocket 2
- 4. Remove stock
- 5. Contour pocket 1
- 6. Remove residual material
- 7. Contour pocket 2
- 8. Remove residual material

The "Residual material" function is a software option.



Cont. Pocket Res. Mat. >

> Press the "Cont. mill." and "Pocket Res. Mat." softkeys.

Call help display with the







Help display for residual material

Ē	Parameters	Description	Unit
	T, F, V	See Sec. "Programming the tool, offset value and spindle speed".	
	Machining type	Roughing	
	TR	Reference tool for residual material	
	Z0	Workpiece height (abs.)	mm
	Z1	Depth with reference to Z0 (abs. or inc.)	mm
	DXY	Max. infeed, plane	mm
		Alternatively, you can specify the plane infeed as a %, as a ratio> plane infeed	%
		(mm) to milling cutter diameter (mm).	
	DZ	Max. infeed, depth	mm
	UXY	Finishing allowance, plane	mm
	UZ	Finishing allowance, depth	mm



mm
mm

3.5.10 Finishing the contour pocket

		If you programmed stock removal from the pocket with a finishing allowance for the base or edge of the pocket, you still have to finish the pocket. Separate blocks must be programmed for finishing the base and/or for finishing the edge. In each case, the pocket will only be machined once. When finish cutting, ShopMill takes any existing island(s) into account as is the case for rough cutting.
_	Mill pocket >	 Press the "Cont. mill." and "Mill pocket" softkeys". Select "Finish base" or "Finish edge" in machining mode.
	Call help display with the key	Image: state of the state of

Parameters	Description of finish cut along base:	Unit
T, F, V	See Sec. "Programming the tool, offset value and spindle speed".	
Machining type	Finish base	
Z0	Workpiece height (abs.)	mm
Z1	Depth with reference to Z0 (abs. or inc.)	mm
DXY	Max. infeed, plane	mm
	Alternately, you can specify the plane infeed as a %, as a ratio> plane infeed (mm) to milling cutter diameter (mm).	%
UXY	Finishing allowance, plane	mm
UZ	Finishing allowance, depth	mm
Start point	The starting point can be determined automatically or entered manually. Manual entry allows for a start point outside the pocket, whereby straight line machining into the pocket is performed first, e.g. for a pocket with a side opening without any insertion.	
Х	Coordinate of starting point (abs.), manual input only	mm
Y	Coordinate of starting point (abs.), manual input only	mm
Insertion	Oscillation: The tool is inserted at the programmed angle (EW). Helical: The tool is inserted along a helical path with the programmed radius (ER) and programmed pitch (EP). Center: For this insertion strategy, a milling cutter is required that cuts in the center. The programmed feed (FZ) is used for insertion.	
EW	Insertion angle (for oscillation only)	Degr.
EP	Insertion gradient (only for helical) The gradient of the helix may be smaller in some geometric conditions.	mm/rev
ER	Insertion radius (only for helical) The radius must not be larger than the cutter radius, otherwise material will remain. Also make sure the pocket is not violated.	mm
FZ	Feedrate FZ (for Center only)	mm/min
Retraction mode	If the machining operation requires several points of insertion, the retraction height can be programmed:	
	 To retraction plane Z0 + safety clearance (SC) 	mm mm
	On making the transition to the next insertion point, the tool returns to this height. If no elements greater than Z0 are in the pocket area, Z0 + safety clearance (SC) can be programmed as the retraction mode.	



e	Parameters	Description of finish cut along edge:	Unit
	T, F, V	See Sec. "Programming the tool, offset value and spindle speed".	
	Machining type	Edge finishing	
	Z0	Workpiece height (abs.)	mm
	Z1	Depth with reference to Z0 (abs. or inc.)	mm
	DZ	Max. infeed, depth	mm
	UXY	Finishing allowance, plane	mm
	Retraction	If the machining operation requires several points of insertion, the retraction height	
	mode	can be programmed:	
		To retraction plane	mm
		• Z0 + safety clearance (SC)	mm
		On making the transition to the next insertion point, the tool returns to this height.	
		If no elements greater than Z0 are in the pocket area, Z0 + safety clearance (SC)	
		can be programmed as the retraction mode.	
		Note: An alternative to the "Edge finish cut" option is the "Path milling" function	
		which offers greater optimization potential (approach and retract strategies and	
		modes).	

3.5.11 Chamfering a contour pocket

If you have planned edge breaking, mill a chamfer after that.

> Press the "Cont. mill." and "Mill pocket" softkeys.

> Select "Chamfer" in machining mode.







If you want to mill a chamfer and have programmed inside corners without filleting during rounding, you must specify the radius of the finishing tool as the rounding in the contour.

Parameters	Description for chamfer:	Unit
T, F, V	See Sec. "Programming the tool, offset value and spindle speed".	
Machining type	Chamfer	
Z0	Workpiece height (abs.)	mm
FS	Chamfer width (for chamfer only), inc.	mm
ZFS	Insertion depth tool tip (for chamfer only), abs. or inc.	mm









3.5.12 Milling contour spigots (roughing)

	Use the "Mill spigot" function if you want to mill any kind of spigot.		
=?	Before you mill the spigot, you must first enter a blank contour and then one or more spigot contours. The blank contour defines the outer limits of the material. The tool moves at rapid traverse outside this area. Material is then removed between the blank contour and spigot contour.		
	You can select the machining mode (roughing or finishing) for milling. If you want to rough and then finish, you have to call the machining cycle twice (Block 1 = roughing, Block 2 = finishing). The programmed parameters are retained on the second call. For more on finishing, see Sec. "Finishing the contour spigot".		
8	If you only program a blank contour without a second contour for a spigot, you can face mill the blank contour.		
Approach/retraction	 The tool approaches the starting point at rapid traverse at the height of the retraction plane and adjusts to the safety clearance. The start point is calculated by ShopMill. The tool first infeeds to the machining depth and then approaches the spigot contour from the side in a quadrant at machining feedrate. The spigot is cleared in parallel with the contours from the outside in. The direction is determined by the machining direction (climb/conventional) (see "Creating a new program; defining a blank"). When the first plane of the spigot has been cleared, the tool retracts from the contour in a quadrant and then infeeds to the next machining depth. The spigot is again approached in a quadrant and cleared in parallel with the contours from outside in. Steps 4 and 5 are repeated until the programmed spigot depth is reached. The tool moves back to the safety clearance at rapid traverse. 		
Cont. mill. spi	 Press the "Cont. mill." and "Mill spigot" softkeys. Select "Roughing" machining mode. 		
5		6	
-----	---	----	---
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	-	-	

Parameters	Description for roughing	Unit
T, D, F, S, V See Sec. "Creating program blocks".		
Machining	✓ Roughing	
type		
Z0	Reference point in Z direction (abs.)	mm
Z1	Depth with reference to Z0 (abs. or inc.)	mm
DXY Maximum infeed in the XY plane		mm
	Plane infeed in %: Ratio of plane infeed (mm)	%
	to milling cutter diameter (mm)	
DZ	Maximum depth infeed (Z direction)	mm
UXY	Finishing allowance in plane	mm
UZ	Finishing allowance in depth	mm
Retraction If more than one approach point is necessary, specify the retraction height to whether t		
mode	the tool retracts between approach points.	
	To retraction plane	
	Z0 + safety clearance	
	If there are no spigots or other elements larger than Z0 in the machining area, "Z0 +	
	safety clearance" can be selected as the retraction mode.	

3.5.13 Removing residual material from a contour spigot

=?			

When you have milled a contour spigot and residual material remains in place, this is automatically detected by ShopMill. You can use a suitable tool to remove this residual material without having to machine the whole spigot again, i.e. avoiding unnecessary idle motions.

Material that remains as part of the finishing allowance is not residual material.

The residual material is calculated on the basis of the milling cutter used for clearing.

If you mill several spigots and want to avoid unnecessary tool changeover, clear all the spigots first and then remove the residual material. In this case, for removing the residual material, you also have to enter a value for the "Reference tool TR" parameter that appears when you press the "All parameters" softkey. Then program as follows:

- 1. Contour blank 1
- 2. Contour spigot 1
- 3. Clear spigot 1
- 4. Contour blank 2
- 5. Contour spigot 2
- 6. Clear spigot 2
- 7. Contour blank 1



- 9. Clear residual material spigot 1
- 10. Contour blank 2
- 11. Contour spigot 2
- 12. Clear residual material spigot 2

The "Residual material" function is a software option.



Press the "Cont. mill." and "Spigot Res. Mat." softkeys. \geq

Press the "All parameters" softkey if you want to enter additional \triangleright parameters.

	Parameters	Description	Unit
Ð			
	T, D, F, S, V See Sec. "Creating program blocks".		
	Machining	✓ Roughing	
	type		
	TR	Reference tool for residual material	
	D	Cutting edge of reference tool (1 or 2)	
	Z0	Reference point in Z direction (abs.)	mm
	Z1	Depth with reference to Z0 (abs. or inc.)	mm
	DXY	Maximum infeed in the XY plane	mm
		Plane infeed in %: Ratio of plane infeed (mm)	%
		to milling cutter diameter (mm)	
	DZ	Maximum depth infeed (Z direction)	mm
	UXY	Finishing allowance in plane	mm
	UZ	Finishing allowance in depth	mm
Retraction If more than one approach point is necessary, specify the retraction heigh		If more than one approach point is necessary, specify the retraction height to which	
	mode	the tool retracts between approach points.	
		To retraction plane	
		Z0 + safety clearance	
		If there are no spigots or other elements larger than Z0 in the machining area, "Z0 +	
		safety clearance" can be selected as the retraction mode.	



3.5.14 Finishing the contour spigot



10.04

If you programmed a finishing allowance for the base or edge of the spigot in spigot milling, you still have to finish the spigot.

Separate blocks must be programmed for finishing the base and/or for finishing the edge. In each case, the spigot will only be machined once.

You can program "Path milling" as an alternative to "Edge finishing". Optimization possibilities are also offered for the approach/retract strategy and the approach/retract mode. Then program as follows:

- 1. Contour blank
- 2. Contour spigot
- 3. Mill spigot (roughing)
- 4. Contour blank
- 5. Path milling (finishing)
- 6. Contour spigot
- 7. Path milling (finishing)



- > Press the "Cont. mill." and "Mill spigot" softkeys.
- > Select "Finish base" or "Finish edge" machining mode.

0	Parameters	Description	Unit
	T, D, F, S, V See Sec. "Creating program blocks".		
	Machining VVV Finishing the base		
	type	Finishing the edge	
	Z0	Reference point in Z direction (abs.)	mm
	Z1	Depth with reference to Z0 (abs. or inc.)	mm
	DXY	Maximum infeed in the XY plane (base finishing only)	mm
		Plane infeed in %: Ratio of plane infeed (mm)	%
		to milling cutter diameter (mm)	
	DZ	Maximum depth infeed (Z direction) – (edge finishing only)	mm
	UXY	Finishing allowance in plane	mm
	UZ	Finishing allowance in depth – (edge finishing only)	mm
	Retraction	If more than one approach point is necessary, specify the retraction height to which	
	mode	the tool retracts between approach points.	
		To retraction plane	
		Z0 + safety clearance	
		If there are no spigots or other elements larger than Z0 in the machining area, "Z0 +	
		safety clearance" can be selected as the retraction mode.	



3.5.15 Chamfering a contour spigot



If you have planned edge breaking, mill a chamfer after that.

Parameters	Description	Unit
T, D, F, S, V	See Sec. "Creating program blocks".	
Machining Chamfer		
type		
Z0	Reference point in Z direction (abs.)	mm
FS	Chamfer width; abs	mm
ZF	Insertion depth tool tip; abs or inc	mm

3.6 Linear or circular path motions

This function is intended for the implementation of very simple machining operations as path movements. More complex operations such as contours with chamfers, radii, approach strategies, tangential transitions, etc. should be implemented using the "Mill contour" and "Path milling" functions.
You must program a tool before you program simple lines or circles. A tool with spindle speed is selected by means of softkeys "Straight circle" and "Tool". You can only program rapid traverse for linear travel motions.

3.6.1 Straight



Radius compensation

Alternately you can implement the straight line with radius compensation. The radius compensation acts modally, which means you must deactivate the radius compensation again if you want to traverse without radius compensation. Where several straight line blocks with radius compensation are programmed sequentially, you may select radius compensation only in the first program block.

When executing the first path motion with radius compensation, the tool traverses without compensation at the start point and with compensation at the end point. This means that if a vertical path is programmed, the tool traverses an oblique path. The compensation is not applied over the entire traversing path until the second programmed path motion with radius compensation is executed. The reverse occurs when radius compensation is deactivated.



First path motion with radius compensation



First path motion with deselected radius compensation



To avoid deviation between the programmed and actually traversed path, you can program the first path motion with radius compensation or deselected radius compensation outside the workpiece. Programming without coordinate data is not possible.



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the

HELP

key

> Press the "Straight/Circle" and "Straight" softkeys.



Help display for a line

Parameters	Description	Unit
x	Coordinate of end point in X direction (abs. or inc.)	mm
Y Coordinate of end point in Y direction (abs. or inc.) Z Coordinate of end point in Z direction (abs. or inc.)		mm mm
RadiusInput defining which side of the contour the cutter travels in the programmedcompensationdirection:		
	Radius compensation, left of contour Image: Compensation and the compensation of the compensation and the compensation of the compensation and the compensation is retained as set Image: Compensation and the compensation and	



3.6.2 Circle with known center point



The tool travels along a circular path from its current position to the programmed circle end point. You must know the position of the circle center point. The control calculates the radius of the circle/arc on the basis of your interpolation parameter settings.

The circle can only be traversed at machining feedrate. You must program a tool before the circle can be traversed.

Press the "Straight/Circle" and "Circle center point" softkeys.



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Help display for circle with known center point

Parameters	Description		
Direction of The tool travels in the programmed direction from the circle starting point to its en			
rotation	point. You can program this direction as clockwise or counterclockwise.		
X X position circle end point (abs. or inc.)			
Y Y position circle end point (abs. or inc.)			
Distance between circle start and center point in X direction (inc.)		mm	
J Distance between circle start and center point in Y direction (inc.)			
Plane	The circle is traversed in the set plane with the relevant interpolation		
	parameters:		
XYIJ: XY plane with interpolation parameters I and J		mm	
	XZIK: XZ plane with interpolation parameters I and K	mm	
	YZJK: YZ plane with interpolation parameters J and K	mm	



3.6.3 Circle with known radius



The tool traverses a circular path with the programmed radius from its current position to the programmed circle end point. The control system works out the circle center point. You do not need to program interpolation parameters.

The circle can only be traversed at machining feedrate.

> Press the "Straight/Circle" and "Circle radius" softkeys.



Help display for circle with known radius

Parameters	Description	Unit
Direction of	The tool travels in the programmed direction from the circle starting point to its end	
rotation point. You can program this direction as clockwise or counterclockwise.		
X X position circle end point (abs. or inc.)		mm
Y Y position circle end point (abs. or inc.)		mm
R	Radius of arc;	mm
	You can select the arc of your choice by entering a positive or a negative sign.	

10.04

3.6.4 Helix



With helical interpolation, a circular movement is overlaid in the plane with a linear motion in the tool axis, i.e. a spiral is created.



Call help display with the HELP key

>

> Press the "Straight Circle" and "Helix" softkeys.





3

Help display for a helix

Parameters	Description			
Direction of	The tool travels	he tool travels in the programmed direction from the circle starting point to its end		
rotation	point. You can program this direction as clockwise or counterclockwise.			
I, J	Incremental: Distance between helix start and center point		mm	
	X and Y direction			
	Absolute: Center point of helix in X and Y directions			
Р	Pitch of helix; The pitch is programmed in mm per revolution.			
Z	Z position of he	lix end point (abs. or inc.)	mm	



3.6.5 Polar coordinates

	Defining a pole	If a workpiece has been dimensioned from a central point (por radius and angles, you will find it helpful to program these as coordinates. You can program straight lines and circles as polar coordinate You must define the pole before you can program a line or cir polar coordinates. This pole acts as the reference point of the coordinate system. The angle for the first line or circle then needs to be program absolute coordinates. You can program the angles for any fur lines and circles as either absolute or incremental coordinates	le) with polar es. cle in polar med in ther s.
. ,	Strai. Polar Pole >	Press the "Straight/Circle", "Polar" and "Pole" softkeys.	
A	Parameters	Description	Unit

Parameters	Description	Unit
х	X position of the pole (abs. or inc.)	mm
Y	Y position of the pole (abs. or inc.)	mm

3.6.6 Straight polar



A straight line in the polar coordinate system is defined by a radius (L) and an angle (α). The angle refers to the X axis. The tool moves from its current position on a straight line to the

programmed end point at the machining feedrate or in rapid traverse.

The 1st line in polar coordinates entered after the pole must be programmed with an absolute angle. You can program any further lines or circles with incremental coordinates.

> Press the "Straight/Circle", "Polar" and "Straight polar" softkeys.



Polar

>



Help display for polar line with absolute and incremental angle

Parameters	Description	Unit
L	Radius from pole to end point of line	mm
α	Polar angle (abs. or inc., positive or negative)	Degr.
Radius compensation	Input defining which side of the contour the cutter travels in the programmed direction: Image: Radius compensation, left of contour Radius compensation off	
	Radius compensation, right of contour	



3.6.7 Circle polar



Parameters	Description	Unit
Direction of	The tool travels in the programmed direction from the circle starting point to its end	
rotation	point. You can program this direction as clockwise (right) or counterclockwise (left).	
α	Polar angle (abs. or inc., positive or negative)	Degr.



10.04

3.6.8 Programming examples for polar coordinates



Programming a pentagon

You want to machine the outside contour of a pentagon. Make sure that you enter the correct workpiece dimensions! Approach starting point in rapid traverse: X70, Y50, radius compensation off. Pole: X=50, Y=50

- 1. polar line: L=20, α = -72 **absolute**, radius compensation right
- to 5th polar line: L=20, α= -72 degrees incremental, radius compensation right



	N10 RAPID 🕱 X70 Y50 Z2
Ф	N15 X50 Y50
→	N20 №5 L20 α-72
→	N25 L20 α-72inc
→	N30 L20 α-72inc
→	N35 L20 α-72inc
→	N40 L20 α-72inc
→	N45 L20 α-72inc
END	N50 Program end

Programming graphics and extract from machining plan



Programming an arc of 225 degrees

You want to machine the outside contour of an arc.

Make sure that you enter the correct workpiece dimensions! Approach starting point in rapid traverse: X=80, Y=50, radius compensation right

Pole: X=60, Y=50

CW rotation, α = 135 degrees absolute



Programming graphics and extract from machining plan



3.7 Drilling

Programming holes and threads

In ShopMill, first program the technology blocks in the exact order in which they need to be performed, e.g.

- 1. **Centering**, with tool and input of spindle speed and machining feedrate
- 2. **Deep-hole drilling**, with tool and input of spindle speed and machining feedrate
- 3. **Tapping** with tool and input of spindle speed and machining feedrate

Once you have programmed the technologies, you need to enter the **position data**. ShopMill provides various positioning patterns (see Sec. "Positions").

This sequence, first technology block and then positioning block must be adhered to in drilling cycles.



3.7.1 Centering



The tool is moved in rapid traverse to the position to be centered, allowing for the retraction plane and safety clearance. The tool is inserted into the workpiece at programmed feedrate (F) until it reaches Z1 or until the surface diameter is the correct size. When the dwell time expires, the tool is retracted in rapid traverse to either the retraction plane or the safety clearance depending on the setting in parameter "Retraction position pattern". You will find parameter "Retraction position pattern" in the program header or under "Settings" in the "Miscellaneous" menu.



Press the "Drilling" and "Centering" softkeys.







Help display for centering at depth

Help display for centering on diameter

ê	Parameters	Description	Unit
	T, D, F, S, V	See Sec. "Programming the tool, offset value and spindle speed".	
	Diameter Tip	The tool is inserted into the workpiece until the diameter on the surface is the correct size. The angle for the center drill entered in the tool list is applied in this case. The drill is inserted into the workpiece until the programmed insertion depth is reached.	
	Ø	It is inserted into the workpiece until the diameter is correct.	mm
	Z1	It is inserted into the workpiece until it reaches Z1.	mm
	Z0	Height of workpiece; Z0 is specified in the position pattern ("Positioning" softkey).	mm
	DT	Dwell time for relief cut	s rev

3.7.2 Drilling and reaming



The tool is moved at rapid traverse to the programmed position, allowing for the retraction plane and safety clearance. It is then inserted into the workpiece at the feedrate programmed under F until it reaches depth Z1.

Drilling: If Z1 has been reached and the dwell time expired, the drill is retracted at rapid traverse either to the retraction plane or the safety clearance depending on the setting in parameter "Retraction position pattern". You will find parameter "Retraction position pattern" in the program header or under "Settings" in the "Miscellaneous" menu.

Reaming: If Z1 has been reached and the dwell time expired, the reamer is retracted at the programmed retraction feedrate to the safety clearance.



> Press the "Drilling" and "Drilling reaming" softkeys.







Help display for drilling

Help display for reaming

₿	Parameters	Description	Unit
	T, D, F, S, V	See Sec. "Programming the tool, offset value and spindle speed".	
	Shank	The drill is inserted into the workpiece until the drill shank reaches the value programmed for Z1. The insertion angle entered in the tool list is applied.	
	Тір	The drill is inserted into the workpiece until the drill tip reaches the value programmed for Z1 (does not apply in reaming).	
	Z1	Insertion depth for drill tip or drill shank.	mm
	Z0	Height of workpiece; Z0 is specified in the position pattern ("Positioning" softkey).	mm
	DT	Dwell time for relief cut.	s
			rev
	FB	Retraction feedrate (for reaming only)	





3.7.3 Deep-hole drilling



The tool is moved at rapid traverse to the programmed position, allowing for the retraction plane and safety clearance. It is then inserted into the workpiece at the programmed feedrate.



Stock removal

Press the "Drilling" and "Deep hole drilling" softkeys. ⋟

The tool drills at the programmed feedrate (F) until the 1st infeed depth is reached. On reaching the 1st depth, the tool is retracted from the workpiece at rapid traverse for stock removal and is then reinserted at the 1st infeed depth reduced by a clearance distance (V3). The tool then drills to the next infeed depth and is then retracted again, repeating this process until the final drill depth (Z1) is reached. On expiry of the dwell time (DT), the tool is retracted at rapid traverse to the safety clearance.

Chipbreaking The tool drills at the programmed feedrate (F) until the 1st infeed depth is reached. Once this depth is reached, the tool is retracted by a withdrawal distance (V2) for chip breaking and is then inserted again down to the next drilling depth. It repeats this process until the final drilling depth (Z1) is reached.

The specified amount can be defined either per machine data or in the parameter screenform. If the parameter is pre-assigned via machine data, it does not appear in the parameter screen.

Please refer to the machine manufacturer's instructions.



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Help display for deep hole drilling with chipbreaking

Help display for deep hole drilling with stock removal



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e	Parameters	Description	Unit
	T, D, F, S, V	See Sec. "Programming the tool, offset value and spindle speed".	
	Stock removal	The drill is retracted from the workpiece for stock removal.	
	Chipbreaking	The drill is retracted by the retraction amount V2 for chipbreaking.	
	Tip	The final drilling depth (Z1) refers to the drill tip	
	Shank	The final drilling depth (Z1) refers to the drill shank	
	Z1	Final drilling depth (inc.)	mm
	D	Max. infeed	mm
	DF	Percentage for each additional infeed	%
		DF=100: Amount of infeed remains constant	
		DF<100: Amount of infeed is reduced in direction of final drilling depth.	
		Example: Last infeed was 4mm; DF is 80	
		next infeed = 4 x 80% = 3.2 mm	
		next infeed = 3.2 x 80% = 2.56 mm etc.	
	V1	Minimum infeed	mm
		Parameter V1 is provided only if DF< 100 has been programmed.	
		If the infeed increment becomes minimal, a minimum infeed can be programmed in parameter "V1".	
		V1 < Amount of infeed: The tool is inserted by the infeed increment.	
		V1 < Amount of infeed: The tool is inserted by the infeed value programmed under V1.	
	V2	Specified amount or defined per machine data – for chip breaking only	mm
		Amount by which the drill is retracted for chipbreaking.	
		V2=0: The tool is not retracted but is left in place for one revolution.	
	V3	Limit distance – for unclamping only	mm
		Distance to last infeed depth that the drill approaches at rapid traverse after	
		unclamping.	
		Automatic: The limit distance is calculated by ShopMill.	
	DT	Dwell time for relief cut.	S
			rev



3.7.4 Boring



The tool is moved at rapid traverse to the programmed position, allowing for the retraction plane and safety clearance. It is then inserted into the workpiece at the feedrate programmed under F until it reaches the programmed depth (Z1). The spindle stops are a specific position there. "Lift off contour" or "Do not lift off contour" can be programmed on expiry of the dwell time.

With retraction, withdrawal distance D and the tool orientation angle α can either be defined via machine data or in the parameter screen. If both parameters are pre-assigned via machine data, they do not appear in the parameter screen.

Please refer to the machine manufacturer's instructions.



> Press the "Drilling" and "Boring" softkeys.





Help display for boring

Parameters	Description	Unit
T, D, F, S, V	See Sec. "Programming the tool, offset value and spindle speed".	
Lift off Do not lift off	The cutting edge is retracted from the bore edge and then moved back to the retraction plane. The cutting edge is not retracted, but traverses back to the safety clearance in rapid traverse.	
Z1	Depth with reference to Z0 (abs. or inc.)	mm
Z0	Height of workpiece; Z0 is specified in the position pattern ("Positioning" softkey).	mm



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DT	Dwell time for relief cut.	S
		rev
D	Withdrawal (retract) distance (or defined in machine data) - only for retraction	mm
α	Tool orientation angle (or defined via machine data) - only for retraction	Degr.

3.7.5 Tapping

	The "Tapping" function is used for tapping an inside thread.
	The spindle speed can be controlled with the spindle override during tapping. The feed override is inoperative during this process.
	You can select drilling in one cut, chipbreaking or retraction from the workpiece for stock removal.
	The tool is moved at rapid traverse to the programmed position, allowing for the retraction plane and safety clearance. With the spindle stationary, the tool moves at rapid traverse to the retraction plane and then to the safety clearance. Here the spindle begins to rotate and the spindle speed and feedrate are synchronized. The tool continues to move at rapid traverse towards the programmed position.
1 cut	 The tool drills at the programmed spindle speed S or cut rate V as far as the tapping depth Z1. The direction of rotation of the spindle reverses and the tool retracts to the safety clearance at the programmed spindle speed SR or cut rate VR.
Stock removal	 The tool drills at the programmed spindle speed S or feedrate V as far as the first infeed depth (maximum infeed depth D). The tool retracts from the workpiece to the safety clearance at spindle speed SR or cut rate VR for stock removal. Then the tool is inserted again as far as the 1st infeed depth at spindle speed S or feedrate V and drills to the next infeed depth. Steps 2 and 3 are repeated until the programmed final drilling depth Z1 is reached. The direction of rotation of the spindle reverses and the tool retracts to the safety clearance at spindle speed SR or cut rate VR.

1. The tool drills at the programmed spindle speed S or feedrate V as far as the first infeed depth (maximum infeed depth D).

- 2. The tool retracts by the retraction amount V2 for chipbreaking.
- 3. The tool then drills to the next infeed depth at spindle speed S or feedrate V.
- 4. Steps 2 and 3 are repeated until the programmed final drilling depth Z1 is reached.
- The direction of rotation of the spindle reverses and the tool retracts to the safety clearance at spindle speed SR or cut rate VR.

For tapping with an analog spindle, a floating tapholder is required. This can only be used to dill in one cut.

The machine manufacturer may have made specific settings for tapping in a machine data code.

Please refer to the machine manufacturer's instructions.

> Press the "Drilling", "Boring", and "Tapping" softkeys.

Help display for tapping

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Parameters	Description	Unit
T, D, S, V	See Sec. "Programming the tool, offset value and spindle speed".	
Р	Pitch	mm/rev
	The pitch is determined by the tool used.	in/rev
	MODULUS: Used with endless screws, for example, which extend into a gear wheel.	MODULE
	Turns/ ": Used with pipe threads, for example. For values entered in turns/", enter the integer in front of the decimal point in the first	Turns/ "
	parameter field and the figures after the decimal point as a fraction in the second and third field.	
	For example, 13.5 turns/" is entered as follows: P 13 1/ 2 Thrds/"	









SR	Spindle speed for retraction (not for tapping with a floating tapholder)	rev/min
VR	Cutting rate for retraction (alternative to SR) (not for tapping with a floating tapholder)	m/min
1 cut	The thread is drilled in one cut without stopping.	
Stock removal	The drill is retracted from the workpiece for stock removal (not for tapping with a	
	floating tapholder)	
Chipbreaking	The drill is retracted by the retraction amount V2 for chipbreaking (not for tapping	
	with a floating tapholder)	
Z1	Tapping depth with reference to Z0 (abs. or inc.)	mm
	Z0 is specified in the position pattern ("Positioning" softkey).	
D	Maximum infeed (for stock removal or chipbreaking only)	mm
V2	Retraction amount (for chipbreaking only)	mm
	Amount by which the drill is retracted for chipbreaking.	
	V2=automatic: The tool is retracted by one revolution.	

3.7.6 Thread milling

You can use a form cutter to machine any type of right-hand or lefthand thread.

Threads can be machined as right-hand or left-hand threads and from top to bottom or vice versa.

For metric threads (thread pitch P in mm/rev) ShopMill assigns a value calculated from the thread pitch to the Thread depth K parameter. You can change this value. The default selection must be activated via a machine data code.

Please refer to the machine manufacturer's instructions.

> Press the "Drilling", "Thread" and "Cut thread" softkeys.



Internal thread

Sequence:

- Position on thread center point on retraction plane in rapid traverse
- Infeed at rapid traverse to reference plane shifted forward by amount corresponding to safety clearance
- Approach along an approach circle calculated in the control at programmed feedrate
- Approach motion to thread diameter on circular path
- Cut thread along a spiral path in clockwise or counterclockwise direction (depending on whether it is left-hand or right-hand thread)





- Exit motion along a circular path in the same rotational direction at programmed feedrate
- Retract to thread center point and then to retraction plane in rapid traverse

External thread

Sequence:

- Position on starting point in retraction plane at rapid traverse
- Infeed at rapid traverse to reference plane shifted forward by amount corresponding to safety clearance
- Approach along an approach circle calculated in the control at programmed feedrate
- Approach motion to thread diameter on circular path
- Cut thread along a spiral path in clockwise or counterclockwise direction (depending on whether it is left-hand or right-hand thread)
- Exit motion along a circular path in opposite rotational direction at programmed feedrate
- Retract to retraction plane at rapid traverse

Call help display with







Help displays for thread cutting



3

Parameters	Description	Unit
Machining type	Roughing	
	I hread cutting up to programmed finishing allowance (U)	
D 1		
Direction	Depending on the rotational direction of the spindle, a change in direction also	
	changes the machining direction (climb/conventional).	
	20 to 21: Machining starts at workpiece surface 20.	
	21 to 20: The machining starts at thread depth, e.g. for blind hole tapping	
Internal thread	An inside thread is cut.	
External thread	An outside thread is cut.	
Left-hand	A left-hand thread is cut.	
thread		
Right-hand	A right-hand thread is cut.	
thread		
NT	Number of teeth in a milling insert.	
	Single or multiple toothed milling inserts can be used. The cutting teeth are entered	
	in parameter NT. The motions required are executed by the cycle internally, so that	
	the tip of the bottom tooth on the milling insert corresponds to the programmed end	
	position when the thread end position is reached. Depending on the cutting edge	
	geometry of the milling insert, the retraction path must be taken into account at the	
	base of the workpiece.	
Z1	Thread length	mm
Z0	Height of workpiece; Z0 is specified in the position pattern ("Positioning" softkey).	mm
Ø	Nominal thread diameter, example: Nominal diameter of M12 = 12mm	mm
Р	Pitch	mm/rev
	If the cutter has several teeth, the thread pitch is determined by the tool.	inch/rev
	For a thread pitch entered in turns/", enter the integer in front of the decimal point in	MODULE
	the first parameter field and the figures after the decimal point as a fraction in the	Turns/ "
	second and third fields.	
	For example, 13.5 turns/" is entered as follows: P 13 1/ 2 Thrds/"	
к	Thread depth	mm
DXY	Infeed per cut	mm
	Alternately, you can specify the plane infeed as a %, as a ratio> plane infeed (mm)	%
	to milling cutter diameter (mm).	
U	Final machining allowance	mm
α0	Start angle	Degr.





Programming example for Cut cir thread cutting The m

Cut circular pocket in a solid blank and cut a thread. The milling tool cannot cut across center. The circular pocket will therefore have to be predrilled with a Ø22mm drill. The milling tool can then be inserted centrally.

Using position patterns, the positions of the above-mentioned cycles can be programmed (see Sec. "Using position patterns in milling").



Workshop drawing of circular pocket with thread

N10 ך 💏	CENTERING		T=center F250/min S900rev. ø5
🖏 - N15	DRILL		T=drill22 F80/min S400rev. Z1=42inc
💭 - N20	Circ. pocket	V	T=12 F500∕min S600rev. Z1=40inc ø50
^{,∰} ∦ ∦ − N25	Inside thread	V	T=thread56 F100/min S400rev. Z1=40 ø56
√ - №30	001: Positions		Z0=0 X0=60 Y0=50

Extract from machining plan; cut a circular pocket with thread



3.7.7 Drill and thread milling

that you can use the same tool for drilling and thread milling, a change of tool is superfluous. The thread can be machined as a right- or left-hand thread.
 Sequence: The tool travels at rapid traverse to the safety distance. If pre-drilling is required, the tool travels at a reduced drilling feedrate to the pre-drilling depth defined in a machine data. Please refer to the machine manufacturer's instructions.
 The tool drills to the first drilling depth D with drilling feedrate F1. If the final drilling depth is not reached, the tool will travel back to the workpiece surface in rapid traverse for stock removal. Then the tool will travel at rapid traverse to a position 1mm above the drilling depth previously achieved - allowing it to continue drilling at drill feedrate F1 at the next infeed.
 If another feedrate FR is required for through-boring, the residual drilling depth ZR is drilled with this feedrate. If required, the tool travels back to the workpiece surface for stock
 removal before thread milling at rapid traverse. The tool travels directly to the starting position for thread milling. The thread milling is carried out (climb milling, conventional milling or conventional milling + climb milling) with milling feedrate F2. The

drate F2. The thread milling acceleration path and deceleration path is traversed in a semicircle with concurrent infeed in the tool axis.

You can use a drill and thread milling cutter to manufacture an internal thread with a specific depth and pitch in one operation. This means

Press the "Drilling", "Thread" and "Cut thread" softkeys. \triangleright



Thread >



10.04





Displays for drill and thread milling cutter

A	Parameters	Description	Unit
	T, D, S, V	See Sec. "Programming the tool, offset value and spindle speed".	
	F1	Drilling feed	mm/min mm/rev
	Z1	Drilling depth	mm
	D	Maximum infeed	mm
	DF	Percentage for each additional infeed DF=100: Amount of infeed remains constant DF<100: Amount of infeed is reduced in direction of final drilling depth Z1. Example: Last infeed 4 mm; DF 80% next infeed = 4 x 80% = 3.2 mm infeed after next = 3.2 x 80% = 2.56 mm etc.	%
	V1	Minimum infeed Parameter V1 is provided only if DF<100 has been programmed. If the infeed increment becomes minimal, a minimum infeed can be programmed in parameter "V1". V1 < Amount of infeed: The tool is inserted by the infeed increment. V1 < Amount of infeed: The tool is inserted by the infeed value programmed under V1.	mm

Pre-drilling	When drilling, start initially with a reduced feedrate.	
	The reduced drilling feedrate results as follows:	
	Drilling feedrate F1 < 0.15mm/rev: Pre-drilling feedrate = 30% of F1	
	Pre-drilling feedrate F1 \ge 0.15mm/rev: Pre-drilling feedrate = 0.1mm/rev	
Through-drilling	When drilling the residual drilling depth ZR drill with feedrate FR.	
ZR	Residual drilling depth (for through-drilling only)	mm
FR	Feedrate through-drilling (for through-drilling only)	mm/min
		mm/rev
Stock removal	Return to workpiece surface for stock removal before thread milling.	
Thread	Right-hand thread	
	Left-hand thread	
F2	Milling feed	mm/min
		mm/tooth
Р	Pitch	in/rev
	For a thread pitch entered in turns/", enter the integer in front of the decimal point in	Turns / "
	the first parameter field and the figures after the decimal point as a fraction in the	
	second and third fields.	
	For example, 13.5 turns/" is entered as follows: P 13 1/ 2 Thrds/"	
Z2	Retraction before thread milling	mm
	Z2 is for defining the thread depth in the direction of the tool axis. Z2 is relative to the	
	tool tip.	
Ø	Nominal thread diameter	mm
Machining	Climb milling: Mill thread in one cycle.	
direction	Conventional milling: Mill thread in one cycle.	
	Conventional milling + climb milling: Mill thread in two cycles: rough cutting is	
	performed by conventional milling with defined allowances, then finish cutting is	
	performed by climb milling with milling feedrate FS.	
FS	Milling feed finish cutting (for conventional milling + climb milling only)	mm/min
		mm/tooth
L		1

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3.7.8 Positioning on freely programmable positions and position patterns

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Cylinder surface transformation	When working with the cylinder surface transformation, please note that the A axis or B axis is not supported in all cases. Programming of any position in the XYA plane is not possible while cylinder surface transformation is active. A work offset in the rotary axis A or B is effective even while cylinder surface transformation is active.
Select with softkey	Positions

3.7.9 Freely programmable positions



Drill-holes point toward the center





Y axis is not central above the cylinder (Δ Y)

XYA plane •

You program in XYA if the Y axis is required to move during machining. A value can be specified for each position.

In addition to the possibilities of XA, the following is also possible, for example.



Y axis is traversed (Y0, Y1)



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Select with softkey











Help display for "Freely programmable positions, rectangular"

Help display for "Freely programmable positions, polar"

Parameters	Description XY	Unit
	(without A/ or B axis support)	
Rectangular/ polar	Programming with rectangular or polar dimensions.	
Z0	Height of workpiece (abs. or inc.)	mm
X0	1. position of the hole in X (abs. or inc.)	mm
Y0	1. position of the hole in Y (abs. or inc.)	mm
Rectangular:		
X1 X8	Other positions in the X axis (abs. or inc.)	mm
Y1 Y8	Other positions in the Y axis (abs. or inc.)	mm
	If you want to program further positions, store the ones you have already programmed and then open the parameter input form again by pressing softkey "Any positions".	
Polar:		
L1 L7	Position distance (abs.)	mm
α1 α7	Angle of rotation of line in relation to the X axis.Positive angle:Line is rotated counterclockwise.Negative angle:Line is rotated clockwise.	Degr.
	If you want to program further positions, store the ones you have already programmed and then open the parameter input form again by pressing softkey "Any positions".	

10.04

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	Z0
	XA:
	X0
	A0

Parameters	Description	Unit
	(with A/ or B axis support)	
Z0	Height of workpiece (abs. or inc.)	mm
XA:	(B can be used everywhere instead of A; Y can be used instead of X)	
X0	1. position of the hole in X (abs. or inc.)	mm
A0	1. position of the hole in A (abs.)	Degr.
X1 X8	Other positions in the X axis (abs. or inc.)	mm
A1 A8	Other positions in the A axis (abs. or inc.)	Degr.
	If you want to program further positions, store the ones you have already	
	programmed and then open the parameter input form again by pressing softkey "Any	
	positions".	
XYA:	(B can be used everywhere instead of A)	
X0	1. position of the hole in X (abs. or inc.)	mm
Y0	1. position of the hole in Y (abs. or inc.)	mm
A0	1. position of the hole in A (abs.)	Degr.
X1 X5	Other positions in the X axis (abs. or inc.)	mm
Y1 Y5	Other positions in the Y axis (abs. or inc.)	mm
A1 A5	Other positions in the A axis (abs. or inc.)	Degr.
	If you want to program further positions, store the ones you have already	
	programmed and then open the parameter input form again by pressing softkey "Any positions".	



3.7.10 Line position pattern



Parameters	Description	Unit
Z0	Height of workpiece (abs. or inc.)	mm
	This position must be programmed absolutely in the first call.	
X0	Reference point (first position)	mm
	This position must be programmed absolutely in the first call.	
Y0	Reference point (first position)	mm
	This position must be programmed absolutely in the first call.	
α0	Angle of rotation of line in relation to the X axis.	Degr.
	Positive angle: Line is rotated counterclockwise.	
	Negative angle: Line is rotated clockwise.	
L	Position spacing.	mm
N	Number of positions.	





3.7.11 Matrix position pattern



●	Parameters	Description	Unit
	Z0	Height of workpiece (abs. or inc.)	mm
		This position must be programmed absolutely in the first call.	
	X0	Reference point (first position)	mm
		This position must be programmed absolutely in the first call.	
	Y0	Reference point (first position)	mm
		This position must be programmed absolutely in the first call.	
	α0	Angle of rotation of matrix.	Degr.
		Positive angle: Matrix is rotated counterclockwise.	
		Negative angle: Matrix is rotated clockwise.	
	αX	Shear angle of matrix relative to X axis.	Degr.
		Positive angle: Matrix shears in CCW direction.	
		Negative angle: Matrix shears in CW direction.	
	αY	Angle of rotation of matrix relative to Y axis	Degr.
		Positive angle: Matrix is rotated counterclockwise.	
		Negative angle: Matrix is rotated clockwise.	
	L1	Position spacing in X direction	mm
	L2	Position spacing in Y direction	
	N1	Number of positions in X direction	
	N2	Number of columns in Y direction	



3.7.12 Box position pattern



	Parameters	Description	Unit
	Z0	Height of workpiece (abs. or inc.)	mm
		This position must be programmed absolutely in the first call.	
	X0	Reference point (first position)	mm
		This position must be programmed absolutely in the first call.	
	Y0	Reference point (first position)	mm
		This position must be programmed absolutely in the first call.	
	α0	Angle of rotation of box	Degr.
		Positive angle: Box is rotated counterclockwise.	
		Negative angle: Box is rotated clockwise.	
	αX	Shear angle of box relative to X axis.	Degr.
		Positive angle: Box shears in CCW direction.	
		Negative angle: Box shears in CW direction.	
	αY	Shear angle of box relative to Y axis.	Degr.
		Positive angle: Box shears in CCW direction.	
		Negative angle: Box is rotated clockwise.	
	L1	Position spacing in X direction	mm
	L2	Position spacing in Y direction	
	N1	Number of positions in X direction	
	N2	Number of columns in Y direction	

You can use this function to program any number of positions spaced at an equal distance along on a box. The spacing may be different on

If you want to program a rhombus-shaped box, enter the angle αX or



Position the cursor in the "Line/matrix/box" field. With the "Alternat." softkey you can select the "Box" position pattern.

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3.7.13 Full circle position pattern

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This function can be used to program drill holes on a circle with a defined radius. The basic angle of rotation (α 0) for the 1st position is relative to the X axis. The control calculates the angle of the next hole position as a function of the total number of holes. The angle it calculates is identical for all positions. If the A or B axis is used, the angle refers to a set reference point

(A0).

You can use the XA selection if use of the rotary axis on the machine is required.

The Y axis is not traversed, i.e. the Y axis must first be positioned centrally over the cylinder.

The tool can approach the next position along a linear or circular path.



Approaching positions on a linear or circular path

Select with softkey



If you position the cursor on the "Full/pitch circle" field, you can toggle between the two options using the "Alternat." softkey.





Help display for "Full circle of holes"



Parameters	Description XY	Unit
	(without A/B axis)	
Z0	Height of workpiece (abs. or inc.)	mm
X0	X position of full circle center point (abs. or inc.)	mm
Y0	Y position of full circle center point (abs. or inc.)	mm
α0	Basic angle of rotation; angle of 1st hole in relation to X axis. Positive angle: Full circle is rotated counterclockwise. Negative angle: Full circle is rotated in clockwise direction.	Degr.
R	Radius of full circle	mm
Ν	Number of positions on full circle	
FP	Feed for positioning on a circular path.	mm/min
Positioning	Linear: Next position is approached linearly at rapid traverse. Circular: Next position is approached at the programmed feedrate (FP) along a circular path.	



Parameters	Description XA	
	(with A/B axis)	
Z0	Height of workpiece surface (abs. or inc.)	mm
X0	Reference position (abs. or inc.)	
A0	Start angle (abs.)	Degr.
	Angle of 1st hole with reference to X axis.	
	Positive angle: Full circle is rotated counterclockwise.	
	Negative angle: Full circle is rotated in clockwise direction.	
Ν	Number of positions on full circle	



3.7.14 Pitch circle position pattern

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A	Parameters	Description normal/XY	Unit
Ð		(without A/B axis)	
	Z0	Height of workpiece (abs. or inc.)	mm
	X0	X position of pitch circle center point (abs. or inc.)	mm
	Y0	Y position of pitch circle center point (abs. or inc.)	mm
	α0	Basic angle of rotation; angle of 1st position in relation to X axis.	Degr.
	α1	Advance angle; after the first hole has been drilled, all further positions are advanced by this angle.	Degr.
		Positive angle: Further positions are rotated counterclockwise.	
		Negative angle: Further positions are rotated clockwise.	
	R	Radius of pitch circle	mm
	N	Number of positions (holes) on the pitch circle	
	FP	Feed for positioning on a circular path.	mm/min
	Positioning	Linear: Next position is approached linearly at rapid traverse.	
		Circular: Next position is approached at the programmed feedrate (FP) along a circular path	

	Parameters	Description XA	Unit
₿		(with A/B axis)	
	Z0	Height of workpiece surface (abs. or inc.)	mm
	X0	Reference position (abs. or inc.)	mm
	A0	Start angle (abs.) Angle of 1st position relative to X axis.	Degr.
	A1	Advance angle (abs.) after the first hole has been drilled, all further positions are advanced by this angle. Positive angle: Further positions are rotated counterclockwise. Negative angle: Further positions are rotated clockwise.	Degr.
	Ν	Number of positions on pitch circle	



The diagram shows the skipped positions dotted. The current position is highlighted by a circle.

The number of the current position is displayed along with its status

The "Skip positions" window opens on top of the input form of the

Select the required position pattern and press the "Skip pos."

- Enter the number of the point you want to skip in the "Position" field (in accordance with the machining sequence).
- OR -

 \geq

softkey.

position pattern.

Press the "Position +" softkey to select the next position (in the machining sequence).

- OR -

- Press the "Position -" softkey to select the previous position (opposite direction to the machining sequence).
- > Press the "Alternat." softkey to include or skip the current position.

3.7.15 Including and skipping positions

•	Position	pattern	line

- Position pattern matrix
- Position pattern box
- Position pattern rhombus
- Position pattern full circle (XY only)
- Position pattern pitch circle (XY only)

The suppressed positions are skipped during machining.

You can skip any positions in the following position patterns:







Including or skipping all positions at once		
Skip all	\triangleright	Press the "Skip all" softkey to skip all positions.
Include all	~	Press the "Include all" softkey to include all positions again.

3.7.16 Obstacle

	Function
	If there is an obstacle between 2 position patterns, it can be crossed. The height of the obstacle can be programmed absolutely or incrementally.
	If all positions in the 1st pattern have been machined, the tool axis travels in rapid traverse to a height corresponding to the obstacle height + safety clearance. The new position is approached in rapid traverse at this height. The tool axis then approaches a position corresponding to Z0 of the position pattern + safety clearance.
Select with softkey	Positions > Obstacle
Note	Obstacles are registered only if they lie between 2 position patterns. If the tool change point and the programmed retraction plane are positioned below the obstacle, the tool travels to the retraction plane height and on to the new position without taking the obstacle into account. The obstacle must not be higher than the retraction plane.





\$

Programming example

Drilling 4 positions with an obstacle in-between. The holes are first centered and then drilled. When you have programmed the first two positions at X=15, you need to program the obstacle. The remaining positions are then programmed at X=100.



Workshop drawing

N10 ۲	CENTERING	T=4 F250∕min S900rev. ø3
🖏 - N15	DRILL	T=DRILL10 F80/min S600rev. Z1=22ink
√ - N20	001: Positions	Z0=0 X0=15 Y0=8 X1=15 Y1=38
- N25	Obstacle	Z20
√	002: Positions	Z0=0 X0=100 Y0=8 X1=100 Y1=38

Extract from machining plan for "Obstacle" programming example



3.7.17 Repeating positions

Function

If you want the tool to re-approach positions that you have already programmed, the "Repeat positions" function is a quick and easy solution.

You must specify the number of the position pattern. This is a number assigned automatically by ShopMill. You will find it inserted after the block number in the machining plan.



Extract from machining plan, position pattern number=001

Select with softkey

Drilling Repeat positions >

After you have entered the position pattern number, e.g. 1, press the "Accept" softkey. The position pattern you have selected is then approached again.

S .	N15	Longit. slot 🛛 🖓	T=12 F0.2/Z S600rev.
≎⊐	N20	001: Hole full cir.	Z0=0 X0=50 Y0=50 R32 N6
ך 🖏	N25	Centering	T=3 F200/min S900rev. Z1=1inc
79 1 77 -	NЗØ	DRILL	T=2 F400/min S500rev. Z1=15inc
<u>−û</u> _	N35	Repeat pos.	001: Hole full cir.

Extract from machining plan; repeat positions in block no. 60





3.7.18 Programming examples for drilling



Drilling at different heights Machining task: You have already cut a recess in a workpiece. You now want to machine blind and through holes of Ø 12 mm on this workpiece with different machining planes.

Programming:

Center the 4 holes

Deep drill the blind holes with stock removal

Deep drill the through holes with chipbreaking



Workshop drawing

N10 ۲ 🐜	CENTERING	T=center F250/min S900rev. Z1=2ink
N - N15	001: Positions	Z0=0 X0=25 Y0=12 X1=25 Y1=30
√ [_] N20	002: Positions	Z0=-36 X0=60 Y0=12 X1=60 Y1=30
פ 8 8 ך №25	Deep hole dr.	T=DRILL12 F80/min S600rev. Z1=14ink
=∜ N30	Repeat pos.	001: Positions
8 <mark>8 ך №</mark>	Deep hole dr.	T=DRILL12 F80∕min S600rev. Z1=-52
=⊕ <mark>_</mark> N40	Repeat pos.	002: Positions

Extract from machining plan



Drilling with a counterbore

You want to machine through holes with screw head recesses around a pitch circle on a workpiece.

When you program the counterbore, you must select offset value D2 (see Sec. "Creating a tool offset block for tool edge $\frac{1}{2}$ ").



Workshop drawing

7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	N5	Centering	T=center F200/min S600rev. ø3
18 77+77: -	N10	DRILL	T=drill9 F100/min S400rev. Z1=31inc
18 77+77: -	N15	DRILL	T=spot_facer F60/min S400rev. Z1=8inc
۵-	N2Ø	001: Hole pitch cir	Z0=0 X0=50 Y0=40 R30 N6

Extract from machining plan



3.8.1 Face milling

•	You can use this cycle to face mill any workpiece. A rectangular surface is always machined. The rectangle results from corner points 1 and 2 that are pre-assigned with the values of the blank part dimensions from the program header. Workpieces with and without limits can be face-milled. To machine a work piece with four limits select the pocket cycles.
	 The cycle makes a distinction between roughing and finishing: Roughing: Several material removal operations on surface Tool turns above the workpiece edge Finishing: First material removal operation on surface Tool turns at safety distance in the X/Y plane Retraction of mill Depth infeed always takes place outside the workpiece.
6	For a workpiece with edge breaking, select the rectangular spigot cycle. In face milling, the effective tool diameter for a tool of type "Milling cutter" is stored in machine data.
	Please refer to the machine manufacturer's instructions.
Start point	For vertical machining the start point is always above or below. For horizontal machining it is right or left. Machining is performed from outside to inside, if possible. The starting point is marked in the help display.
Select with softkey	Face ing milling









The same finishing allowance must be entered for both roughing and finishing. The finishing allowance is used to position the tool for retraction.

Programming example Face milling

You want to cut to a depth of 10mm on a workpiece surface. 8mm must be removed in a rough cut and 2mm in a finish cut. The cutter diameter is 40mm. Blank dimensions: X0=0, Y0=0, Z0=10, X1=100 abs., Y1=50 abs., Z1=0 abs



Face milling: Roughing and finishing

Fac	ce mi	illing				Face	e milling	9		
Т	2			D1		т	2			D
F		600.000	nn/nir	n		F	300.	000 m	n∕nir	n i
S		300	грм			S		350 r	pm	
Mac	chini	ing:	∇			Macl	hining:	7	$\overline{\mathbf{N}}$	
XØ		0.000	abs			XØ	0.	000 a	bs	
YØ.		0.000	abs			YØ	0.	000 a	bs	
ZØ		10.000	abs			ZØ	10.	000 a	bs	
X1		100.000	abs			X1	100.	000 a	bs	
Y1		50.000	abs			Y1	50.	000 a	bs	
Z1		0.000	abs			Z1	0.	000 a	bs	
DX٩	Y	18.000				DXY	18.	000		
DZ		5.000								
UΖ		2.000				UZ	2.	ини		
Fac	e mill	ing, roughir	ng			Face	e milling, fir	nishing	1	
中	N10	Face mill	ling	V	T=2	F600/min	5300rev.	X0=0	Y0=0	ZØ=1
中	N15	Face mill	ling	$\overline{\nabla}$	T=2	F300/min	5350rev.	X0=0	Y0=0	ZØ=1

Extract from machining plan; Roughing and finishing in face milling



3.8.2 Rectangular pocket

		If you want to mill a rectangular pocket, use the "Rectangular pocket" function.
=?		 The following machining methods are available: Mill rectangular pocket from solid material. Predrill rectangular pocket in the center first if, for example, the milling cutter does not cut across center (program the drilling, rectangular pocket and position program blocks one after another). Machine pre-machined rectangular pocket (see "Machining" parameter).
		Depending on the dimensions of the rectangular pocket in the workpiece drawing, you can select a corresponding reference point for the rectangular pocket.
	Approach/retraction	 The tool approaches the center point of the pocket at rapid traverse at the height of the retraction plane and adjusts to the safety clearance. The tool is inserted into the material according to the chosen strategy. The pocket is always machined with the chosen machining type from inside out. The tool moves back to the safety clearance at rapid traverse.
	Machining type	 You can select the machining mode for milling the rectangular pocket as follows: Roughing During roughing, the individual planes of the pocket are machined one after the other from center point until depth Z1 is reached. Finishing In "Finishing" mode, the edge is always machined first. The pocket edge is approached on the quadrant which joins the corner radius. In the last infeed, the base is finished from the center out. Edge finishing Edge finishing is performed in the same way as finishing, except that the last infeed (finish base) is omitted. Chamfer Chamfer Chamfering involves edge breaking at the upper edge of the pocket.
	Select with softkey	Mill- ing Pocket > Rectangular pocket









Help display for milling a rectangular pocket

If you want to mill a chamfer and the corner radius was R = 0 during finishing, you must specify the radius of the finishing milling tool in parameter R during chamfering.

Parameters	Description	Unit
4		
T, F, V	See Sec. "Programming the tool, offset value and spindle speed".	
Position of	5 different positions for the reference point can be selected:	
reference point	Pocket center	
	Lower left-hand corner	
	Lower right-hand corner	
	Upper left-hand corner	
	Upper right-hand corner	
	The reference point (highlighted in yellow) is displayed in the Help screen.	
Machining type	Roughing	
	Finishing	
	Finishing edge	
	Chamfer	
Single pos.	A rectangular pocket is machined at the programmed position (X0, Y0, Z0).	
Pos. pattern	Several rectangular pockets are machined in a position pattern (e.g. full circle, pitch	
	circle, matrix, etc.).	
	The positions refer to the reference point:	
X0	Position in X direction (single position only), abs. or inc.	mm
YO	Position in Y direction (single position only), abs. or inc.	mm
Z0	Workpiece height (single position only), abs. or inc.	mm
W	Pocket width	mm
L	Pocket length	mm
R	Radius at pocket corners	mm
α0	Angle of rotation of pocket in relation to X axis.	Degr.
Z1	Depth of pocket in relation to Z0 (abs. or inc.) (not for chamfer)	mm
DXY	Max. infeed in plane (XY direction)	mm
	Alternatively, you can specify the plane infeed as a %, as a ratio $ ightarrow$ plane infeed	%
	(mm) to milling cutter diameter (mm). (not for chamfer)	

3

DZ	Max. depth infeed (Z direction) (not for chamfer)	mm
UXY	Finishing allowance in plane (pocket edge) (not for chamfer)	mm
UZ	Finishing allowance in depth (pocket base) (not for chamfer)	mm
Insertion	You can select one of several insertion strategies: Helical: Insertion along helical path The cutter center point traverses along the helical path determined by the radius and depth per revolution. If the depth for one infeed has been reached, a full circle motion is associated to aligning to the institute of the section of the	
	Oscillation: Insertion with oscillation along center axis of pocket The cutter center point oscillates along a linear path until it reaches the depth infeed. When the depth has been reached, the path is traversed again without depth infeed in order to remove the slope caused by insertion.	
	Center: Insert vertically in center of pocket The tool executes the calculated depth infeed vertically in the center of the pocket. Note: This setting can be used only if the cutter can cut across center or if the pocket has been predrilled.	
EP	Max. insertion gradient (only for helical insertion) The gradient of the helix may be smaller in some geometric conditions.	mm/rev
ER	Insertion radius (only for helical insertion) The radius must not be larger than the cutter radius, otherwise material will remain. Also make sure the pocket is not violated.	mm
EW	Insertion angle (for insertion with oscillation only)	Degr.
FZ	Depth infeed rate (for insertion in center only)	mm/min mm/tooth
Remove stock	Complete mach.: The pocket must be milled from a solid workpiece (e.g. casting). Remachining: A small pocket or hole has already been machined in the workpiece. This needs to be enlarged in one or several axes. You must program parameters AZ, W1 and L1 for this purpose.	
FS	Chamfer width (for chamfer only), inc.	mm
ZFS	Insertion depth tool tip (for chamfer only), abs. or inc.	mm
AZ	Depth of premachined pocket (for remachining only)	mm
W1	Width of premachined pocket (for remachining only)	mm
L1	Length of premachined pocket (for remachining only)	mm







Programming example

You wish to cut a rectangular pocket, starting with a rough cut operation and followed by a finish cut. Since the cutting tool you are using cannot cut across center, the workpiece needs to be predrilled first with a drill of \emptyset 20 mm.





Т	CUTTER3		D1
F	300.000	mm/mir	n i
S	500	rpm	
	Center		
Mact	nining:	∇	
	Position pat	ttern	
ω	50.000		
₩ L	50.000 80.000		
₩ L R	50.000 80.000 1.000		
₩ L R αØ	50.000 80.000 1.000 0.000	o	
₩ L R αØ Z1	50.000 80.000 1.000 0.000 26.000	o inc	
₩ L R αØ Z1 DXY	50.000 80.000 1.000 0.000 26.000 3.000	o inc	
₩ L R αØ Z1 DXY DZ	50.000 80.000 1.000 0.000 26.000 3.000 3.000	o inc	
W L R Z1 DXY DZ UXY	50.000 80.000 1.000 0.000 26.000 3.000 3.000 1.000	o inc MM	
W L R Z1 DXY DZ UXY UXY UZ	50.000 80.000 1.000 26.000 3.000 3.000 1.000 1.000	o inc mm	
₩ L R Z1 DXY DZ UXY UZ App	50.000 80.000 1.000 26.000 3.000 3.000 1.000 1.000 1.000	o inc mm centr	ic

Rect	tangular poc	:ket
Т	CUTTER3	D1
F	300.000	mm/min
S	500	rpm
	Center	
Mach	nining:	
	Position pa	ttern
	FO 000	
Ψ	50.000	
L	80.000	
R	1.000	
αØ	0.000	0
Z1	26.000	inc
DXY	3.000	
DZ	3.000	
UXY	1.000	mm
UZ	1.000	
Appr	roach:	centric
FZ	0.100	mm/tooth

Rough cut a rectangular pocket

Finishing a rectangular pocket

ך <i>אוו</i> ר	NS	Centering		T=center F250/min S900rev. ø5
79 1 777 -	N1Ø	DRILL		T=drill22 F80/min S400rev. Z1=26inc
<u> </u>	N15	Right pocket	▽	T=milling3 F300/min S500rev.
<u> </u>	N20	Right pocket		T=milling2 F200/min S600rev.
N^{\perp}	N25	001: Positions		Z0=0 X0=60 Y0=45

Extract from machining plan; predrilling and milling a rectangular pocket



3.8.3 Circular pocket

		Use the "Circular pocket" function if you want to mill any kind of circular pocket.
=?		 The following machining methods are available: Mill circular pocket from solid material. Predrill circular pocket in the center first if, for example, the milling cutter does not cut across center (program the drilling, circular pocket and position program blocks one after another). Machine pre-machined circular pocket (see "Machining" parameter).
	Approach/retraction	 The tool approaches the center point of the pocket at rapid traverse at the height of the retraction plane and adjusts to the safety clearance. The tool is inserted into the material according to the chosen strategy. The pocket is always machined with the chosen machining type from inside out. The tool moves back to the safety clearance at rapid traverse.
	Machining type	 You can select the machining mode for milling the circular pocket as follows: Roughing During roughing, the individual planes of the pocket are machined one after the other from center point until depth Z1 is reached. Finishing In "Finishing" mode, the edge is always machined first. The pocket edge is approached on the quadrant, which joins the pocket radius. In the last infeed, the base is finished from the center out. Edge finishing Edge finishing is performed in the same way as finishing, except that the last infeed (finish base) is omitted. Chamfer Chamfer Chamfering involves edge breaking at the upper edge of the pocket.
	Select with softkey	Mill- ing Pocket > Circular pocket







Parameters	Description	Unit
T, F, V	See Sec. "Programming the tool, offset value and spindle speed".	
Machining type	Roughing	
3.974	Finishing	
	Finishing on edge	
	Chamfer	
Single pos.	A circular pocket is machined at the programmed position (X0, Y0, Z0).	
Pos. pattern	Several circular pockets are machined in a position pattern (e.g. full circle, pitch circle, matrix, etc.).	
	The positions refer to the center point of the circular pocket:	
X0	Position in X direction (single position only), abs. or inc.	mm
Y0	Position in Y direction (single position only), abs. or inc.	mm
Z0	Workpiece height (single position only), abs. or inc.	mm
Ø	Diameter of pocket	mm
Z1	Depth of pocket in relation to Z0, abs. or inc. (not for chamfer)	mm
DXY	Max. infeed in plane (XY direction)	mm
	Alternatively, you can specify the plane infeed as a %, as a ratio \rightarrow plane infeed (mm) to milling cutter diameter (mm). (not for chamfer)	%
DZ	Max. depth infeed (Z direction) (not for chamfer)	mm
UXY	Finishing allowance in plane (pocket edge) (not for chamfer)	mm
UZ	Finishing allowance in depth (pocket base) (not for chamfer)	mm
Insertion:	You can select one of several insertion strategies:	
	Helical: Insertion along helical path	
	The cutter center point traverses along the helical path determined by the radius and depth per revolution. If the depth for one infeed has been reached, a full circle motion is executed to eliminate the inclined insertion path.	
	Feedrate: Machining feedrate	
	Center: Insert vertically in center of pocket	
	The tool executes the calculated depth infeed vertically in the center of the pocket.	
	Feedrate: Infeed rate as programmed under FZ	
	Note: The vertical insertion into pocket center method can be used only if the tool can cut across center or if the workpiece has been predrilled.	

EP	Max. insertion gradient (only for helical insertion) The gradient of the helix may be smaller in some geometric conditions.	mm/rev
ER	Insertion radius (only for helical insertion) The radius must not be larger than the cutter radius, otherwise material will remain. Also make sure the pocket is not violated.	mm
FZ	Depth infeed rate (for insertion in center only)	mm/min
		mm/tooth
Remove stock	Complete mach.:	
	The pocket must be milled from a solid workpiece (e.g. casting).	
	Remachining:	
	A small pocket or hole has already been machined in the workpiece. This needs to	
	be enlarged. Parameters AZ, and \varnothing must be programmed.	
FS	Chamfer width (for chamfer only), inc.	mm
ZFS	Insertion depth tool tip (for chamfer only), abs. or inc.	mm
AZ	Depth of premachined pocket or hole (for remachining only)	mm
Ø1	Diameter of premachined pocket or hole (for remachining only)	mm

3.8.4 Rectangular spigot

=?

The "Rectangular spigot" function is used when you want to mill various rectangular spigots.

You can select from the following shapes with or without a corner radius:



Rectangular spigot

Depending on the dimensions of the rectangular spigot in the workpiece drawing, you can select a corresponding reference point for the rectangular spigot.

In addition to the required rectangular spigot, you must also define a blank spigot, i.e. the outer limits of the material. The tool moves at rapid traverse outside this area. The blank spigot must not overlap adjacent blank spigots and is placed by ShopMill automatically on the finished spigot in a centered position.

The spigot is machined using only one infeed. If you want to machine the spigot using multiple infeeds, you must program the "Rectangular spigot" function several times with a reducing finishing allowance.



10.04

Contour approach/retraction

- The tool approaches the starting point at rapid traverse at the height of the retraction plane and adjusts to the safety clearance. The starting point is on the positive X axis rotated through α0.
- 2. The tool traverses the spigot contour sideways in a semicircle at machining feed. The tool first executes infeed at machining depth and then moves in the plane. The spigot is machined as a function of the programmed machining direction (climb/conventional) in a clockwise or counterclockwise direction.
- 3. When the spigot has been circumnavigated once, the tool retracts from the contour in the plane in a semicircle and then infeeds to the next machining depth.
- 4. The spigot is approached again in a semicircle and circumnavigated once. It repeats the process until the spigot depth has been reached.



5. The tool moves back to the safety clearance at rapid traverse.

Contour approach/retraction along semi-circle with CW rotating spindle and conventional milling operation

Machining type

You can select the machining mode for milling the rectangular spigot as follows:

- Roughing Roughing involves moving round the spigot until the programmed finishing allowance has been reached.
- Finishing If you have programmed a finishing allowance, the spigot is moved round until depth Z1 is reached.
- Chamfer Chamfering involves edge breaking at the upper edge of the rectangular spigot.

Select with softkey



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Help displays for milling rectangular spigots

Parameters	Description	Unit
5		
T, F, S, V	See Sec. "Programming the tool, offset value and spindle speed".	
Reference	You can select 5 different reference points:	
point	Spigot center	
	Bottom left	
	Bottom right	
	Top left	
	Top right	
Machining type	Roughing	
	Finishing Chamfer	
Single pos.	A rectangular spigot is machined at the programmed position (X0, Y0, Z0).	
Pos. pattern	Several rectangular spigots are machined in a position pattern (e.g. full circle, pitch circle, matrix, etc.).	
	The positions refer to the reference point:	
X0	Position in X direction (single position only), abs. or inc.	mm
Y0	Position in Y direction (single position only), abs. or inc.	mm
Z0	Workpiece height (single position only), abs. or inc.	mm
W	Width of spigot after machining	mm
L	Length of spigot after machining	mm
R	Radius at edges of spigot (corner radius)	mm
α0	Angle of rotation	Degr.
Z1	Depth of spigot (abs. or inc.) (not for chamfer)	mm
DZ	Max. depth infeed (Z direction) (not for chamfer)	mm
FS	Chamfer width (for chamfer only), inc.	mm
ZFS	Insertion depth tool tip (for chamfer only), abs. or inc.	mm
UXY	Finishing allowance in the plane in relation to length (L) and width (W) of the spigot;	mm
	Smaller spigot dimensions are obtained by calling the cycle again and programming it with a lower finishing allowance. (not for chamfer)	
UZ	Finishing allowance in depth (tool axis) (not for chamfer)	mm
W1	Width of specified blank spigot (important for determining approach position)	mm
L1	Length of specified blank spigot (important for determining approach position)	mm



3.8.5 Circular spigot

The "Circular spigot" function is used when you want to mill a circular spigot. In addition to the required circular spigot, you must also define a blank spigot, i.e. the outer limits of the material. The tool moves at rapid traverse outside this area. The blank spigot must not overlap adjacent blank spigots and is placed by ShopMill automatically on the finished spigot in a centered position. The spigot is machined using only one infeed. If you want to machine the spigot using multiple infeeds, you must program the "Circular spigot" function several times with a reducing finishing allowance. Approach/retraction 1. The tool approaches the starting point at rapid traverse at the height of the retraction plane and adjusts to the safety clearance. The starting point is always on the positive X axis. 2. The tool traverses the spigot contour sideways in a semicircle at machining feed. The tool first executes infeed at machining depth and then moves in the plane. The spigot is machined as a function of the programmed machining direction (climb/conventional) in a clockwise or counterclockwise direction. 3. When the spigot has been circumnavigated once, the tool retracts from the contour in the plane in a semicircle and then infeeds to the next machining depth. 4. The spigot is approached again in a semicircle and circumnavigated once. It repeats the process until the spigot depth has been reached.

5. The tool moves back to the safety clearance at rapid traverse.



Help display for milling a circular spigot



3	10.04

A	Parameters	ers Description	
U			
	T, F, S, V	See Sec. "Programming the tool, offset value, and spindle speed".	
	Machining type	Roughing	
		Finishing	
		Chamfer	
	Single pos.	A circular spigot is machined at the programmed position (X0, Y0, Z0).	
	Pos. pattern	Several circular spigots are machined in a position pattern (e.g. full circle, matrix,	
		line).	
		The positions refer to the reference point:	
	X0	Position in X direction (single position only), abs. or inc.	mm
	Y0	Position in Y direction (single position only), abs. or inc.	mm
	Z0	Workpiece height (single position only), abs. or inc.	mm
	Ø	Diameter of spigot after machining	mm
	Z1	Depth of spigot (abs. or inc.) (not for chamfer)	mm
	FS	Chamfer width (for chamfer only), inc.	mm
	ZFS	Insertion depth tool tip (for chamfer only), abs. or inc.	mm
	DZ	Max. depth infeed (Z direction) (not for chamfer)	mm
	UXY	Finishing allowance in plane (spigot diameter) (not for chamfer)	mm
	ZU	Finishing allowance depth (spigot base) (not for chamfer)	mm
	Ø1	Diameter of blank spigot	mm
		(important for determining approach position)	

3.8.6 Longitudinal slot

•		Use the "Longitudinal slot" function if you want to mill any kind of longitudinal slot.
=?		 The following machining methods are available: Mill longitudinal slot from solid material. Predrill longitudinal slot in the center first if, for example, the milling cutter does not cut across center (program the drilling, rectangular pocket and position program blocks one after another).
		Depending on the dimensions of the longitudinal slot in the workpiece drawing, you can select a corresponding reference point for the longitudinal slot.
	Approach/retraction	 The tool moves at rapid traverse to the retraction plane and infeeds at safety clearance. The tool is inserted into the material according to the chosen strategy. The longitudinal slot is always machined with the chosen machining type from inside out. The tool moves back to the safety clearance at rapid traverse.

Select with softkey

(1) HELP

the

Call help display with

key

Machining type
 You can select the machining mode for milling the longitudinal slot as follows:

 Roughing
 During roughing, the individual planes of the slot are machined one after the other until depth Z1 is reached.

• Finishing

In "Finishing" mode, the edge is always machined first. The slot edge is approached on the quadrant, which joins the corner radius. In the last infeed, the base is finished from the center out.

- Edge finishing Edge finishing is performed in the same way as finishing, except that the last infeed (finish base) is omitted.
- Chamfer

Chamfering involves edge breaking at the upper edge of the longitudinal slot.







Parameters	Description	Unit	
T, F, S, V	See Sec. "Programming the tool, offset value, and spindle speed".		
Reference	The reference point position must be defined:		
point	Center point of longitudinal slot:		
	Inside left		
	Inside right		
	Left-hand edge		
	Right-hand edge		
Machining type	Roughing		
	Finishing		
	Edge finishing		
Single pos	A longitudinal slot is milled at the programmed position (X0, X0, Z0)		
Pos pattern	Several longitudinal slots are milled in a position pattern (e.g. full circle, pitch circle)		
	matrix, etc.).		
	The positions refer to the reference point:		
xo	Position in X direction (single position only), abs. or inc.	mm	
YO	Position in Y direction (single position only), abs. or inc.	mm	
ZO	Workpiece height (single position only), abs. or inc.	mm	
W	Slot width	mm	
L	Slot length	mm	
α0	Angle of rotation	Degr.	
Z1	Depth of the slot (not for chamfer)	mm	
DXY	Max. infeed in plane (XY direction)	mm	
	Alternatively, you can specify the plane infeed as a %, as a ratio \rightarrow plane infeed (mm) to milling cutter diameter (mm). (not for chamfer)	%	
DZ	Max. depth infeed (Z direction) (not for chamfer)	mm	
FS	Chamfer width (for chamfer only), inc.	mm	
ZFS	Insertion depth tool tip (for chamfer only), abs. or inc.	mm	
UXY	Finishing allowance in plane (slot edge) (not for chamfer)	mm	
ZU	Finishing allowance in depth (slot base) (not for chamfer)	mm	
Insertion	It can be inserted vertically over slot center (Mi) or with oscillating motion (Pe):	mm	
	Center=Insert vertically in center of longitudinal slot:		
	The tool is inserted to infeed depth in the pocket center.		
	Note: This setting can be used only if the cutter can cut across center.		
	Oscillation=Insert with oscillation along center axis of longitudinal slot:		
	The cutter center point oscillates along a linear path until it reaches the depth infeed.		
	in order to remove the slope caused by insertion.		
FZ	Depth infeed rate (for insertion in center only)	mm/min	
		mm/tooth	



3.8.7 Circumferential slot

		The "Circumferential slot" function is used when you want to mill one or more circumferential slots of the same size in a full circle or pitch circle.
=?	Tool size Annular slot	Please note that there is a minimum size for the milling cutter used to machine the circumferential slot: • Roughing: $\frac{1}{2}$ slot width W – finishing allowance UXY \leq milling cutter diameter • Finishing: $\frac{1}{2}$ slot width W \leq cutter diameter • Edge finishing: Finishing allowance UXY \leq milling cutter diameter To create an annular slot, you must enter the following values for the "Number N" and "Aperture angle α_1 " parameters: N = 1 $\alpha_1 = 360^{\circ}$
	Approach/retraction	 The tool approaches the center point of the semicircle at the end of the slot at rapid traverse at the height of the retraction plane and adjusts to the safety clearance. Then, the tool enters the workpiece at machining infeed (taking into consideration the maximum infeed in the Z direction and the finishing allowance). The circumferential slot is machined in the programmed machining direction (climb or conventional) in a clockwise or counterclockwise direction. When the first circumferential slot is finished, the tool moves to the retraction plane at rapid traverse. The next circumferential slot is approached along a straight line or circular path and then machined. The tool moves back to the safety clearance at rapid traverse.



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Machining type	 You can select the machining mode for milling the circumferential slot as follows: Roughing During roughing, the individual planes of the slot are machined one after the other from center point of the semicircle at the end of the slot until depth Z1 is reached. Finishing In "Finishing" mode, the edge is always machined first until depth Z1 is reached. The slot edge is approached on the quadrant, which joins the radius. In the last infeed, the base is finished from the center point of the semicircle to the end of the slot. Edge finishing Edge finishing is performed in the same way as finishing, except that the last infeed (finish base) is omitted. Chamfer Chamfering involves edge breaking at the upper edge of the circumferential slot.
Select with softkey	Mill- ing Slot > Longitu- dinal slot With the "Alternat." softkey, you can position the circumferential slots on a full circle or pitch circle.
Call help display with the HELP key	Image: state of the state



Parameters	Description	Unit
T, F, S, V	See Sec. "Programming the tool, offset value and spindle speed".	
FZ	Depth infeed rate	mm/min mm/tooth
Machining type	Roughing Finishing Edge finishing Chamfer	
Full circle	The circumferential slots are positioned around a full circle. The slot spacing is uniform and is calculated by the control.	
Pitch circle	The slots are positioned around a pitch circle. The slot spacing can be determined on the basis of angle α 2.	
	The positions refer to the center point:	
X0	Position in the X direction, abs. or inc.	mm
Y0	Position in the Y direction, abs. or inc.	mm
Z0	Workpiece height, abs. or inc.	mm
W	Slot width	mm
R	Radius of circumferential slot	mm
α0	Angle of rotation in relation to X axis	Degr.
α1	Angle of aperture of a slot	Degr.
α2	Advance angle (for pitch circle only)	Degr.
N	Number of slots	
Z1	Depth of the slot, relative to Z0 (not for chamfer)	mm
DZ	Max. depth infeed (Z direction) (not for chamfer)	mm
FS	Chamfer width (for chamfer only), inc.	mm
ZFS	Insertion depth tool tip (for chamfer only), abs. or inc.	mm
UXY	Finishing allowance in XY plane (edge of slot) (not for chamfer)	mm
Positioning	Linear: Next position is approached linearly at rapid traverse. Circular: Next position is approached at the programmed feedrate FP along a circular path.	
FP	Feed for positioning on a circular path	mm/min





3.8.8 Use of position patterns for milling



If you want to mill a pocket, spigot or longitudinal slot at more than one position, you must program a separate positioning block. When you call the milling cycle, use softkey "Alternat." to select "Pos. pattern" in the "Single position" parameter field. The parameters for single positions X0, Y0 and Z0 then disappear from the display.



Extract from the parameter form of a rectangular pocket with "Pos. pattern" entry

After you have finished programming the cycle and stored it, you need to program the position pattern.

Select with softkey



ShopMill automatically chains the milling cycle and the subsequently programmed position pattern.

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Ie 1 You want to mill 12 mutually parallel rectangular pockets at an angle of 15 degrees. Arrangement on matrix: 4 columns, 3 rows.

Blank dimensions: X=115mm, Y=80mm, Z=30mm

Rectangular pocket dimensions: Length 20 mm, width 10 mm, depth 8 mm Corner radius 1.5mm.

You have selected "Bottom left" as the pocket reference point.

Rect	tangular poc	:ket			
Т	15	D1			
F	0.200	mm∕tooth			
S	400	грм			
	Botton left				
Mact	nining:				
	Pos. pattn.				
ы	10 000				
ï	20 000		Patt	arn	
R	1.500		T G C		
αØ	15.000	0	70	UF10 0 000	_
Z1	8.000	inc	20	0.000	abs
DXY	2.000		20	45,000	
DZ	1.000		20	15.000	abs
UXY	0.000	nn	YU	5.000	abs
UZ	0.000		αØ	15.000	U U
Appr	roach:	He	L1	26.000	
EP	2.000	mm/rev	LZ	18.000	
ER	2.000	nn	N1	4	
Soli	id mach:Comp	olete	N2	3	

Parameter input fields for rectangular pocket and position pattern



Programming graphic, rectangular pockets on matrix at angle of 15 degrees

Щ ₁ N10	Right pocket	V	T=15 F0.2/Z S400rev. Z1=60ink W10 L20
∰ [_] N15	001: Hole grid		Z0=0 X0=15 Y0=5 N1=4 N2=3

Extract from machining plan; milling rectangular pockets on a matrix







Programming example 2 You want to rough cut 6 longitudinal slots on a full circle of Ø 32mm. The slots are rotated through 30 degrees.

Blank dimensions: X=100mm, Y=100mm, Z=20mm

Slot dimensions: Length 28mm, width 16mm, depth 5mm

You have selected "center point" as the slot reference point.

Long	gitudinal sl	ot				
Т	12	D1				
F	0.200	mm∕tooth				
S	600	грм				
	Center					
Mach	nining:	∇				
	Pos. pattn.					
			Pat	tern		
				Full	circle	
W	16.000		ZØ		0.000	abs
L	28.000					
α0	30.000	0	XØ		50.000	abs
Z1	5.000	inc	YØ		50.000	abs
DXY	1.000		αØ		0.000	0
DZ	1.000		B		32.000	
UXY	0.000	nn	N		60000	
UZ	0.000				U	
Appr	roach:	OSC.				
EΨ	20.000	0	Pos	tion	ing:	Straig

Parameter input fields for longitudinal slot and position pattern



Programming graphics, longitudinal slots at angle of 30 degrees on full circle

N10 _[Longit.slot ⊽	T=12 F0.2/Z S600rev. Z1=5ink W16 L28
🗘 - N15	002: Hole full cir.	Z0=0 X0=50 Y0=50 R32 N6

Extract from machining plan; milling longitudinal slots on a full circle



3.8.9 Engraving

		The "Engraving" function is used to engrave a text on a workpiece along a line or arc. You can enter the text directly in the text field as "fixed text" or assign it via a variable as "variable text".
=?		ShopMill uses a proportional font for engraving, i.e. the width of the individual characters varies.
	Approach/retraction	 The tool approaches the starting point at rapid traverse at the height of the retraction plane and adjusts to the safety clearance. The tool moves to the machining depth Z1 at the infeed feedrate FZ and mills the characters. The tool retracts to the safety clearance at rapid traverse and moves along a straight line to the next character. Steps 2 and 3 are repeated until the entire text has been milled.
5	Variable texts	 There are various ways of defining variable text: Date and time You can engrave workpieces with the production date and current time of day, for example. The values for data and tiem are read from the CNC. Workpiece count Using the workpiece variables you can assign a consecutive number to the workpieces. You can define the format (number of digits, leading zeroes). The "workpiece count" variable is defined as a user variable (_E_PART[0]) in the GUD 7 data block. The place holder (#) is used to format the number of digits at which the workpiece counts output will begin. If you output the workpiece count 1 for the first workpiece, you can specify an additive value (e.g., <#,_E_PART[0] + 100>). The workpiece count output is then incremented by this value (e.g. 101, 102, 103,). Numbers When outputting number (e.g. measurement results), you can select the output format (digits either side of the point) of the number to be engraved. Text Instead of entering a fixed text in the engraving text field, you can specify the text to be engraved via a text variable (e.g., _VAR_TEXT="ABC123")



	Mirror writing	If you want to engrave mirror writing, first program the mirroring (see Section "Defining coordinate transformations" and then enter the text in the "Engraving" function.
	Full circle	If you want to distribute the characters evenly around a full circle, enter the arc angle α 2=360°. ShopMill then distributes the characters evenly around the full circle.
\$	Mill- ing >	Press the "Milling" and "Engraving" softkeys.
	Lowercase letters	 Press the "Lowercase" softkey to enter lowercase letters. Press it again to enter uppercase letters.
	Special characters Special characters>	Press the "Special characters" softkey if you need a character that does not appear on the input keys.
		The "Special characters" window appears.
	DK	Place the cursor on the character you require.
		Press the "OK" softkey.
		The selected character is inserted into the text at the cursor position.
	Entering a date	
	Variable > Date	Press the "Variable" and "Date" softkeys if you want to engrave the current date.
		The data is inserted in the European date format (<dd>.<mm>.<yyyy>).</yyyy></mm></dd>
		To obtain a different date format, you must adapt the format specified in the text field. For example, to engrave the date in the American

<M>/<D>/<YY> .

date format (month/day/year => 8/16/04), change the format to



Entering a time	
Variable > Time	Press the "Variable" and "Time" softkeys if you want to engrave the current time.
	The time is inserted in the European format (<time24>). To have the time in the American format, change the format to <time12>.</time12></time24>
	Example: Text entry: Time: <time24> Execution: Time: 16.35 Time: <time12> Time: 04.35 PM</time12></time24>
Entering workpiece counts	
Variable > Workpiece count 000123	Press the "Variable" and "Workpiece count 000123" softkeys to engrave a workpiece count with a fixed number of digits and leading zeroes.
	 The format text <######,_E_PART[0]> is inserted and you return to the engraving field with the softkey bar. ➢ Define the number of digits by adjusting the number of place holders (#) in the engraving field.
	If the specified number of digits (e.g. ##) is not enough to display the workpiece count, ShopMill will increase the number digits automatically. - OR -
Variable > Workpiece count 123	Press the "Variable" and "Workpiece count 123" softkeys if you want to engrave a workpiece count without lead zeroes.
	 The format text <#,_E_PART[0]> is inserted and you return to the engraving field with the softkey bar. > Define the number of digits by adjusting the number of place holders in the engraving field.
	If the specified number of digits is not enough to display the workpiece count (e.g. 123), ShopMill will increase the number digits automatically.
	You can enter an additive value, for example, if you want to resume production of workpieces after an interruption. The workpiece count output is then increased by this value.
Entering a variable	
Variable > Number 123.456	Press the "Variable" and "Number 123.456" softkeys if you want to engrave a any number in a certain format.
	The format text <# ### \/AD NILIM> is inserted and you return to the

The format text <#.###,_VAR_NUM> is inserted and you return to the engraving field with the softkey bar.
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The place holders #.### define the digit format in which the number defined in _VAR_NUM will be engraved.

For example, if you have stored 12.35 in _VAR_NUM, you can format the variable as follows.

Input	Output	Meaning
<#,_VAR_NUM>	12	Integer digits not formatted,
		no fractional digits
<####,_VAR_NUM>	0012	4 integer digits, leading
		zeroes, no fractional digits
< #,_VAR_NUM>	12	4 integer digits, leading
		zeroes, no fractional digits
<#.,_VAR_NUM>	12.35	Integer and fractional digits
		not formatted.
<#.#,_VAR_NUM>	12.4	Integer digits not formatted,
		1 fractional digit (rounded)
<#.##,_VAR_NUM>	12.35	Integer digits not formatted,
		2 fractional digits (rounded)
<#.####,_VAR_NUM>	12.3500	Integer digits not formatted,
		4 fractional digits (rounded)

If there is insufficient space in front of the decimal point to display the number entered, it is automatically extended. If the specified number of digits is larger than the number to be engraved, the output format is automatically filled with the appropriate number of leading and trailing zeroes.

Instead of the decimal point you can also use a blank.

Instead of _VAR_NUM you can use any other numeric variable (e.g. R0).





Entering a variable text Variable > Variable > Variable >	Press the "Variable" and "Variable text" softkeys if you want to take the text to be engraved (up to 200 characters) from a variable.
	The format text <text, _var_text=""> is inserted and you return to the engraving field with the softkey bar. You can use any other text variable instead of _VAR_TEXT.</text,>
Deleting text Delete text >	Press the "Delete text" softkey to delete the entire text.
1	The format text for the variables is always inserted at the current cursor position.



The "Lowercase", "Special characters", "Variable", and "Delete text" softkeys only appear when you place the cursor in the input field for engraving text.

Parameters	Description	Unit			
T, D, F, S, V	See Sec. "Creating program blocks".				
Alignment	Align text to line				
	Align text to arc				
	Align text to arc				
Reference point	Position of reference point within text				
Engraving text	a maximum of 91 characters				
X0	Reference point in X direction (abs.)	mm			
R	Ref. point on longitudinal polar axis (alternative to X0) – (for curved alignment only)	mm			
Y0	Reference point in Y direction (abs.)	mm			
α0	Ref. point on angular polar axis (alternative to Y0) – (for curved alignment only)	Degr.			
Z0	Reference point in Z direction (abs.)	mm			
Z1	Machining depth (abs. or inc.)	mm			
FZ	Depth infeed rate				
		mm/tooth			
W	Character height	mm			
DX1	Character spacing	mm			
DX2	Total width (alternative to DX1) – (for linear alignment only)	mm			
α1	Text direction (for linear alignment only)	Degr.			
α2	Arc angle (alternative to DX1) – (for curved alignment only)	Degr.			
XM	Center point of arc (abs.) – (for curved alignment only)	mm			
YM	Center point of arc (abs.) – (for curved alignment only)	mm			



3.9 Measurement

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3.9.1 Measuring the workpiece zero

The "Workpiece zero" function is used to determine the workpiece zero in a program by means of an electronic measuring probe.

For example, if you want to produce several workpieces, an offset may arise between the old and the new workpiece zero when clamping the next workpiece in the vise. You can measure the workpiece edges to determine the new workpiece zero and save it in a work offset or in a GUD.



Workpiece clamping with offset in relation to previous clamping

Even if you want to machine several clamped workpieces in parallel, you can determine the zero for each workpiece first.



Several clamped workpieces

You can use electronic measuring probes exclusively to determine the workpiece zero within a program. These must be calibrated beforehand (see Sec. "Calibrating an electronic measuring tool"). These measuring probes must always be specified as 3D probe in the tool management.



During automatic measurement, the measuring probe first moves at rapid traverse and then at measuring infeed to the edge of the workpiece and back. The measuring infeed is defined in a machine data.

Please refer to the machine manufacturer's instructions.

The workpiece radius is considered during calculation of the workpiece zero and is stored in a work offset.

- Insert an electronic measuring probe in the spindle (see Sec.
 "Programming the tool, offset value, and spindle speed").
- > Select the "Misc." and "Workpiece zero" softkeys.
- Use the softkeys to select in which axis direction you want to approach the workpiece first.
- > Enter the values for the individual parameters.
- Press the "Accept" softkey.
- > Repeat the process for the other two axes.

Parameters	Description			
Т	Tool of type 3D probe			
Х	Approach position in X direction (abs.)	mm		
Y	Approach position in Y direction (abs.)	mm		
z	Approach position in Z direction (abs.)	mm		
Zero off.	Work offset where the workpiece zero is to be saved.			
	Basic work offset			
	 Work offset (the values are saved in the coarse offset and existing values in the fine offset are deleted.) 			
	• GUD data (you to scan the measurement result in GUD E_MEAS, e.g. for other calculations (tolerance checks, etc.)).			
Approach	+: The probe approaches the workpiece in the plus direction			
direction	-: The probe approaches the workpiece in the minus direction			
	At the approach position in the Z direction, this parameter does not apply as the tool			
	can only approach the workpiece in a negative direction!			
X0, Y0, Z0	Setpoint position of the workpiece edge	mm		









Use the "Measure tool" function if you want to check the tool wear while machining the workpiece.

You can only measure the tools within a program using an electronic measuring probe, which you must calibrate the probe first.

You can consider a lateral or longitudinal offset V when measuring. If the maximum length of the tool is not at the outer edge of the tool or the maximum width is not at bottom edge of the tool, you can store this difference in the offset.





Longitudinal offset

ShopMill then calculates the tool wear data from the known positions of the toolholder reference point and of the probe and from the tool offset data. The wear values are automatically entered in the wear list

If the wear exceeds the maximum permissible value for tool wear ΔL or ΔR , the tool is replaced and disabled against further use. If no replacement tool is available, the machining operation is interrupted.

and added to any existing values stored there.

During the measuring cycle the tool automatically approaches the probe at measurement feedrate. The tool then moves to the retraction plane before returning to the tool change point.

ShopMill automatically executes the measurement with either a rotating or stationary spindle depending on the tool type and selected measurement method (measure radius/length).

Th radius is always measured in the opposite direction to spindle rotation.

Mics.	Measure tool >
Measure length	-or- Measure

The length of a tool is measured with the spindle stationary. However, if the diameter of the milling cutter to be measured is gerater than the diameter of the probe, the rotating spindle is measured in the opposite direction. The tool is then not move over the probe center to center but with the outside edge of the tool above the center of the probe.

- Move the tool until it is positioned over the approximate center of the measuring surface of the probe (see Section "Straight or circular path motion").
- > Press the "Misc." and "Measure tool" softkeys.
- Use the softkeys to select whether you want to measure the radius or the length of the tools.

Parameters	Description	Unit			
Т	Tool to be measured				
D Cutting edge of the tool					
V Lateral offset (if necessary) – for length measurement only					
	Longitudinal offset (if necessary) – for radius measurement only				
ΔL	Max. permissible wear value (see tool data sheet supplied by tool manufacturer) –	mm			
	applies only to length measurement				
∆R	Max. permissible wear value (see tool data sheet supplied by tool manufacturer) –	mm			
	applies only to radius measurement				

3.9.3 Calibrating the measuring calipers

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3.10 Miscellaneous functions

3.10.1 Calling a subroutine

If you require the same machining steps in the programming of different workpieces, you can define these machining steps in a separate routine. You can then call this subroutine in any programs. Identical machining steps therefore only have to be programmed once.
ShopMill does not differentiate between main program and subroutine. This means that you can call a "standard" sequential control or G code program as subroutine in another sequential control program. In this subroutine, you can also call another subroutine. The maximum nesting depth is 8 subroutines. You cannot not insert subroutines among blocks chained by the control.
If you want to call a sequential control program as a subroutine, the program must already have been calculated once (load or simulate program in Machine Auto mode). This is not necessary for G code subroutines.
The subroutine must always be stored in the NC main memory (in a separate directory "XYZ" or in the "ShopMill", "Part programs", "Subroutines" directories).
If you want to call a subroutine located on another drive, you can use G code command "EXTCALL".
Example: Calling program "Form25_1.mpf" on the compact flash card of the PCU 20: EXTCALL "C:\FORM25_1.MPF"
Please note that, when a subroutine is called, ShopMill evaluates the settings in the program header of the subroutine. These settings also remain active even after the subroutine has ended.

If you wish to activate the settings from the program header for the main program again, you can make the settings again in the main program after calling the subroutine (see Sec. "Changing program settings").





- How to create a ShopMill or G code program that you can call as a subroutine in another program.
- Place the cursor in the machining plan of the main program on the program block after which the subroutine call is to be inserted.
- > Press the "Misc." and "Subroutine" softkeys.
- Enter the path of the subroutine if the desired subroutine is not stored in the same directory as the main program.

Directory	Path to enter
ShopMill	ShopMill
Separate directory XYZ	XYZ
Part programs	MPF
Subprograms	SPF

Enter the name of the subroutine that you want to insert. You only need to enter the file extension (*.mpf or *.spf) if the subroutine does not have the file extension specified for the directory in which the subroutine is stored.

Directory	Specified file extension
ShopMill	*.mpf
Separate directory XYZ	*.mpf
Part programs	*.mpf
Subprograms	*.spf

The subroutine is thus executed in the position pattern.



> Press the "Accept" softkey.

The subroutine call is inserted in the main program.

Ρ	N5	SHOPMILL		
t-1	N10	Face milling ∇	T=CUTTER F	
Ì2,	N15	Work offset	1 G54	
원물 수면	N45	Execute	"Tasche_b"	Call subroutine "Tasche_b"
ÌØ,	N20	Work offset	2 G55	_
문문 수단	N40	Execute	"TASCHE_b"	
ÌØ,	N25	Work offset	3 G56	
원물 수면	N50	Execute	"TASCHE_b"	
ig,	N30	Work offset	4 G57	
E E E	N55	Execute	"Tasche_b"	
END		Program end		

Subroutine call

3.10.2 Repeating program blocks





If certain steps in the machining of a workpiece have to be executed more than once, it is only necessary to program these steps once. ShopMill offers a function for repeating program blocks.

You must mark the program blocks that you want to repeat with a start and end marker. You can then call these program blocks up to 9999 times again within a program. The markers must be unique, i.e. they must have different names.

You can also set markers and repeats after creating the program, but not within chained program blocks.

Accept

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1			lt is prec proo	also p ceding gram b	possible to use the program blocks a plocks.	same nd as	marker as the the start marker	end marker of the er for the following	
			P	N5	SHOPMILL				
			*:00	N10	begin:		-	— Start marker	
				N15	Right pocket	V	T=MILL16 FØ		
			*:00	N20	end:		_	— End marker	
			∆÷∡	N25	Offset		X30 Y0		
			∆→4	N30	Scaling	add	X1.5 Y1.5		
			昌€	N35	Repetition		begin end -	– Repeat	
			END	N40	Program end				
			Repe	eating p	rogram blocks				
\rightarrow	Mics.	Set marker		Press the "Misc." and "Set marker" softkeys.					
			\succ	Enter a name.					
	Accept		\triangleright	Press the "Accept" softkey.					
			A st	A start marker is inserted behind the current block.					
			\triangleright	Enter	the program block	s that	you want to re	epeat later.	
	Mics.	Set	\triangleright	Press	the "Misc." and "S	Set ma	rker" softkeys.		
		liaikei	\triangleright	Enter	a name.				
	Accent		\triangleright	Press	the "Accept" softk	ey.			
			An e	end m	arker is inserted be	ehind	the current blo	ck.	
				Contii the pr	nue programming (ogram blocks.	up to f	he point where	e you want to repeat	
	Mics.	Repeat	\triangleright	Press	the "Misc." and "F	Repea	t" softkeys.		

- Enter the names of the start and end markers and the number of ≻ times the blocks are to be repeated.
- Press the "Accept" softkey.

The marked program blocks are repeated.



3.10.3 Changing program settings





All parameters defined in the program header, with the exception of the unit of measurement, can be changed at any location in the program.

The settings in the program header are modal, i.e. they remain active until they are changed.

Define a new blank, e.g. in the sequential control program, if you want to change the visible cutout during simulation.

This is useful for the work offset, coordinate transformation, cylinder peripheral surface transformation and swiveling functions. First program the functions listed above and then define a new blank.



- > Press the "Misc." and "Settings" softkeys.
- Enter the desired parameters. For a description of the parameters, see Sec. "Creating a new program".
- Press the "Accept" softkey.

The new settings for the program are loaded.



Work offset >

3.10.4 Calling work offsets

You can call work offsets (G54, etc.) from any program. You can use these offsets, for example, when you want to machine workpieces with various blank dimensions using the same program. The offset will, in this case, adapt the workpiece zero to the new blank.

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х_м

You define the work offsets in the work offset list (see Sec. "Defining work offsets"). You can also view the coordinates of the selected

Press the "Misc.", "Transformation", and "Work offset" softkeys.

Select one of the work offsets or the standard offset. \geq

-or-

 \geq

offset here.

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Work offset in X and Y directions

Enter the desired offset directly in the input field. \geq

-or-

Press the "Work offset" softkey. \succ

The work offset list is displayed.

-and-

Select a work offset. \triangleright











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То

Program

Programming with ShopMill 3.10 Miscellaneous functions

-and-

Press the "To Program" softkey.

The work offset is loaded into the parameterization screen form.

To deselect the work offsets, select the standard offset or enter zero in the field.

3.10.5 Defining coordinate transformations



To make programming easier, you can transform the coordinate system. Use this possibility, for example, to rotate the coordinate system.

Coordinate transformations only apply in the current program. You can define displacement, rotation, scaling or mirroring. You can select between a new or an additive coordinate transformation. In the case of a new coordinate transformation, all previously defined coordinate transformations are deselected. An additive coordinate transformation acts in addition to the currently selected coordinate transformations.

Offset

For each axis, you can program an offset of the zero point.





New offset

Additive offset

Rotation

You can rotate every axis through a specific angle. A positive angle corresponds to counterclockwise rotation.







New rotation

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Additive rotation

Scaling •

> You can specify a scale factor for the active machining plane as well as for the tool axis. The programmed coordinates are then multiplied by this factor.

Note that the scaling always refers to the zero point of the workpiece. For example, if you increase the size of a pocket whose center point does not coincide with the zero point, scaling will shift the center of the pocket.



New scaling



Additive scaling



Offset, rotation, and scaling

Mirroring Furthermore, you can mirror all axes. Enter the axis to be mirrored in each case.



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Note that with mirroring, the travel direction of the cutting tool (conventional/climb) is also mirrored.





New mirroring





Mirroring of the X axis

- > Press the "Misc." and "Transformation" softkeys.
- > Select the coordinate transformation using the softkey.
- Select whether you want to program a new or an additive coordinate transformation.
- Enter the desired coordinates.





3.10.6 Cylinder surface transformation



Function

The cylinder surface transformation is required in order to

- Longitudinal grooves on cylindrical bodies,
- Transverse grooves on cylindrical objects,
- Grooves with any path on cylindrical bodies.

The cylinder peripheral surface transformation is a software option.

The path of the grooves is programmed with reference to the unwrapped, level surface of the cylinder. The slot can be programmed as a line/circle contour, via drilling or milling cycles or with the contour milling function (free contour programming).



There are two variants of cylinder surface transformation, i.e.

- Slot side compensation OFF
- Slot side compensation on (path milling only)

Slot side compensation OFF

When slot side compensation is deactivated, any type of slot with parallel sides can be machined if the tool diameter equals the slot width.

The slot sides are not parallel if the slot width is larger than the tool diameter.



The slot contour is programmed for machining purposes.



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	Slot side compensation ON	When slot side compensation is active, slots with parallel sides are machined even if the slot width is larger than the tool diameter.
1		The slot contour must not be programmed for machining purposes, but the imaginary center-point path of a bolt inserted in the slot; the bolt must be in contact with all sides of the slot. The slot width is determined by parameter D. (see also Sec. "Example 5: Slot side compensation".)
	Programming	 The basic programming procedure is as follows: Select work offset for cylinder surface transformation (e.g. offset the zero point on the center point of the cylinder end face) Position the Y axis (Y axis must be positioned prior to cylinder surface transformation because it is defined differently after transformation) Activate cylinder surface transformation Select work offset for machining on developed cylinder surface (e.g. shift zero point to the zero point on the workpiece drawing) Program machining operation (e.g. enter contour and path milling) Deactivate cylinder surface transformation
		The programmed cylinder surface transformation is simulated only as a developed peripheral surface.
1		The work offsets active prior to selection of cylinder surface transformation are no longer active after the function has been deselected.
	Select with softkey	Mics. Transfor- mations > Cylinder surface >



Parameters	Description	Unit			
Transformation	Activate/deactivate cylinder peripheral surface transformation (see also example below				
Ø	Cylinder diameter (only when transformation is active)				
Slot wall offset	Activate/deactivate slot side compensation (only when transformation is active)				
D	Offset to the programmed path (only with groove wall offset ON)	mm			

Options for free contour programming

General information	For contours (e.g. slots) on a cylinder, lengths in the circumferential direction of the cylinder peripheral surface (e.g. Y axis) are often specified as angles. Several options are available under the "Mill contour" function in free contour programming for this purpose. Depending on the selected axis (selection is made via a display machine data), you can enter the length as an angle.
Start point	In the screen form for selecting the starting point, you can also activate or deactivate the cylinder surface transformation function via the "Alternat." softkey. When the function is active, you are offered the diameter \emptyset of the cylinder.



Notes

The dimensions of the developed surface are specified in mm in the graphics!

Depending on the axis and the relevant element, angle parameters α , I α or Y α , J α are added to the "Horizontal/vertical/diagonal line" and

"Arc" when the cylinder surface transformation function is active.



3.10.7 Swiveling

You can use swivel heads or swivel tables to create and/or machine inclined planes.

It is not necessary to program the swivel axes of the machine (A, B, C), since you can specify the rotations around the geometry axes (X, Y, Z) of the workpiece coordinate system directly as described in the relevant workpiece drawing.

The rotation of the workpiece coordinate system in the program is then automatically converted to a rotation for the relevant swivel axis of the machine during machining.

The swivel axes are always rotated to place the machining plane perpendicular to the tool axis for machining. During machining, the machining plane is permanently set.

When the coordinate system is swiveled, the previously set work offset is automatically converted for the swiveled state.

The main programming procedure is:

- 1. Swivel the coordinate system into the plane to be machined.
- 2. Program machining in the X/Y plane in the usual way.
- 3. Swivel the coordinate system back to its original position.

It is possible the software limit switches may be violated in the swiveled plane when approaching the programmed machining. In this case, ShopMill travels along the software limit switches above the retraction plane. In the event of violation below the retraction plane, the program is interrupted with an alarm for safety's sake. To avoid this, before swiveling, e.g. move the tool in the X/Y plane and position it as close as possible to the starting point of the machining operation or define the retraction plane closer to the workpiece.

In a swiveled plane the "Workpiece zero" function is operative but not the "Measure tool" function.

The swiveled coordinates are retained in reset state and even after power ON, i.e. you can still retract from an inclined hole by retracting in +Z direction.

Please refer to the machine manufacturer's instructions.

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	Direction	In swivel systems with 2 rotary axes, a particular plane can be reached in two different ways. You can choose between these two different positions in the "Direction" parameter. The +/- corresponds to the larger or smaller value of a rotary axis. This may affect the working area. When the swivel data set is set up, the entries in the "Direction" parameter determine for which rotary axis you can select each of the two settings.
		Please refer to the machine manufacturer's instructions.
	Fixing the tool tip	If one of the two positions cannot be reached for mechanical reasons, the alternative position is automatically selected irrespective of the setting of the "Direction" parameter. To avoid collisions, you can use the 5-axis transformation (software option) to retain the position of the tool tip during swiveling. This function must be enabled in the "Follow-up tool" parameter when the "Swivel" function is set up.
		Please refer to the machine manufacturer's instructions.
_ 3 ™	Mics. Transformation > Swivel > Swivel >	Press the "Misc." and "Transformation" softkeys.
	Delete values	 Press the "Delete values" softkey to restore the initial state, i.e. to zero the values. This is done, for example, to swivel the coordinate system back to

This is done, for example, to swivel the coordinate system back to its original orientation.

Parameters	Description	Unit		
TC Name of the swivel data block				
	0: Removing the swivel head, deselecting the swivel data set			
No entry: No change to set swivel data block				
T Tool name				
Move clear No: Do not retract tool before swiveling				
Z: Move tool axis to retraction position before swiveling				
	Z, X, Y: Move machining axis to retraction position before swiveling			
	Tool max: Retract tool as far as the software limit switch in the tool direction			
	Tool inc: Retract tool up to the incremental value entered in the tool direction			

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Swiveling	Yes: compute and swivel (swivel coordinate system and move swivel axes) No: only compute, don't swivel (only swivel coordinate system, don't move swivel				
	axes)				
Transformation	Swiveling additive or new				
X0	Reference point for rotation		mm		
Y0	Reference point for rotation		mm		
Z0	Reference point for rotation		mm		
Swivel method	Axial swiveling, or swiveling via solid or projecti	on angle			
х	Axis angle (axial swivel)	The sequence of the axes	Degr.		
Y	Axis angle (axial swivel)	can be altered as required	Degr.		
Z	Axis angle (axial swivel) with "Alternat."		Degr.		
α	Angle of rotation in the XY plane about the Z axis (swiveling via solid angle)				
β	Angle of rotation in space about the Y axis (swiveling via solid angle)		Degr.		
Χα	Axis angle (swiveling via projection angle)	The sequence of the axes	Degr.		
Υα	Axis angle (swiveling via projection angle)	can be altered as required	Degr.		
Ζβ	Axis angle (swiveling via projection angle)	with "Alternat."	Degr.		
X1	New zero point of rotated surface				
Y1	New zero point of rotated surface				
Z1	New zero point of rotated surface				
Direction	Preferred direction of rotation with 2 alternatives				
	+: Larger angle of the axis on the scale of the swivel head / swivel table				
	-: Smaller angle of the axis on the scale of the swivel head / swivel table				
Fix tool tip	Follow-up: The position of the tool tip is maintained during swiveling.				
	Do not correct: The position of the tool tip is changes during swiveling.				



Other additive transformations can be added to the offsets before (X0, Y0, Z0) or after (X1, Y1, Z1) swiveling (see Sec. "Work offsets").



Programming example

You want to bevel a corner on a cube. The oblique surface is defined as the machining plane as follows:

- With axial swiveling and swiveling using solid angles, the system of coordinates is rotated first in the XY plane in such a way that the upper edge of the inclined surface of the cube runs parallel to the X axis (rotate 45° about Z axis or α =45°). The system of coordinates is then tilted so that the inclined plane of the cube is in the XY plane (rotate -54.736° about Y axis -54.736° or β =54.736°).
- With the swiveling via projection angles options, the X and Y axes are rotated through 45° so that the inclined plane of the cube is in the XY plane. The Z axis is then rotated through 30° so that the X axis runs through the center point of the inclined surface (zero point of rotated surface).

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Programming with ShopMill 3.10 Miscellaneous functions



Workpiece machined by a swivel head



Swivel					
т	CUTTER		D1		
Retr	act	No			
Swiv	/el	Yes			
	New				
XØ	-50.000				
YØ	-50.000				
ZØ	-25.000				
	Solid angle				
α	45.000	•			
β	54.736	•			
X1	20.412				
Y1	0.000				
Z1	0.000				
Direction: -					
	track				

Swiv	vel					
т	CUTTER		D1			
Retr	act	No				
Swiv	/el	Yes				
	New					
XØ	-50.000					
YØ	-50.000					
ZØ	-25.000					
	Projection a	ngle				
Χα	45.000	•				
Υα	-45.000	•				
Zβ	30.000	•				
X1	20.412					
Y1 -	0.000					
Z1	0.000					
Dire	Direction: -					
	track					

Swivel (axial)

Swivel (solid angle)

Swivel (projection angle)



3.10.8 Miscellaneous functions



You can e.g. position the spindle again between the individual machining steps or activate the coolant or stop machining.

The following functions are available:

Spindle

Determine direction of spindle rotation or spindle position (see Sec. "Starting, stopping, and positioning a spindle manually")

Gear stage
 Set gear stage, if machine has gears

Please refer to the machine manufacturer's instructions.

 Miscellaneous M functions Machine functions, such as "Close door"; they are additionally provided by the machine manufacturer

Please refer to the machine manufacturer's instructions.

- Coolant Activate/deactivate coolant 1/2
- Tool-spec. fct 1 to 4 Select tool-specific functions 1 to 4; they are additionally provided by the machine manufacturer

Please refer to the machine manufacturer's instructions.

- Dwell time Set time after which execution on the machine is continued
- Programmed stop
 Stop execution on the machine if the "Programmed Stop" softkey is also active (see Sec. "Program control").
- Stop Stop execution on the machine
- > Press the "Line Circle" and "Machine func." softkeys.
- > Enter the desired parameters.
- Press the "Accept" softkey.





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3.11 Inserting G code into the sequential control program

		You can a	can also	progra insert	am G co comme	de blocł nts to e	ks in a sequential control program. You kplain the program.
=?		You	will	find a d	detailed	descrip	tion of G code blocks to DIN 66025 in:
		Refe	ren	ces:	/PG/, /PGA/,	Progra SINUM Progra SINUM	Imming Guide Fundamentals /IERIK 840D/840Di/810D Imming Guide Advanced /IERIK 840D/840Di/810D
		You end o	can of th	not ins ie prog	ert G co ram or v	de bloc within a	ks before the program header, after the chained sequence of program blocks.
		Shop	Mill	does	not disp	lay G co	ode blocks in programming graphics.
	Feed	After type was activ Shop	eac G94 prog e af Mill	ch Sho 4 (mm/ gramm ter a S cycle.	pMill cy min) is a ed in the hopMill	cle (drilli always a e ShopN cycle if	ing, milling, profile milling), the feed active, irrespective of the feed type that Aill cycle. The feed value F is only G94 was programmed in the G94
		How the fe avoid	evei eed d an	r, you s value y unex	should a (F) in th pected	lways p e first G types of	rogram the feed type (G94 or G95) and code block after a ShopMill cycle to motion.
	FOR loop	lf you you o _E_0	u wa can COL	ant to p use the JNTER	orogram e global t [9] of ty	a FOR user va /pe INT.	loop in the sequential control program, riables (GUD7) _E_COUNTER [0] to
		COUN	TER	_E			
		Р	N5	COUNT	ER_E		Work offs 1 G54
		т	N10	T=CUT	TER_10	S1000U	
		G	N15				
			N20	RAPID	X0 Y0	Z5	
		G	N20	F2007	min 7-5		
		G	N35	664	MTU 7-2		
		G	N40				
		G	N45	FOR _	E_COUNT	ER[0]=0	TO 3600
		G	N50				
		G	N55	61	X=_E_CO	UNTERIØ)]/20 Y=SIN(_E_COUNTER[0]/10)*70
		G	N60	ENDFO	R		
		→	N65	RAPID	Z5		
		END		Progr	am end		N=1

Example of loop programming (sine path)





- In the machining plan of a sequential control program, position the cursor on the program block after which you want to insert a G code block.
- Press the "Input" key.
- Enter the G code commands or comments.
 The comment must always start with a semicolon (;).

The newly created G code block is marked with a "G" in front of the block number in the machining plan.

Р	NS SHOPMILL
G	N10 ;Program with G-Code
G	N15 F200 S900 T1 D2 M3
G	N20 G0 X100 Y100
G	N25 G1 X150
G	N30 Y120
G	N35 X100
G	N40 Y100
G	N45 G0 X0 Y0
END	N50 Program end

G code in sequential control program

- **.**



3

Programming with G Code

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4.1 Creating a G code program

G code

program

New

₽		If you do not want to program with the ShopMill functions, you can also generate a G code program with G code commands in the ShopMill user interface. You can program a G code command according to DIN 66025. In addition, the parameter screens offer support for measuring and programming contours, drilling and milling cycles. G code is generated from the individual forms, which you can recompile back to the screen forms. The measuring cycle support function must be set up by the machine manufacturer.
		Please refer to the machine manufacturer's instructions.
		For a detailed description of G code commands to DIN 66025, and of cycles and measuring cycles, please refer to: References: /PG/, Programming Guide Fundamentals SINUMERIK 840D/840Di/810D /PGA/, Programming Guide Advanced SINUMERIK 840D/840Di/810D /PGZ/, Cycles Programming Guide SINUMERIK 840D/840Di/810D /BNM/, User Manual Measuring Cycles SINUMERIK 840D/840Di/810D
		You can call up context-sensitive help, if you require more information on particular G code commands or cycle parameters on the PCU 50.
		For a detailed description of the online help, please refer to:References:/BAD/,Operator's Guide HMI Advanced SINUMERIK 840D/840Di/810D
,	Creating a G code program	
	NC Pro-	Press the "Program" softkey.
	y gram	Select the directory in which you want to create a new program.

- > Press the "New" and "G code program" softkeys.
- Enter a program name.
 Program names may be a maximum of 24 characters in length.
 You can use any letters, digits or the underscore symbol (_).
 ShopMill automatically replaces lower case with upper case.





Create contour



> Press the "OK" softkey or the "Input" key.

The G code editor is opened.

- > Enter the desired G code commands.
- Select the "Continue" and "Tools" softkeys if you want to select a tool from the tool list.

-and-

> Place the cursor on the tool that you want to use for machining.

-and-

> Press the "To program" softkey.

The selected tool is loaded into the G code editor. Text such as the following is displayed at the current cursor position in the G code editor: T="MILL"

Unlike sequential control programming, the settings made in the tool management do not become active automatically when the tool is called.

This means that you must also program the tool change (M6), the direction of spindle rotation (M3/M4), the spindle speed (S...), the coolant (M7/M8) and any other tool-specific functions required.

Example:

• • •	
T="MILL"	;Call tool
M6	;Change tool
M7 M3 S2000	;Deactivate coolant and spindle

- Use the softkeys to select whether you want support for programming contours, drilling or milling cycles.
- > Select the cycle you want via the softkey.
- > Enter the parameters.
- Press the "OK" softkey.

The cycle is transferred to the editor as G code.

Programming with G Code Creating a G code program 4.1

📝 Edit	

Measuring cycle support

Position the cursor on a cycle in the G code editor if you want to display the associated parameter screen form again.

Select the "Recompile" softkey.

The parameter screen for the selected cycle appears.

Select the "Edit" softkey if you want to go directly back to the G code editor from a parameter screen form.

- Switch to the extended horizontal softkey bar. \geq
- Press the "Measure mill" softkey.
- Select the required measuring cycle via the softkey.
- \geq Enter the parameters.
- Press the "OK" softkey. ≻

The measuring cycle is transferred to the editor as G code.

- Position the cursor on a measuring cycle in the G code editor, if you want to display the associated parameter screen form again.
- Select the "Recompile" softkey.

The parameter screen for the selected measuring cycle appears.

Select the "Edit" softkey if you want to return directly to the G code editor from a parameter screen form.

- > Place the cursor on a G code command in the G code editor or on an input field in a cycle support parameter screen form.
- Press the "Help" key.

The relevant help screen is displayed.





Measure mill

Calibr. probe

OK



Recompile



4.2 Running a G code program



During execution of a program, the workpiece is machined in accordance with the programming on the machine.

After the program is started in automatic mode, workpiece machining is performed automatically. You can, however, stop the program at any time and then resume execution later.

Execution of the program can be simulated graphically on the screen to enable you to check the programming result without moving the machine axes.

For more information about simulation, see Sec. "Simulation".

The following requirements must be met before executing a program on the machine:

- The measuring system of the control is synchronized with the machine.
- A program created in G code is available.
- The necessary tool offsets and work offsets have been entered.
- The necessary safety interlocks implemented by the machine manufacturer are activated.

When executing a G code program, the same functions are available as for executing a sequential control program (see Sec. "Machining a workpiece").



Simulating a G code program

Pro-	PROGRAM
gram	MANAGER







- > Press the "Program" softkey or the "Program Manager" key.
- > Position the cursor on the desired G code program.
- > Press the "Input" or "Cursor right" key.

The program is opened in the G code editor.

> Press the "Simulation" softkey.

Execution of the program will be displayed in full on the screen in graphical form.

Select the "Edit" softkey if you want to return directly to the G code editor from the simulation screen.

Running a G code		
program		
PROGRAM MANAGER	۶	Press the "Program" softkey or the "Program Manager" key.
	-an	d-
	\triangleright	Position the cursor on the desired G code program.
	-an	d-
Execute		Press the "Execute" softkey.
	-or-	
Ex- ecute		Press the "Execute" softkey if you are in the "Program" operating area.
	Sho anc	ppMill automatically changes to "Machine Auto" operating mode I loads the G code program.
\bigcirc	۶	Press the "Cycle Start" key.
Cycle Start	Eve	ocution of the C code program starts on the machine

Execution of the G code program starts on the machine.

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4.3 G code editor





You use the G code editor when you want to change the sequence of program blocks within a G code program, delete program blocks or copy program blocks from one program to another.

When you want to change G code in a program that you are currently executing, you can only change the G code blocks that have not yet been executed. These blocks are highlighted.

The following functions are available in the G code editor:

- Select
 - You can select any G code.
- Copy/paste You can copy and paste G code within a program or between different programs.
- Cut

You can cut and therefore delete any G code. However, the G code remains in the buffer, so you can still paste it in somewhere else.

Search/replace

In a G code program, you can search for a specific character string and replace it with a different one.

To start/end

You can jump easily to the start or end of the G code program.

• Number

If you insert a new or copied G code block between two existing G code blocks, ShopMill automatically assigns a new block number. This block number may be higher than the one in the following block. The "Renumber" function is used to renumber the G code blocks in ascending order.

Programming with G Code **4.3 G code editor**

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. ,		The G code editor will be opened automatically if you write or open a G code program.	
	Selecting G code		
		Place the cursor at the position in the program where you want your selection to start.	
	Mark	Press the "Mark" softkey.	
		Place the cursor at the position in the program where you want your selection to end.	
		The G code is selected.	
	Copying G code	opying G code	
		Select the G code that you want to copy.	
	Сору	Press the "Copy" softkey.	
		The G code is stored in buffer memory and remains there even if you switch to another program.	
	Pasting G code		
		Copy the G code that you want to insert.	
	Insert	Press the "Insert" softkey.	
		The copied G code is pasted from buffer memory into the text in front of the cursor.	
	Cutting G code		
		Select the G code that you want to cut.	
	Cut	Press the "Cut" softkey.	
		The selected G code is removed and stored in buffer memory.	
10.04

Finding G code Press the "Search" softkey. Search \succ > A new vertical softkey bar appears. Enter the character string that you want to locate. \geq Press the "OK" softkey. \geq DK The G code program is searched for the character string in the forward direction. The character string is marked in the editor by the cursor. Press the "Find next" softkey if you want to continue the search. \geq Continue search The next character string found is displayed. Finding and replacing G code Press the "Search" softkey. Search \triangleright A new vertical softkey bar appears. Press the "Search/Replace" softkey. Search/ \geq Replace Enter the character string that you want to find and the characters ⋟ that you want to insert in its place. Press the "OK" softkey. \geq DK The G code program is searched for the character string in the forward direction. The character string is marked in the editor by the cursor. Press the "Replace all" softkey if you want to replace the \geq Replace all character string throughout the entire G code program. -or-Press the "Find next" softkey if you want to continue the search \geq Find next without replacing the instance of the character string found.

-or-

Press the "Replace" softkey if you want to replace the character string at this point in the G code program.

Replace

Jumping to start/end



Renumber the G code blocks

Continue	Re-	
>	number	>



- > Select the "Continue" and "To start" or "To end" softkeys.
- The beginning or end of the G code program is displayed.
- > Select the "Continue" and "Renumber" softkeys.
- Enter the number of the first block and the increment between block numbers (e.g. 1, 5, 10).
- > Press the "Accept" softkey.

The blocks are renumbered.

You can cancel the numbering again by entering 0 for the increment or block number.



4.4 Arithmetic variables



Arithmetic variables (R variables) are variables that you can use within a G code program. G code programs can read and write the variables. You can assign a

Input and deletion of variables can be disabled via the keyswitch.



Displaying R variables

Vos -or-	OFFSET
R vari.	

Press the "Tools WOs" softkey or the "Offset" key.

value in the R variable list to variables that can be read.

Press the "R vari." softkey.

The R variable list is opened.

Finding R variables

Editing R variables

Search >



Press the "Search" softkey.

- > Enter the number of the variable you want to find.
- Press the "Accept" softkey.

The variable is displayed.

- Place the cursor on the input field of the variable that you want to change.
 - > Enter the new value.

The new value of the variables is applied immediately.

Deleting R variables

HACKSPACE

- Place the cursor on the input field of the variable whose value you want to delete.
- Press the "Backspace" key.

The value of the variable is deleted.



ISO dialects 4.5



If ISO dialects are set up in ShopMill, you can also create and run ISO dialect programs.

Please refer to the machine manufacturer's instructions.

ISO dialect programs are not programs that were created with SIEMENS G code. See Section "Creating a G code program".

5

Simulation

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5.1 General information

	ShopMill provides various extensive and detailed simulation functions for displaying machining paths.
	Please refer to the machine manufacturer's instructions.
Standard simulation	To simulate the machining process, the control system completely calculates the currently selected program and displays the result in graphical form.
	You can select the following modes of representation for simulation:
	Plan view3-plane viewVolume model
	The simulation function displays tools and workpiece contours in their correct proportions. Cylindrical die-sinking cutters, bevel cutters, bevel cutters with corner rounding and tapered die-sinking cutters are displayed as end milling tools.
	The traverse paths for the tools are shown in color: Red line = tool is moving at rapid traverse Green line = tool is moving at machining feedrate
	In all views, a clock is displayed during graphical processing. The displayed machining time (in hours/minutes/seconds) indicates the approximate time that would actually be required to execute the machining program on the machine (incl. tool change). If a program is interrupted during simultaneous recording the clock stops.
	In addition, the current axis coordinates and the program block that is currently executing are also displayed. The active tool with the cutting edge number and feedrate are also displayed in the simulation.
Transformations	 Transformations are displayed differently during simulation and simultaneous recording: Coordinate transformations (translation, scaling,) are displayed as programmed. Cylinder surface transformations are displayed as a developed surface. After swivel transformation, the previous machining operations are deleted from the display and only machining of the swiveled plane is displayed (viewing angle perpendicular to the swiveled plane). Work offset (G54,) do not alter the zero in the graphical display. With multiple clampings, machining of all the separate workpieces is drawn superimposed.

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51		If you want to display a different portion of the workpiece from the one defined in ShopMill, you can define a new blank in the program (see Sec. "Changing program settings").
	Quick display for mold making	Quick display of traverse paths is possible for large part programs. In this quick dashed-line drawing view, all programmed positions (even those resulting from work offsets) are shown as axis paths resulting from G1.
		Please refer to the machine manufacturer's instructions.
FI		Quick display for mold making is only available for the PCU 50.

5.2 Starting/stopping a program in standard simulation

Start simulation

Preconditio	on	Th	e required
		٠	sequential
		•	G Code Pr
		ha	s been sele
Simu- lation	Standard	۶	Press the
Details	Single Block		Press the execute the

- program
- control program or
- rogram

ected and is in the program editor.

- "Simulation" and "Standard" softkeys.
- "Details" and "Single Block" softkeys, if you wish to he program block by block.

Execution of the program will be displayed on the screen in graphical form. The machine axes do not move.

In the case of sequential control programs, the dimensions of the blank for simulation are taken from the program header.

If a subroutine is called in the program, ShopMill evaluates the program header of the subroutine and uses the blank defined there for graphically displaying the part. The settings from the subroutine header remain effective, even after the subroutine has been executed. If you want to retain the blank used in the main program, delete the data relating to the blank in the subroutine header.

With G code programs, you must specify the dimensions of the blank or the selected viewport yourself.

5-332



settings	With a G code program, select the "Details" and "S softkeys and enter the dimensions of your choice ("Creating a new program; defining a blank").
	These dimensions are stored for simulation of the next program. If you set the "Blank" parameter to "off", the of be deleted.

Feedrate override for simulation must be activated via a machine data

Press the "End" softkey.

The machining plan or programming graphic for the program is displayed again.





10.04



5.3 Representation as a plan view

You can display the workpiece as a plan view by pressing this softkey. A depth display indicates the current depth at which machining is currently taking place.

The rules for depth display in these graphics is: "The deeper, the darker".



Display as a plan view

Plan view

Press the "Plan view" softkey.

A plan view of the current workpiece is displayed. Example of a plan view display of a workpiece:





5.4 Representation as a 3-plane view



The process is represented as a plan view with 2 sections, similar to a technical drawing.

Functions for zooming viewports are provided in the 3-plane view.



Display as a 3-plane view

		_	_
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	=+		-
	ור	П	
	- 11		

> Press the "3-Plane View" softkey.

A 3-plane view of the current workpiece is displayed. Example of a 3-plane view of a workpiece:



Shifting section planes

The cross-hair can be positioned in the plan view to display the section plane in the relevant side view.

To reveal concealed contours, you can shift the section planes to any position you want in the 3-plane display. This way you can make hidden contours visible.

Press a cursor key to move the section plane in the y plane.

-or-



Press a cursor key to move the section plane in the x plane.

-or-

Press the "Page Down" or "Page Up" key to move the section plane in the y plane.



5.5 Enlarging a portion of the display



Functions for displaying a more detailed representation of a workpiece are available

- in the plan view and
- in the 3-plane display.





Zoom

-or-

Auto

Zoom

Back to

original



-or

> Press the "Zoom -" softkey or the "-" key to reduce the viewport.

-or-

Press the "Auto Zoom" softkey to fit the viewport to the size of the window automatically.

-or-

Press the "Back to original" softkey to restore the original size of the viewport.

-or-

> Press a cursor key to move the viewport right, left, up, or down.



5.6 Three-dimensional display

The workpiece is displayed as a volume model. The simulation window displays the current machining status.

You can display concealed contours and views on the volume model by

- changing the position about the vertical axis or
- cutting a section out of the volume model at the desired point.



Press the "Volume model".

The volume model of the current workpiece is displayed. Example of a volume model:





5.6.1 Changing the position of the viewport



You can select different views for viewing the volume module.











Press the "Details" softkey.

-and-

Press this softkey to view the left side of the workpiece from the front.

-or-

Press this softkey to view the right side of the workpiece from the front.

-or-

Press this softkey to view the right side of the workpiece from the back.

-or-

Press this softkey to view the left side of the workpiece from the back.



5.6.2 Cutting a section out of the workpiece

		Ì	Ì	
ſ				



Precondition: You have selected one side of the workpiece.

You can cut a section out of the volume module to obtain certain

Select the "Cut open" softkey.

views.

Shifting section planes

To make concealed contours visible, shift the section planes using the cursor and "Paging" keys (see also Sec. "Representation in 3-plane view") to any position.

The new setting is displayed after a short update time. Example of a section through a volume model:



5.7 Starting/stopping the quick display for mold making

_ , →	Starting simulation	
	Precondition	A part program is selected in the Program Manager.
	Simu- Mold Mak.	Press the "Simulation" and "Mold Making G1 Blocks" softkeys.
	G1 BIOCKS	The program is shown in a two-line portion of the work window header. The first program block is highlighted. Construction of the workpiece graphics starts.
	Progress display	A message line below the visualized workpiece shows the percentage of the total program that is already shown in the graphics.
	Ending simulation	Press the "End" softkey.
П		This takes you back to the Program Manager. Changing operating areas interrupts graphics construction. If you return to the Program Manager operating area, it is resumed.
5.8	Views in the quick displa	У
		You can switch between the 2D- and 3D-views at any time. In the selected view, you can rotate the workpiece in any direction.
	Selecting the 3D view	
	\	Press the "3D-View" softkey.
	Selecting 2D views	
		Press the "X/Y-View" softkey.
		- OR -
	(- OR -
		Press the "Y/Z-View" softkey.
		The workpiece is visualized in the selected view.

5



5.8 Views in the quick display

	Changing the orientation in 3D	You can rotate the graphics in the X, Y, or Z axis direction.
	Details Rotate	Press the "Details" and "Rotate" softkeys.
	Up	Press the "Up" softkey.
		- OR -
	Down	Press the "Down" softkey.
		- OR -
	Left	Press the "Left" softkey.
		- OR -
	Right	Press the "Right" softkey.
		- OR -
	$\blacktriangleright \blacksquare \blacksquare \blacksquare$	Press one of the cursor keys.
	Accept	You can see the result of the rotate command in the coordinate system in the lower left corner.> Press the "Accept" softkey.
		The commands are applied and the visualized workpiece is shown with its new axis orientation.

10.04

5.9 Zooming and panning the workpiece graphics

+

You can adjust the size of the displayed graphics to meet your requirements.



Details	Enlarge Reduce

Enlarge

Details

Autom.

Size

Zooming the view



Press the "Enlarge" softkey or press the "+" key.

The graphics viewport is enlarged.

Reducing the view

-or



-or

Automatic display size

Enlarge

Reduce

> Press the "Details" and "Enlarge Reduce" softkeys.

New softkeys appear on the vertical softkey bar.

Press the "Reduce" softkey or press the "-" key.

The graphics viewport is reduced.

- > Press the "Details" and "Enlarge Reduce" softkeys.
- > Press the "Autom. Size" softkey.

The viewport is fitted to the window size. Automatic resizing takes account of the greatest extent of the workpiece in each axis.



- Press the "Details" and "Pan" softkeys.
- Press the "Up", "Down", "Left", or "Right" softkey.
- OR -
- Press one of the cursor keys.

- OR -

Press the "Center" softkey.

The viewport is panned up, down, left, or right, or aligned in the center of the screen.

Distance measurement 5.10

Measuring distance



It is possible to measure and display the direct path (spatial diagonal)
between to points of the workpiece by marking two points in the
graphics.

	Details	Distance	
	Mark Point A		>
	Mark Point B		~
			Т
			Т
			m
Н			R

- Press the "Details" and "Distance" softkeys.
- Move the cross-hairs to the required position.
- Press the "Mark Point A" softkey to define the first point.
- Position the cursor on the second point and press the "Mark Point B" softkey.

he selected points are marked in the graphics. he distance between the two points is calculated and output in the nessage line below the graphics display. epeat this process if you wish to measure more distances.



5.11 Search function



Selecting a block in the graphics

Details

-and-

Block search



Search



> Press the "Details" and "Search" softkeys.

The mouse changes shape to a cross-hair.

Press the "Up", "Down", "Left", or "Right" softkey to put the crosshairs into the required position and confirm the point with the "Input" key.

- OR -

Press one of the cursor keys to position the cross-hairs and confirm the point with the "Input" key.

- OR -

Position the cross-hairs directly on the required point and press the "Block search" softkey.

The selected point is highlighted in color.

The block associated with the selected point is searched for and shown color-highlighted in the program section above the graphics display.

The **Edit** submenu provides another way of searching for certain blocks.





Simulation 5.12 Editing part program blocks

5.12 Editing part program blocks



During quick display, you are automatically in the G code editor. The program being visualized is open. There are various ways you can edit the part program shown here.

5.12.1 Selecting G blocks



There are various ways you can get to the block to be edited in the opened part program either directly or via a search function.



₽	Searching via a string	
	Edit Search	Press the "Edit " and "Search" softkeys.
		The "Search from cursor position" window opens.Enter a string in the "Search:" input field.
	Search	Press the "Search" softkey.
		The search starts.
		If a matching block is found, it is color-highlighted in the program section.
	Searching via a block number	
	Edit Go to	Press the "Edit " and "Go to" softkeys.
		The "Go to" window opens.
	ОК	 Enter a G block in the "Block number" input field and press the "OK" softkey.
		The search starts.
		If the matching block is found, it is displayed color-highlighted in the program section.
	Jumping to start/end	
	Edit	 Press the "Edit" and "Beginning of program" or "End of program" softkeys.
	Beginning of program End of program	
		The first or last block of the opened part program is displayed color- highlighted in the program section.



Scrolling through the program	
	Place the cursor in the program section.
	Press one of the cursor keys.
	You move up, down, left, or right in the part program.
Stopping a search	You can interrupt a search at any time. ➤ Press the "Abort" softkey.

5.12.2 Editing a G code program



Changing and saving G Yo blocks

Edit

You can edit the selected block and then save it.

- Press the "Edit" softkey.
- > Edit the selected block in the program section.

You are automatically in overwrite mode. - OR -

> Press the "Overwrite" softkey.



Overwrite

The softkey changes to "Insert" You can now insert blocks.

Press the "Save File" softkey.

The changes are applied in the file. The workpiece graphics are redrawn.

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6



File Management

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6.1 Program management with ShopMill

All programs that you have created in ShopMill for machining workpieces are stored in the main NC memory.

You can access these programs at any time via the Program Manager for execution, editing, copying, or renaming. Programs that you no longer require can be deleted to release their storage space.

ShopMill offers several options for exchanging programs and data with other workstations:

- Own hard disk (PCU 50 only)
- RS-232 interface
- Floppy disk drive
- Network connection

The following Sections explain the alternate program management functions as used with PCU 20 or PCU 50.

Find out which PCU your ShopMill system is running on and then read either "Program management with PCU 20" or "Program management with PCU 50".

6.2 Program management with PCU 20

With the ShopMill variant with PCU 20, all programs and data are stored in the NC main memory.

You can exchange data and programs via a RS-232 interface.

It is also possible to display the directory tree for a floppy disk drive or network drive.





Data storage with PCU 20

You will find an overview of all directories and programs in the Program Manager.

DIR	ECTORY						
	Name		Туре	Size	Date/time		
	SHOPMILL		WPD	NCK-Dir.	27.09.2002	10:52	
	TEMP		WPD	NCK-Dir.	27.09.2002	10:52	New
							Rename
							Mark
							Сору
							Paste
							Delete
Fre	e memory	-	-	_	NC: 4	57240	Continue
	NC 🕴	F:/nc_ files	a:				

PCU20 program manager

In the horizontal softkey bar, you can select the storage medium that contains the directories and programs that you want to display. In addition to the "NC" softkey, via which the NC main memory data can be displayed, a further 4 softkeys can also be assigned.

You can display the directories and programs on floppy disks and network drives:

Please refer to the machine manufacturer's instructions.

In the overview, the symbols in the left-hand column have the following meaning:

Directory

Program

Zero point/tool data

The directories and programs are always listed complete with the following information:

Name

The name can be up to 24 characters long. For data transfer to external systems, the name is truncated to 8 characters.

- Type Directory: WPD Program: MPF Zero point/tool data: INI
- Size (in bytes)
- Date/time (of creation or last change)

ShopMill stores the programs that are created internally for calculating the stock removal processes in the "TEMP" directory.

Information about memory allocation in the NC is displayed above the horizontal softkey bar.



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Opening a directory



- Press the "Program" softkey or the "Program Manager" key.
 The directory overview is displayed.
- > Select the storage medium using the softkey.
- > Place the cursor on the directory that you want to open.
- > Press the "Input" or "Cursor right" key.

All the programs in this directory are displayed.

Returning to the next highest directory level

-or



€

÷

INPUT

-> INPUT

Press the "Cursor left" key with the cursor in any line.

-or-

> Place the cursor on the Return line.

-and-

> Press the "Input" or "Cursor left" key.

The next highest directory level is displayed.

6.2.1 Opening a program

Pro

gram



To view a program in more detail or modify it, you must display the machining plan for the program.

> Press the "Program" softkey.

The directory overview is displayed.

- Place the cursor on the program that you want to open.
- > Press the "Input" or "Cursor right" key.

The selected program is opened in the "Program" operating area. The machining plan of the program is displayed.



6.2.2 Executing a program



6.2.3 Multiple clamping

You can select any program that is stored in your system at any time to machine workpieces automatically.

- > Open the Program Manager.
- > Place the cursor on the program that you want to execute.
- > Press the "Execute" softkey.

ShopMill now switches to "Machine Auto" operating mode and uploads the program.

> Then press the "Cycle Start" key.

Workpiece machining is initiated (see also Sec. "Automatic mode".)

If the program is already open in the "Program" operating area, press the "Execute" softkey to load the program in "Machine Auto" mode. Then start machining of the workpiece by pressing the "Cycle Start" key.

The "Multiple clamping" function provides optimized tool change over several workpiece clampings. This shortens idle times because a tool performs all machining operations in all clampings before the next tool change is initiated.

You can use not only the surface clampings but also the "multiple clamping" function for rotating fixture plates. For this, the machine must have an additional rotary axis (e.g. A-axis) or a dividing unit. Please refer to the machine manufacturer's instructions.

You can machine not only identical but also different workpieces with this function.

The "Multiple clamping for different programs" function is a software option.

ShopMill automatically generates a single program out of several programs. The tool sequence within a program remains unchanged. Cycles and subroutines are not opened, position patterns are processed as closed units.

The individual programs must meet the following requirements:

- Only sequential control programs (not G code programs)
- Programs must be executable
- Program for the 1st clamping must have been trial run
- No markers/repetitions, i.e. no branches in the program
- No inch/metric switchover
- No work offsets
- No coordinate transformation (translation, scaling, etc.)
- Contours must have unique names, i.e. the same contour name must not be called in several different programs.
- The "Starting point" parameter must not be set to "manual" in the stock removal cycle (contour milling).
- No modal settings, i.e. settings that are effective for all subsequent program blocks (only with multiple clamping for different programs)
- Max. of 50 contours per clamping
- Max. of 49 clampings

You can substitute subroutines for the markers or repetitions which may not be included in programs for multiple clampings.

- > Open the Program Manager.
- > Press the "Continue" and "Multiple clamping" softkeys.
- Specify the number of clampings and the number of the first work offset to be used.

The clampings are processed in ascending sequence from the start work offset. The work offsets are defined in the "Tools/Work Offsets" menu (see Sec. "Work offsets").

> Enter a name for the new, global program (XYZ.MPF).



Ì	Pro gra	— (9M
	Continue >	Multiple clamping

6

ОК	Press the "OK" softkey.
	A list is displayed in which the different programs must be assigned to the work offsets. Not all work offsets, i.e. clampings, must be assigned to programs, but at least two.
Program	Press the "Program selection" softkey.
Selection	The program overview is displayed.
	Place the cursor on the required program.
ОК	Press the "OK" softkey.
	The program is included in the assignment list.
	Repeat this process until a program is assigned to every required work offset.
On all clampings	 If you wish to execute the same program on all clampings, select "On all clampings" softkey. You can assign different programs to individual work offsets first, and then assign one program to the remaining work offsets by selecting the "On all clampings" softkey.
Delete all selection	Press the "Delete selection" or "Delete all" softkey if you want to clear individual or all programs from the assignment list.
Calculate program	Press the "Calculate program" softkey when the assignment list is complete.
	This optimizes the tool changes. The global program is then renumbered. The number of the current clamping is specified every time the program switches from one clamping to another. Apart from the global program (XYZ.MPF), the file XYZ_MCD.INI is also set up in which the assignment between work offsets and programs is stored. Both programs are stored in the directory that was previously selected in the Program Manager.
	If you switch from the assignment list (without "Abort" or "Create program") to another function and then call the "Multiple clamping"

function later on, the same assignment list is displayed again.

6.2.4 Running a G code program from floppy disk or network drive



If the capacity of your NC main memory is already stretched, you can also execute G code programs from a floppy disk or network drive. The entire G code program is not loaded into NC main memory before it is executed, but only the first part of it. Subsequent program blocks are then continuously reloaded as the first part is executed.

The G code program remains stored on the floppy disk/network drive when executed from there.

You cannot execute sequential control programs from floppy disk/network drive.

- > Open the Program Manager.
- > Select the floppy disk/network drive via the appropriate softkey.
- Place the cursor on the directory that contains the G code program you want to execute.
- > Press the "Input" or "Cursor right" key.

The directory opens.

- > Place the cursor on the G code program you want to execute.
- > Select the "Continue" and "Exec. from hard disk" softkeys.

ShopMill switches to "Machine Auto" mode and uploads the G code program.

Press the "Cycle Start" key.

Workpiece machining is initiated (see also Sec. "Automatic mode"). The program contents are loaded continuously to the NC main memory while the program is being processed.



6.2.5 Creating a directory/program

Creating a directory



Open the Program Manager. \geq

purpose in a directory.

ShopMill").

you to use.

- Press the "New" and "Directory" softkeys. \geq
- DK
- \geq Enter a new directory name.
- Press the "OK" softkey. \geq

The new directory is created.

Creating a program





G code program

- \geq Open the Program Manager.
- > Place the cursor on the directory in which you want to create a new program.

Directory structures help you to manage your program and data transparently. You can create any number of subdirectories for this

You can also create programs in a subdirectory/directory and then create program blocks for the program (see Sec. "Programming with

The new program will be automatically stored in NC main memory for

- Press the "Input" or "Cursor right" key. \geq
- Press the "New" softkey. \geq
- Now press the "ShopMill program" softkey if you want to create a \triangleright ShopMill program. (See Sec. "Programming with ShopMill")

-or-

Press the "G code program" softkey if you want to create a G code program (See Sec. "Programming with G code")

10.04



6.2.6 Selecting multiple programs



You can mark several programs individually or in a block for subsequent copying, deleting, etc.



Selecting several programs as a block





> Open the Program Manager.

- > Place the cursor on the first program that you want to select.
- Press the "Mark" softkey.
- Expand the program selection area by pressing the cursor up or down key.

The entire block of programs is marked.

Selecting several programs individually

P B

> Open the Program Manager.

Press the "Select" key.

۶

> Place the cursor on the first program that you want to select.



- Move the cursor to the next program that you want to select.
- > Press the "Select" key again.

The individually selected programs are marked.



6.2.7 Copying/renaming a directory or program



To create a new directory or program that is similar to an existing program, you can save time by copying the old directory or program and only changing selected programs or program blocks. You can also use the copy and insert capabilities for directories and

programs to exchange data with other ShopMill systems via diskette or the network drive.

You can also rename directories or programs.

It is not possible to rename a program when it is loaded in "Machine Auto" mode at the same time.



Copying a directory/program



DK

DK

- Open the Program Manager.
- Place the cursor on the directory/program that you want to copy.
- Press the "Copy" softkey. \geq
- Select the directory level in which you want to insert your copied \geq directory/program.
- Press the "Insert" softkey.

The copied directory/program is inserted in the selected directory level. If a directory/program of the same name already exists in the directory level, a prompt asks whether you want to overwrite or insert it under a different name.

Press the "OK" softkey if you want to overwrite the directory/ \triangleright program.

-or-

Enter another name if you want to insert the program/directory \geq under another name.

-and-

Press the "OK" softkey.





10.04



6.2.8 Deleting a directory/program

		Delete programs or directories from time to time that you are no longer using to maintain the clarity of your data management system and to release NC main memory. Back up this data beforehand on an external data medium if necessary (see Sec. "Importing/exporting a program via the RS-232 interface").
=?		Please note that when you delete a directory, all programs, tool data and zero point data and subdirectories that this directory contains are deleted.
H		If you want to release space in NC main memory, delete the contents of the "TEMP" directory. ShopMill stores the programs that are created internally for calculating the stock removal processes in this directory.
\$**	Delete	 > Open the Program Manager. > Place the cursor on the directory/program that you want to delete. > Press the "Delete" and "OK" softkeys. The selected directory or program is deleted.



6.2.9 Running a program via the RS-232 interface



You can execute programs stored on external data media directly via the RS-232 interface, i.e. it is not necessary to read in these programs before you can machine a workpiece with them.

If a program needs more memory space for execution than is available in the NC main memory, for example, the program contents are continuously loaded via the RS-232 interface.

The RS-232 interface of the control and the external data medium must be compatible, i.e. you must make the same settings for each RS-232 interface.

- > Open the Program Manager.
- > Select the "Continue" and "Execute RS-232" softkeys.
- > Press the "RS-232 settings" softkey to set up the interface.
- Enter the desired settings.
- Press the "Back" softkey.

The settings for the interface are saved.

- On the partner system, select the program that you want to execute.
- > Start the transfer on the partner system.
- Press "Start" softkey.

ShopMill switches to "Machine Auto" mode and uploads part of the program.



> Then press the "Cycle Start" key.

Workpiece machining is initiated (see also Sec. "Automatic mode"). The program contents are loaded continuously to the NC main memory while the program is being processed. When the program has been executed via the RS-232 interface, the program remains stored on the external medium.
6.2.10 Importing/exporting a program via the RS-232 interface



been exported and the number of bytes transferred.

- > Press the "Stop" softkey if you want to interrupt data transfer.
- > Then press the "Start" softkey again to restart data transfer.

Importing a program

NC Pro	o- am
Continue >	Read in
RS-232 settings	



Start

Stop

Open the Program Manager.

- > Select the "Continue" and "Read in" softkeys.
- > Press the "RS-232 settings" softkey to set up the interface.
- Enter the desired settings.
- Press the "Back" softkey.

The settings for the interface are saved.

- On the partner system, select the programs that you want to read in.
- > Start the transfer on the partner system.
- Press "Start" softkey.

The "Read in" window displays the name of the program that has just been read in and the number of bytes transferred. The program is stored in the directory specified in the program header.

- > Press the "Stop" softkey if you want to interrupt data transfer.
- > Then press the "Start" softkey again to restart data transfer.



6.2.11 Displaying the error log



6.2.12 Backing up/importing tool or zero point data



Apart from programs, you can also save tool data and zero point settings.

You can use this function, for example, to save the tool and zero point data for a specific sequential control program. If you want to execute this program at a later point in time, you will then have quick access to the relevant settings.

Even tool data that you have measured on an external tool setting station can be copied easily into the tool management system using this option. For further details, see:

References: /FBSP/, Description of Functions ShopMill



You can choose which data you want to back up:

- Tool data
- Magazine loading
- Zero points
- Basic zero point

You can also specify the amount of data to be backed up:

- Complete tool list or all zero points
- All tool data or zero points used in the program

You can only read out the magazine assignments if your system provides support for loading and unloading tool data to and from the tool-holding magazine (see Sec. "Loading/unloading tools").



File Management 6.2 Program management with PCU 20



Saving data

Pro- gram





- Open the Program Manager.
- Place the cursor on the program whose tool and zero point data you wish to back up.
- Select the "Continue" and "Back up data" softkeys.
- Select the data you want to back up.
- Change the suggested name if you want to. The name of the originally selected program with extension "..._TMZ" will be suggested as a name for your tool or zero point file.
- Press the "OK" softkey.

The tool/zero point data will be set up in the same directory in which the selected program is stored.

If a tool/zero point file with the specified name already exists, this will now be overwritten with the new data.

Importing data







- > Open the Program Manager.
- Place the cursor on the tool/zero point data backup that you wish to re-import.
- > Select the "Execute" softkey or the "Input" key.

The window "Read in backup data" is opened.

- Select the data (tool offset data, magazine loading data, zero point data, basic work offsets) that you wish to import.
- Press the "OK" softkey.

The data are read in.

Depending on which data you have selected, ShopMill will behave as follows:

All tool offset data

All data in the tool management system is deleted first. The backup data is then read in.

All tool offset data used in the program

If at least one of the tools to be read in already exists in the tool management system, you can choose between the following options.

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Replace

none

Yes

Select the "Replace all" softkey to import all tool data. Any existing tools will now be overwritten without a warning prompt.

-or-

Select the "Replace none" softkey if you want to cancel the data import.

-or-



Select the "No" softkey if you want to keep the old tool. If the old tool is not at the saved magazine location, it is relocated there.

-or-

> Select the "Yes" softkey if you want to overwrite the old tool.

With the tool management option without loading/unloading, the old tool is deleted; the old tool is unloaded beforehand in the variant with loading/unloading.

If you change the tool name before importing it with "Yes", the tool will be added as an extra tool to the tool list.

Work offsets

Existing work offsets are always overwritten when new offsets are imported.

Magazine loading

If magazine loading data are not imported at the same time, tools are entered without location number in the tool list.



6.3 Program management with PCU 50

The ShopMill variant with PCU 50 has its own hard disk in addition to the NC main memory. This makes it possible to store all programs that are not currently required in the NC on the hard disk.

Display of the directory management of a floppy disk or network drive and programs is also possible, as are the import and export of data via an RS-232 interface.



Data storage with PCU 50

You will find an overview of all directories and programs in the Program Manager.

DIR	ECTORY							
	Name		Type L	.oaded	Size	Date/time		
	SHOPMILL		WPD	x	NCK-Dir.	27.09.2002	10:52	
	ТЕМР		WPD	x	NCK-Dir.	27.09.2002	10:52	New
								Rename
								Mark
								Сору
								Paste
								Cut
Fre	e memory		Hard d	isk :	1.2 GBytes	NC: 4	57240	Continue
		:/nc_ Files	a:					

PCU 50 program manager

In the horizontal softkey bar, you can select the storage medium that contains the directories and programs that you want to display. In addition to the "NC" softkey, via which the data in the NC main memory and the data management directories on the hard disk can be displayed, a further 4 softkeys can also be assigned.



You can display the directories and programs of the following storage media:

- Network drives (network card necessary)
- Floppy disk drive
- The hard disk as archive directory.

Please refer to the machine manufacturer's instructions.

In the overview, the symbols in the left-hand column have the following meaning:

Directory

Program

Zero point/tool data

The directories and programs are always listed complete with the following information:

• Name

The name can be up to 24 characters long. For data transfer to external systems, the name is truncated to 8 characters.

- Type
 - Directory: WPD
 - Program: MPF

Zero point/tool data: INI

• Loaded

A cross in the "Loaded" column indicates whether the program is still in NC main memory (X) or whether it has been read out to hard disk ().

- Size (in bytes)
- Date/time (of creation or last change)

ShopMill stores the programs that are created internally for calculating the stock removal processes in the "TEMP" directory.

Information about memory allocation on the hard disk and in the NC is displayed above the horizontal softkey bar.





6.3.1 Opening a program





To view a program in more detail or modify it, you must display the machining plan for the program.

Press the "Program" softkey.

The directory overview is displayed.

- Place the cursor on the program that you want to open.
- > Press the "Input" or "Cursor right" key.

The selected program is opened in the "Program" operating area. The machining plan of the program is displayed.

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6.3.2 Executing a program









You can select any program that is stored in your system at any time to machine workpieces automatically.

- > Open the Program Manager.
- > Place the cursor on the program that you want to execute.
- > Press the "Execute" softkey.

ShopMill now switches to "Machine Auto" operating mode and uploads the program.

> Then press the "Cycle Start" key.

Workpiece machining is initiated (see also Sec. "Automatic mode".)

If the program is already open in the "Program" operating area, press the "Execute" softkey to load the program in "Machine Auto" mode. Then start machining of the workpiece by pressing the "Cycle Start" key. The "Multiple clamping" function provides optimized tool change over several workpiece clampings. This shortens idle times because a tool performs all machining operations in all clampings before the next tool change is initiated.

You can use not only the surface clampings but also the "multiple clamping" function for rotating fixture plates. For this, the machine must have an additional rotary axis (e.g. A-axis) or a dividing unit.

Please refer to the machine manufacturer's instructions.

You can machine not only identical but also different workpieces with this function.

The "Multiple clamping for different programs" function is a software option.

ShopMill automatically generates a single program out of several programs. The tool sequence within a program remains unchanged. Cycles and subroutines are not opened, position patterns are processed as closed units.

The individual programs must meet the following requirements:

- Only sequential control programs (not G code programs)
- Programs must be executable
- Program for the 1st clamping must have been trial run
- No markers/repetitions, i.e. no branches in the program
- No inch/metric switchover
- No work offsets
- No coordinate transformation (translation, scaling, etc.)
- Contours must have unique names, i.e. the same contour name must not be called in several different programs.
- The "Starting point" parameter must not be set to "manual" in the stock removal cycle (contour milling).
- No modal settings, i.e. settings that are effective for all subsequent program blocks (only with multiple clamping for different programs)
- Max. of 50 contours per clamping
- Max. of 99 clampings

6

Π		You can substitute subroutines for the markers or repetitions which may not be included in programs for multiple clampings.
	Pro- gram	 Open the Program Manager.
	Continue Multiple clamping	Press the "Continue" and "Multiple clamping" softkeys.
		 Specify the number of clampings and the number of the first work offset to be used. The clampings are processed in ascending sequence from the start work offset. The work offsets are defined in the "Tools/Work Offsets" menu (see Sec. "Work offsets").
		Enter a name for the new, global program (XYZ.MPF).
	ОК	Press the "OK" softkey.
		A list is displayed in which the different programs must be assigned to the work offsets. Not all work offsets, i.e. clampings, must be assigned to programs, but at least two.
	Program selection	Press the "Program selection" softkey.
		The program overview is displayed.
		Place the cursor on the required program.
		Press the "OK" softkey.
		The program is included in the assignment list.
		Repeat this process until a program is assigned to every required work offset.
	On all clampings	 If you wish to execute the same program on all clampings, select "On all clampings" softkey. You can assign different programs to individual work offsets first, and then assign one program to the remaining work offsets by selecting the "On all clampings" softkey.
	Delete Delete all selection	Press the "Delete selection" or "Delete all" softkey if you want to clear individual or all programs from the assignment list.
	Calculate program	Press the "Calculate program" softkey when the assignment list is complete.
		This optimizes the tool changes.

The global program is then renumbered. The number of the current clamping is specified every time the program switches from one clamping to another.

Apart from the global program (XYZ.MPF), the file XYZ_MCD.INI is also set up in which the assignment between work offsets and programs is stored. Both programs are stored in the directory that was previously selected in the Program Manager. If you switch from the assignment list (without "Abort" or "Create

program") to another function and then call the "Multiple clamping" function later on, the same assignment list is displayed again.

6.3.4 Loading/unloading a program





If you do not want to execute a program in the near future, you can unload it from NC main memory. The program is then stored on hard disk and NC main memory is free again.

As soon as you execute a program that was stored on hard disk, it is loaded into NC main memory again.

You can, however, also load one or more sequential control programs in the NC main memory memory without executing them immediately.

Programs that are in "Machine Auto" mode cannot be unloaded from NC main memory to the hard disk.



Unloading a program





- Open the Program Manager.
- Place the cursor on the program that you want to unload from NC main memory.
- > Press the "Continue" and "Manual Unload" softkeys.

The selected program is no longer marked with an "**X**" in the "Loaded" column.

In the line in which the available memory space is displayed, you can see that NC main memory has become free again.



	Loading a program	
	Pro- gram	Open the Program Manager.
		 Place the cursor on the program that you want to load into NC main memory.
Contir	Continue Load	Press the "Continue" and "Load manual" softkeys.
	mundui	The selected program is now marked with an " X " in the "Loaded" column.

6.3.5 Executing a G code program from the hard disk, floppy disk or network drive



If the capacity of your NC main memory is already stretched, you can also execute G code programs from the hard disk or a floppy disk or network drive.

The entire G code program is not loaded into NC main memory before it is executed, but only the first part of it. Subsequent program blocks are then continuously reloaded as the first part is executed.

The G code program remains stored on the hard disk or floppy disk/network drive when executed from there.

You cannot execute sequential control programs from hard disk or floppy disk/network drive.



Running a G code program from the hard disk







- > Open the Program Manager.
- Place the cursor on the directory that contains the G code program that you want to execute from hard disk.
- > Press the "Input" or "Cursor right" key.

The program overview is displayed.

- Place the cursor on the G code program that you want to execute from hard disk (without "X").
- > Select the "Continue" and "Exec. from hard disk" softkeys.

ShopMill switches to "Machine Auto" mode and uploads the G code program.

Running a G code program from floppy disk or network drive

Exec. from

hard disk



- > Open the Program Manager.
- > Select the floppy disk/network drive via the appropriate softkey.
- Place the cursor on the directory that contains the G code program you want to execute.
- > Press the "Input" or "Cursor right" key.

The directory opens.

- > Place the cursor on the G code program you want to execute.
- > Select the "Continue" and "Exec. from hard disk" softkeys.

ShopMill switches to "Machine Auto" mode and uploads the G code program.



Continue

>

> Press the "Cycle Start" key.

Workpiece machining is initiated (see also Sec. "Automatic mode"). The program contents are loaded continuously to the NC main memory while the program is being processed.



6.3.6 Creating a directory/program



Directory structures help you to manage your program and data transparently. You can create any number of subdirectories for this purpose in a directory.

You can also create programs in a subdirectory/directory and then create program blocks for the program (see Sec. "Programming with ShopMill").

The new program will be automatically stored in NC main memory for you to use.



Creating a directory





Creating a program









- > Open the Program Manager.
- > Press the "New" and "Directory" softkeys.
- > Enter a new directory name.
- Press the "OK" softkey.

The new directory is created.

- > Open the Program Manager.
- Place the cursor on the directory in which you want to create a new program.
- > Press the "Input" or "Cursor right" key.
- > Press the "New" softkey.
- Now press the "ShopMill program" softkey if you want to create a ShopMill program.
 (See Sec. "Programming with ShopMill")

-or-

Press the "G code program" softkey if you want to create a G code program
 (See Sec. "Programming with G code")



 \geq

6.3.7 Selecting multiple programs



Selecting several programs as a block





Selecting several programs individually



Open the Program Manager. \geq

The entire block of programs is marked.

subsequent copying, deleting, etc.

Open the Program Manager.

Press the "Mark" softkey.

down key.

Place the cursor on the first program that you want to select. \geq

You can select several programs individually or in a block for

> Place the cursor on the first program that you want to select.

> Expand the program selection area by pressing the cursor up or

- Press the "Select" key. \geq
- Move the cursor to the next program that you want to select. \geq
- \triangleright Press the "Select" key again.

The individually selected programs are marked.



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6.3.8 Copying/renaming/moving directories/programs



To create a new directory or program that is similar to an existing program, you can save time by copying the old directory or program and only changing selected programs or program blocks. You can also move directories or programs or rename them. You can also use the copy, cut and insert capabilities for directories and programs to exchange data with other ShopMill systems via diskette or the network drive.

It is not possible to rename a program when it is loaded in "Machine Auto" mode at the same time.

- > Open the Program Manager.
- > Place the cursor on the directory/program that you want to copy.
- Press the "Copy" softkey.
- Select the directory level in which you want to insert your copied directory/program.
- Press the "Insert" softkey.

The copied directory/program is inserted in the selected directory level. If a directory/program of the same name already exists in the directory level, a prompt asks whether you want to overwrite or insert it under a different name.

Press the "OK" softkey if you want to overwrite the directory/program.

-or-

Enter another name if you want to insert the program/directory under another name.

-and-

Press the "OK" softkey.

Renaming a



- Place the cursor on the directory/program that you want to
- Press the "Rename" softkey.
- Enter the name of the new directory or program in the "To:" field. The name must be unique, i.e. two directories or programs are not permitted to have the same name.

The directory/program is renamed.

- Open the Program Manager.
- Place the cursor on the directory/program that you want to move.
- Press the "Cut" softkey and then the "OK" softkey.

The selected directory/program is deleted at this point and stored in

> Select the directory level in which you want to insert the

The directory/program is moved to the selected directory level. If a directory/program of the same name already exists in this directory level, a prompt asks whether you want to overwrite or insert

- Press the "OK" softkey if you want to overwrite the
- Enter another name if you want to insert the program/directory



6.3.9 Deleting a directory/program



Delete programs or directories from time to time that you are no longer using to maintain a clearer overview of your data management. Back up this data beforehand on an external data medium if necessary (see Sec. "Importing/exporting a program via the RS-232 interface").

Please note that when you delete a directory, all programs, tool data and zero point data and subdirectories that this directory contains are deleted.

If you want to release space in NC main memory, delete the contents of the "TEMP" directory. ShopMill stores the programs that are created internally for calculating the stock removal processes in this directory.

- > Open the Program Manager.
- > Place the cursor on the directory/program that you want to delete.
- Press the "Cut" and "OK" softkeys.

The selected directory or program is deleted.



6.3.10 Importing/exporting a program via the RS-232 interface

	Programs can be exchanged with other ShopMill stations via an external data storage system through the RS-232 interface. The data read out function can also be used to export data that is not currently required to release NC main memory or hard disk space. You can re-import the exported programs as they are needed.
=?	When you import or export a program into/out of ShopMill, all ShopMill subroutines are transferred with it. It is also possible to import or export more than one program in the same operation.
	The RS-232 interface of the control and the external data medium must be compatible, i.e. you must make the same settings for each RS-232 interface.
6	Make sure that you set the correct file format (binary/PC, punched tape or punched tape/ISO format) on reading out. Otherwise the partner system will not be able to interpret the data.
Exporting a program	
NC Pro- gram	 Open the Program Manager.
	Place the cursor on the program that you want to export.
Continue Read out	Select the "Continue" and "Read out" softkeys.
RS-232 settings	Press the "RS-232 settings" softkey to set up the interface.
	 Enter the desired settings.
Back	Press the "Back" softkey.
	The settings for the interface are saved.
All files	Press the "All files" softkey if you want to read out all the programs displayed.
	 Start the transfer on the partner system.
Start	 Press "Start" softkey.
	The selected program and all its ShopMill subroutines are read out.



Stop	Th be	e "Read en read
	۶	Press
	۶	Then p
Importing a program		
Pro- gram	۶	Open t
Continue Read in	۶	Select
RS-232 settings	۶	Press
	۶	Enter t
K Back	≻	Press
Duok	Th	e setting
	>	On the in.
	≻	Start th
Start		Press
	Th be sto	e "Read en read ored in th
Stop	۶	Press

he "Readout" window displays the name of the program that has just een read out and the number of bytes transferred.

- Press the "Stop" softkey if you want to interrupt data transfer.
- Then press the "Start" softkey again to restart data transfer.
- Open the Program Manager.
- Select the "Continue" and "Read in" softkeys.
- Press the "RS-232 settings" softkey to set up the interface.
- Enter the desired settings.
- Press the "Back" softkey.

The settings for the interface are saved.

- On the partner system, select the programs that you want to read in.
- Start the transfer on the partner system.
- Press "Start" softkey.

The "Read in" window displays the name of the program that has just been read in and the number of bytes transferred. The program is stored in the directory specified in the program header.

- > Press the "Stop" softkey if you want to interrupt data transfer.
- > Then press the "Start" softkey again to restart data transfer.





If errors occur during data transfer via the RS-232 interface, ShopMill records them in an error log.

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- > Open the Program Manager.
- > Press the "Continue" softkey.
- > Press the "Read out" or "Read in" softkey.
- > Then press the "Error log" softkey.

The data transfer log is displayed.

6.3.12 Backing up/importing tool or zero point data

Apart from programs, you can also save tool data and zero point settings.
You can use this function, for example, to save the tool and zero point data for a specific sequential control program. If you want to execute this program at a later point in time, you will then have quick access to the relevant settings.
Even tool data that you have measured on an external tool setting station can be copied easily into the tool management system using this option. For further details, see:
References: /FBSP/, Description of Functions ShopMill
You can choose which data you want to back up:
Tool data
Magazine loading

Zero pointsBasic zero point

You can also specify the amount of data to be backed up:

- Complete tool list or all zero points
- All tool data or zero points used in the program

You can only read out the magazine assignments if your system provides support for loading and unloading tool data to and from the tool-holding magazine (see Sec. "Loading/unloading tools").





- > Open the Program Manager.
- Place the cursor on the program whose tool and zero point data you wish to back up.
- > Select the "Continue" and "Back Up Data" softkeys.
- Select the data you want to back up.
- Change the suggested name if you want to. The name of the originally selected program with extension "..._TMZ" will be suggested as a name for your tool or zero point file.
- Press the "OK" softkey.

The tool/zero point data will be set up in the same directory in which the selected program is stored.

If a tool/zero point file with the specified name already exists, this will now be overwritten with the new data.

- > Open the Program Manager.
- Place the cursor on the tool/zero point data backup that you wish to re-import.
- > Select the "Execute" softkey or the "Input" key.

The window "Read in backup data" is opened.

- Select the data (tool offset data, magazine loading data, zero point data, basic work offsets) that you wish to read in.
- Press the "OK" softkey.

The data are read in.

Depending on which data you have selected, ShopMill will behave as follows:

All tool offset data

All data in the tool management system is deleted first. The backup data is then read in.

All tool offset data used in the program

If at least one of the tools to be read in already exists in the tool management system, you can choose between the following options.



-or-

Select the "Replace none" softkey if you want to cancel the data import.

-or-

Select the "No" softkey if you want to keep the old tool. If the old tool is not at the saved magazine location, it is relocated there.

-or-

Select the "Yes" softkey if you want to overwrite the old tool.

With the tool management option without loading/unloading, the old tool is deleted; the old tool is unloaded beforehand in the variant with loading/unloading.

If you change the tool name before importing it with "Yes", the tool will be added as an extra tool to the tool list.

Work offsets

Existing work offsets are always overwritten when new offsets are imported.

Magazine loading

If magazine loading data are not imported at the same time, tools are entered in the tool list without a location number.

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Replace all



Yes

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Mold Making

10.04

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7.1 Requirements

		This chapter only describes special aspects of mold making with ShopMill. A detailed description of the ShopMill functions is given in the previous chapters.
		ShopMill can process not only sequential control programs but also G code mold-making programs. The precondition for this is optimization of the drives.
		Please refer to the machine manufacturer's instructions.
		Depending on the machine type, 3-axis mold making applications and also dynamic 5-axis machining operations can be performed. You can also use the functions integrated into ShopMill to set up the machine, such as determining the zero of the workpiece or measuring tools for mold making programs.
	Program structure and storage	To achieve optimum velocity control for your mold-making programs, you should split the mold-making program into a central technology program and a separate geometry program rather than creating a single complete program.
		 Technology program The technology program contains basic settings such as work offset, tool call-up, feed values, spindle speed, and control commands for velocity control. The technology program also calls the geometry programs as subroutines. You can create the technology program in ShopMill's G code editor. Geometry program
		The geometry programs of each type of operation (roughing, rough-finishing, and finishing) contain only the geometry values of the free-form surface to be machined.The geometry programs are created on an external CAM system in the form of G01 blocks.
		Depending on the application, the size of geometry programs ranges from 500 KB to 100 MB. Programs of this size can no longer be processed directly in the NC RAM. This means that the geometry programs must be saved either on the hard drive of the PCU 50 or on a Compact Flash card in the PCU 20. Storage on a network drive is only recommended if there is a point-to-point connection between the control and the server because only then is uninterrupted data transmission ensured.
		Storage on hard disk or compact flash card are preferable.



Program structure technology program with geometry programs

• Complete program

Complete programs contain both the basic settings, such as work offset, tool call, etc. and the geometry values of the free-form surfaces to be machined. However, programming optimum velocity control is very complicated in a complete program. Complete programs are also created on external CAM systems. Because of their size, the complete programs are stored on the hard disk of the PCU 50 or on the compact flash card of the PCU 20.

Storage on a network drive is also only recommended for a pointto-point connection between the control and server.



Program structure complete program



Data transferIf you want to copy a geometry program or complete program from a
network drive to the control, you must always use an Ethernet
connection. The data transfer rate of the serial interface (RS232,
V.24) is too low for the transfer of very large part programs.

7.2 Setting up the machine

7.2.1 Measuring the tool

The CAM system already takes the tool geometry into account when the geometry program is created. The tool path calculated refers either to the tool tip or the tool center. This means that, to determine the length of the tool, you must user the same reference point as the CAM system (tool tip or tool center).

If you use a ShopMill function to measure your tools, the tool length refers to the tool tip. On the other hand, if the tool center is taken into account in calculation of the tool path in the CAM system, you must subtract the radius of the tool from the tool length in the tool list.

Entry of the tool diameter in the tool list is not relevant to the processing of mold-making programs. However, you should still enter the tool diameter in the tool list for information.



7.3



7.3.1 Creating a program

For the technology program, you create a new G code program in the program manager and then process it in the G code editor. A sequential control program is not suitable for use as a technology program.

The geometry program or complete program is created on an external CAM system. For example, if you subsequently want to insert comments into the geometry program or change the tool name in the complete program, this can be done in ShopMill's G code editor.

7.3.2 Programming a tool

If you program a tool in the technology program, please note the following:

The geometry of the programmed tool must match the tool geometry used by the CAM system when the geometry program was created.

7.3.3 Programming the "High Speed Settings" cycle

Machining of free-form surfaces involves high velocity, precision, and surface quality requirements .

You can achieve optimum velocity control depending on the type of processing (roughing, rough-finishing, finishing) very simply with the "High Speed Settings" cycle.

You can call the cycle via the cycle support in the G code editor. The output tolerance of the postprocessor of the CAM system is usually entered in the "Tolerance" parameter.

Program the cycle before the geometry program call in the technology program.

More information on the cycle can be found in:

References: /PGZ/, Cycles Programming Guide SINUMERIK 840D/840Di/810D



7.3.4 Subroutine call

	The geometry program is called from the technology program as a subroutine. Because the geometry programs are not stored in the NC working memory but on the hard disk of the PCU 50 or on the compact flash card of the PCU 20 or on a network drive, you only have to call the subroutine with the G code command "EXTCALL".
PCU 50	The technology program and the geometry programs are in the same directory as the hard disk. EXTCALL "Geometry program"
	Example: EXTCALL "ROUGHING"
PCU 20	 The program syntax varies slightly depending on the storage location of the geometry program on the compact flash card. The geometry program is directly on the compact flash card. EXTCALL ("C:\Geometry_program.mpf") Example: EXTCALL ("C:\Roughing.mpf") The geometry program is in a directory on the compact flash card. EXTCALL ("C:\Directory\Geometry_program.mpf") Example: EXTCALL ("C:\Mold\Roughing.mpf")
Network drive	If the geometry program is on a network drive connected via the Ethernet, the program syntax is as follows.
	Example: EXTCALL ("H:\Mold\Roughing.mpf")





7.4.1 Selecting a program for execution

The technology program that is located in the NC working memory is selected for execution just like a normal G code program. The geometry program is then automatically selected via the G code command "EXTCALL".

A complete program, which is located either on the hard disk or the PCU 50 or on the compact flash card of the PCU 20 or on a network drive, is selected with the "Execute HD" sofkey in the program manager.

Processing via the V.24 interface on the PCU 20 is not recommended due to the low data transfer speed.

7.4.2 Starting execution at a specific point in the program

Technology program with geometry programs	To start execution of a certain program section in a geometry program, enter the destination in the search pointer. Level 1 (technology program): Program line with required geometry program call Level 2 (geometry program): Program line for starting machining
	If the geometry program is on the compact flash card, you must not only specify the program name in the "Program" input field on level 2 but also the path. The path for the compact flash card is always "C:\", i.e. you enter the following in the input field: C:\Program_name
	Select the accelerated calculation method "External – without calculation". The block search is performed in the technology program with calculation. All EXTCALL commands before the required geometry program are skipped. The block search in the required geometry program is performed without calculation.
	This calculation method assumes that all machine functions, such as tool call, machining feedrate, spindle speed, etc. are contained in the technology program. The geometry program must only contain geometry values for the free-form surface.



Complete program	To start execution of a certain program section in a complete program, place the cursor directly on the required destination block (using "Search", if necessary).
	 When you then select a calculation method, consider: The "External without calculation" method performs a search without considering the machine functions. That means execution of the program can only be started a points at which all relevant machine functions, such as feed, spindle speed, etc. are performed. For safety reasons, you should therefore choose the "to contour" or "to end point" method. However, these calculation methods require more computation time.

7.5 Example

Workpiece

Program structure

The task is to machine a mobile phone holder on a 3-axis machine.



Workpiece to be machined

The mold-making program is split into a technology program and a geometry program.

Program	

A3_FINISH_G1	Mark
N1 G54 ¶	
N2 T="BALL_CUTTER_6";Ball-cutter D=6 ¶	
N3 L61	Сору
N4 S14000 M3¶	
N5 G0 C0 A0 ¶	Pacto
NG G1 Z10 F3000 ¶	Faste
N7 X0 Y0 ¶	
N8 M08 ¶	Cut
N11 CYCLE832(0.01,2001)¶	
N13 EXTCALL"FINISH_G1" [
N14 M30¶	Find
==eof==	
	Continue
	Recompile
Edit Contour Drilling Milling Turning	Ex-

Technology program for the finishing operation



Mold Making 7.5 Example

The "High Speed Settings" cycle is called in the technology program to achieve optimum velocity control.

Program					
High Speed Settings		Toler	anz Bearbe:	i tungsachsen	
	Operation		Finishing		
	Tolerance	_tol		0.010	
×					
	Anpassung		Yes		
	Kompression		Compcad		
	Bahnsteuerung	I .	G642		Abort
	Fdforw. contr	•	FFWOF SOFT		
		_	_		ОК

"High Speed Settings" cycle (CYCLE832)

PROGRAM						
FINISH_G1	1					
	A Mark					
N1 ; VERTICALPARALLELPLANES []						
N2 ;TOOLDIAMETER: 6. ¶	Carry					
N3 ;TOOLCORNERRADIUS: 3. ¶	Сору					
N4 ;TOOLAXIS: 0.¶						
N5 ;OVERTHICKNESS: 0. ¶	Paste					
N6 ;MACHININGTOLERANCE: 0.001 ¶						
N7 ;SWEEPINGDIRECTION: 0.707 ¶						
N8 ;STEPOVERDIRECTION: -0.707 ¶	Cut					
N9 ;SWEEPINGMODE: ZIGZAG ¶						
N10 X99.343 Y-29.966 Z0.284 ¶						
N11 Z-15. ¶	Find					
N12 X99.343Y-29.966Z-25 ¶						
N13 X100.657Y-28.651Z-25 ¶						
N14 X101.218 Y-27.949 ¶						
N15 X98.655 Y-30.512 ¶						
N16 X98.187 Y-30.838 ¶	Continue					
N17 X101.559 Y-27.467 ¶						
N18 X101.572 Y-27.454 ¶						
	✓ Recompile					
Edit Contour Drilling Milling Turning	Simu- lation Ex-					

Geometry program for the finishing operation



Simultaneous recording

During execution of the mold-making program, progress can be observed on screen.



Graphical display of the workpiece




Alarms and Messages

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8.1 Cycle alarms and messages

8.1.1 Error handling in the cycles

If error conditions are detected in the cycles, an alarm is output and processing is aborted.

Alarms with numbers between 61000 and 62999 are output in the cycles.

The reset criteria for these number ranges are

- 61000 ... 61999 is NC-RESET
- 62000 ... 62999 is CANCEL

The text displayed with the alarm number provides an explanation of the cause of the error.

8.1.2 Overview of cycle alarms

The following table lists the alarms that might occur in the cycles with tips on how to remedy the errors that cause them.

Alarm number	Alarm text	Explanation, remedy
61000	"No tool offset active"	D-correction must be programmed before the
		cycle call
61001	"Thread pitch incorrectly defined"	Check parameters for thread size and check
		pitch information (contradict each other)
61002	"Machining type incorrectly	The machining type parameter has been set to
	defined"	the wrong value and needs to be altered.
61003	"No feedrate programmed in cycle'	The parameter for feedrate has been incorrectly
		set and must be altered.
61006	"Tool radius too large"	Select smaller tool
61007	"Tool radius too small"	Select larger tool
61009	"Active tool number = 0"	Load the required tool
61010	"Finishing allowance too large"	Reduce the finishing allowance setting
61011	"Invalid scaling"	The active scaling factor is not permissible for
		this cycle.
61012	"Different scales in one plane"	Cycle execution only possible with uniform
		scaling in the plane
61013	"Basic settings have been altered,	Check and, if necessary, change the basic
	program cannot be executed"	settings
61101	"Reference plane incorrectly	Either different values must be entered for the
	defined"	reference plane and the retraction plane if they
		are relative values or an absolute value must
		be entered for the depth



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61102	"No spindle direction programmed"	A spindle direction must be programmed
61103	"Number of holes is zero"	No value has been programmed for the number
		of holes
61104	"Contour violation of slots"	Errors in parameterization of milling pattern in
		those parameters which define the position of
		slots on a circle and their shape
61105	"Cutter radius too large"	The diameter of the milling cutter being used is
		too large for the figure that is to be machined;
		either a tool with a smaller radius must be used
		or the contour must be changed
61106	"Number or spacing of circle	Parameterization error, programmed circle
	elements"	elements cannot be arranged around a full
		circle
61107	"First drilling depth incorrectly	First drilling depth is inverted in relation to total
	defined"	drilling depth.
61108	"No valid settings for parameters	Parameters "Radius" and "Infeed depth per
	_RAD1 and _DP1"	revolution" must be taken into account for
		insertion along helical path
61109	"Parameter _CDIR incorrectly	Parameter defining milling direction is
	defined"	incorrectly defined
61110	"Finishing allowance on base >	Alter setting for depth infeed, if necessary.
	infeed depth"	
61111	"Infeed width > tool diameter"	The programmed infeed width is greater than
		the diameter of the active tool. The infeed width
		must be reduced.
61112	"Tool radius negative"	The radius of the active tool is negative. This is
		illegal.
61113	"Parameter _CRAD for corner	Reduce the parameter for corner radius
	radius too large"	
61114	"Direction of machining G41/G42	Check the machining direction of tool radius
	incorrectly defined"	compensation left/right and alter.
61115	"Approach or retract mode	An incorrect contour approach or retract mode
	(line/circle/plane/	was defined. Check the approach/retract mode
	space) incorrectly defined"	or approach/retract strategy parameter.
61116	"Approach or retract path = 0"	The approach or retract path is set to zero, it
		must be increased.
61117	"Active tool radius <= 0"	The radius of the active tool is negative or zero.
		This is illegal.
61118	"Length or width = 0"	The length or width of the milling surface is
		illegal.
61119	"Nominal or core diameter	Check thread geometry
	incorrectly programmed"	
61120	"I hread type internal, external not	You must enter the internal, external thread
	aetinea"	type.

61121	"Number of teeth/cutting edge	Enter the number of teeth/cutting edges for the
	missing"	active tool into the tool list.
61122	"Safety clearance in the plane	The safety clearance is negative or zero. This is
	incorrectly defined"	illegal.
61124	"Infeed width is not programmed"	In active simulation without a tool, a value for
		the infeed width must always be pro-
		grammed.
61125	"Technology selection in	Check settings in machine data 9855 and 9856.
	parameter _TECHNO incorrectly	
	defined"	
61126	"Thread length too short"	Check thread geometry.
61127	"Speed ratio of tapping axis	Check settings in machine data 31050 and
	incorrectly defined (machine data)	'31060.
61128	"Insertion angle = 0 for insertion	Use larger insertion angle.
	via oscillation or helix"	
61180	"No name assigned to swivel data	Assign a unique name for the swivel data block.
	block although machine data	
	\$MN_MM_NUM_TOOL_CARRIER	र
	> 1"	
61181	"NCK software version too old	Upgrade NCK software.
	(no TOOLCARRIER functionality)"	
61182	"Name of swivel data record	Check the name of the swivel data block.
	unknown"	
61183	"Retraction mode GUD7 _TC_FR	Check installation and start-up of the swivel
	outside value range 02"	cycle CYCLE800.
61184	"No solution can be found with	Check the angle entered for the swivelling of
	current angle inputs"	the machining plane.
61185	"No or incorrect (min > max)	Check installation and start-up of the swivel
	angle ranges declared for rotary	cycle CYCLE800.
	axes"	
61186	"Invalid rotary axis vectors"	Check installation and start-up of the swivel
		cycle CYCLE800.
61188	"No axis name declared for 1st	Check installation and start-up of the swivel
	rotary axis -> check CYCLE800	cycle CYCLE800.
	start-up"	
61200	"Too many elements in machining	Revise machining block, if necessary deleting
	block"	elements
61201	"Incorrect sequence in machining	Sort the machining block sequence.
	block"	
61202	"Not a technology cycle"	Program technology block.

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61203	"Not a position cycle"	Program positioning block.
61204	"Unknown technology cycle"	Delete and reprogram technology block.
61205	"Unknown position cycle"	Delete and reprogram positioning block.
61210	"Block search element not found"	Repeat block search.
61212	"Incorrect tool type"	Select a new tool type.
61213	"Circle radius too small"	Enter a larger value for the circle radius.
61214	"No pitch programmed"	The pitch must be programmed
61215	"Blank dimension incorrectly	Check dimensions of blank spigot. The blank
	programmed"	spigot must be larger than the finished spigot.
61216	"Feed/tooth possible only for	Alternatively, you can set another feed type
	milling tools"	
61217	"Cutting rate programmed for tool	Enter a cutting rate setting.
	radius 0"	
61218	"Feed/tooth programmed, but	Enter the number of teeth of the cutting tool in
	number of teeth is zero"	the "Tool list" menu.
61222	"Plane infeed greater than tool	Reduce plane infeed.
	diameter"	
61223	"Approach path too small"	Enter a larger value for the approach path.
61224	"Retract path too small"	Enter a larger value for the retract path.
61225	"Swiveling data block unknown"	An attempt was made to access a swivel data
		block which has not been defined.
61226	"Swivel head cannot be replaced"	The parameter "Swivel data block" is set to
		"No". In spite of this, an attempt has been made
		to change the swivel head.
61230	"Tool probe diameter too small"	The tool probe is not correctly calibrated.
61231	"Sequential control program	The program has to be simulated first in
	cannot be executed; not yet tested	ShopMill or loaded into the operating mode
	by ShopMill"	"Machine auto" by ShopMill.
61232	"Magazine tool cannot be loaded"	Only manual tools may be loaded into a swivel
		head in which the tools can only be manually
		loaded.
61234	"ShopMill subroutine cannot be	The subroutine has to be simulated first in
	executed; not yet tested by	ShopMill or loaded into the ShopMill operating
01001	ShopMill	mode "Machine auto".
61301	"Probe is not responding"	Check probe connection
		Set a longer measuring distance via
		MD 9752, 9753, 9754, 9755
		• For edge measurements: Position probe
		closer to edge
		Ear spigate/balas: Position roughly over the
		middle

61302	"Probe collision"	The measuring probe collided with an obstacle
		when being positioned.
		 Check spigot diameter (it may be too
		small)
		Check measuring path (it may be too long)
61303	"Safe area exceeded"	Measuring result deviates greatly from specified
		value for the spigot/hole diameter.
		Check radius or diameter.
		Check measuring location (e.g. for inaccuracies
		caused by swarf)
61308	Check measuring path 2a	Measuring path = 0 entered
		Check MD 9752, 9753, 9754, 9755
61309	Check probe type	Probe type: 3D probe not active
61310	Scaling factor is active	Scaling factor = scaling is active
61311	No D number is active	No tool offset for the measuring probe (for
		workpiece measurement) or no tool offset for
		the active tool (for tool measurement) is
		selected.
61316	Center point and radius cannot be	It is not possible to calculate a circle from the
	calculated	measured points.
61332	Alter the tool tip position	Tool tip is positioned below the probe surface
		(e.g. with a setting ring gauge or cube)
61338	Positioning speed is zero	Set corresponding feedrate (plane/infeed rate)
		via MD 9757 or 9758
61605	"Contour incorrectly programmed"	Check the contour.
61610	"No infeed depth programmed"	The infeed depth must be programmed
62100	"No drilling cycle active"	No modal drilling cycle has been called before
		the drilling pattern cycle.
62101	"Milling direction incorrect - G3 will	Climb or conventional milling programmed.
	be generated"	However the spindle was not rotating when the
		cycle was called.
62103	"No finishing allowance	Program a finishing allowance.
	programmed"	
61275	"Destination point violates	Swiveling has placed the destination point
	software limit switch!"	outside the software limit switch.
		You may have to choose a different preferred
		direction for swiveling or place the retraction
		plane lower.
62180	"Set rotary axes "	Prompt to position rotary axes manually.

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62181	"Set rotary axis "	Prompt to position rotary axis manually.
62182	"Attach inclinable head:"	Request to load a swivel head.
62183	"Remove inclinable head:"	Prompt to remove inclinable head.
62184	"Replace inclinable head:"	Prompt to replace inclinable head.
62185	"Angle adjusted to angular grid:"	Indication that the desired angle cannot be set
		due to the Hirth tooth system. The displayed
		angle is set instead.

8.1.3 Messages in the cycles

The cycles output messages in the dialog line of the control. These messages do not interrupt execution.

They provide information about specific cycle behavior and how machining is progressing and are usually displayed for the duration of the machining operation or until the end of the cycle.

8.2 Alarms in ShopMill

8.2.1 Overview of alarms

If errors are detected in ShopMill, the system generates an alarm and aborts program execution, if necessary.

The text displayed with the alarm number provides an explanation of the cause of the error.

Overview of alarms	100000-100999	Basic system	
	101000-101999	Diagnostics	
	102000-102999	Services	
	103000-103999	Machine	
	104000-104999	Parameters	
	105000-105999	Programming	
	106000-106999	Spare	
	107000-107999	OEM	
	110000-110999		reserved
	111000-112999	ShopMill	
	120000-120999		reserved

Warning

Please check the situation in the plant on the basis of the description of the active alarm(s). Eliminate the cause/s of the alarm/s and acknowledge it/them as instructed. Failure to observe this warning will place your machine, workpiece, stored settings and possibly even your own safety at risk.

If you are working in CNC ISO mode, please refer to alarm descriptions in the following manual: **References:** /DA/, Diagnostics Guide SINUMERIK 840D/840E

References: /DA/, Diagnostics Guide SINUMERIK 840D/840Di/ 810D

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8.2.2 Selecting the alarm/message overview

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ALARM



Function

You can view alarms and messages and then acknowledge them.

Operating sequence

The alarm/message overview displays all active alarms and messages with numbers, date, cancel criterion and explanation. Clear the alarm by pressing the key that is displayed as a symbol:

Switch machine/control off and on again (main switch) or NCK Power ON

Press the "Reset" key

Press the "Alarm cancel" key

Alarm is canceled with "Cycle Start"

Alarm is canceled with the "Return" key



Alarm

list



8.2.3 Description of the alarms

112100	Renumbering error. Initial state restored.
Explanation	You have selected the "Renumber" softkey in the program editor. An error during renumbering has damaged the program in the memory. The initial program must now be reloaded to the memory.
Response	Alarm display
	Program has not been renumbered.
Remedy	Create space in the memory, e.g. by deleting an old program. Select "Renumber" softkey again.
112200	Contour is step in current program sequence. Processing not enabled
Explanation	The selected contour is an element of the program loaded under "Program".
Response	Alarm display
	The contour is an element from a loaded program and cannot be deleted or renamed.
Remedy	Remove contour from the loaded program.
112201	Contour is step in current Automatic sequence. Processing not enabled
Explanation	The selected contour is an element of the program loaded under
	"Machine Auto".
Response	Alarm display
	The contour is an element of a program loaded under "Machine Auto" and cannot be deleted or renamed. After program start, contours included in the current program cannot be altered under "Program" while the program is running.
Remedy	Stop program run and load program under "Program". Delete contour from program.

112210	Tool axis cannot be reselected. Insufficient NC memory.
Explanation	If you select another tool axis, you must generate a new NC program. You must save the old NC program first and then generate the new one. There is not sufficient NC memory available at this point to store
	the new program.
Response	Alarm display
	The new tool axis selection is not implemented.
Remedy	You must create free space in the NC memory corresponding to at
	least the space required by the new program (e.g. by deleting
	programs you no longer need).
112211	System unable to process tool preselection. Insufficient NC memory.
Explanation	Before a tool preselection can be processed, you must generate a new NC program. You must save the old NC program first and then generate the new one. There is not sufficient NC memory available at this point to store the new program.
Response	Alarm display
	The system does not process the preselected tool.
Remedy	You must create free space in the NC memory corresponding to at
	least the space required by the new program (e.g. by deleting
	programs you no longer need).
112300	Tool management strategy 2 impossible.
	Magazine is not fully loaded
Explanation	The magazine is not fully loaded with tools. In the magazine of tool
	management type 2, the number of tools specified in machine data
	18082 has to be created.
Response	Power ON alarm
Remedy	Start-up: Set up correct selection of tools
112301	Tool management strategy 2 impossible.
	Magazine is not sorted according to tool list
Explanation	The magazine list is not sorted according to the tool list. The tools in the magazine of tool management concept 2 must be ordered according to T number.
Response	Power ON alarm
Remedy	Start-up: Define tools in magazine locations according to T number.

112320	Detach manual tool: %n%1
Explanation Response	The operator is prompted to detach the specified manual tool. Alarm display
Remedy	Please refer to the machine manufacturer's instructions. Detach manual tool.
,	Please refer to the machine manufacturer's instructions.
112321	Attach manual tool: %n%1
Explanation	The operator is prompted to attach the specified manual tool.
Response	Please refer to the machine manufacturer's instructions. Alarm display
Remedy	Please refer to the machine manufacturer's instructions. Attach manual tool.
	Please refer to the machine manufacturer's instructions.
112322	Replace manual tool: %n%1 -> %2
Explanation	The operator is prompted to replace the specified manual tool with the new manual tool.
Response	Alam usplay
Remedy	Replace manual tool.
	Please refer to the machine manufacturer's instructions.
112323	Unload swivel head
Explanation	The operator is prompted to remove the specified swivel head from the spindle.
Response	Alarm display
	Please refer to the machine manufacturer's instructions.
Remedy	Replace swivel head.
	Please refer to the machine manufacturer's instructions.
112324	Load swivel head
Explanation	The operator is prompted to load the specified swivel head into the spindle.
Коронас	Please refer to the machine manufacturer's instructions
Bomody	
Remeuy	Please refer to the machine manufacturer's instructions

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112325	Replace swivel head
Explanation	The operator is prompted to replace the specified swivel head in the spindle with the new swivel head.
Response	Alarm display
	Please refer to the machine manufacturer's instructions.
Remedy	Exchange swivel head.
	Please refer to the machine manufacturer's instructions.
440000	Set owivel head
112320 Explanation	The energies is prompted to get the swivel head in apportance with
	the specified data
Response	Alarm display
	Please refer to the machine manufacturer's instructions.
Remedy	Set swivel head.
	Please refer to the machine manufacturer's instructions.
112327	Angle outside the permissible range
Explanation	The programmed machining operation cannot be performed with the inclinable head.
Response	Alarm display
Remedy	Perform NC reset.
	Clamp the workpiece differently if appropriate.
112328	Angle adapted to angle grid
Explanation	Due to the angle grid, the swivel head could not be set exactly to the
	specified angle.
Response	Alarm display
Remedy	Machining can be continued with the specified values, but it will not
	correspond exactly to the programming.
112329	Set swivel head/table
Explanation	The operator is prompted to set the swivel head/table in accordance
	with the specified data.
Response	Alarm display
	Please refer to the machine manufacturer's instructions.
Remedy	Set swivel head/table.
	Please refer to the machine manufacturer's instructions.

112330	Set swivel table				
Explanation	The operator is prompted to set the swivel table in accordance with				
	the specified data.				
Response	Alarm display				
	Please refer to the machine manufacturer's instructions.				
Remedy	Set swivel table.				
	Please refer to the machine manufacturer's instructions.				
112340	Confirmation not possible because axes are not referenced!				
Explanation	User confirmation in Safety Integrated cannot be given until the				
	reference point has been approached.				
Response	Alarm display				
Remedy	Approach reference point.				
112350	No swiveling data available				
Explanation	No swiveling data sets are available.				
Response	Alarm display				
Remedy	Set up the necessary swiveling data sets				
······,	(see /FBSP/, ShopMill Description of Functions)				
112360	Step was not included in program chain because program is				
	running				
Explanation	The program that you want to change is currently being executed in				
	"Machine Auto" mode. You cannot change programs when they are				
	being executed in "Machine Auto" mode.				
Response	Alarm display				
Remedy	End program execution in "Machine Auto" mode.				
112400	Does not exist in tool management				
Explanation	The tool specified in the program does not exist.				
Response	Alarm display				
Remedy	The tool must be created before the data backup.				
112401	Could not create tool				
Explanation	A tool could not be created when reading in tool data.				
Response	Alarm display				
Remedy	Check the tool management system.				
112402	Work offsets: Error when writing				
Explanation	Data was not written into the work offset.				
Response	Alarm display				
Remedy	Check work offset.				

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112420	Error on inch/metric changeover! Check all data!
Explanation	Data conversion not completed for inch/metric changeover.
Response	Alarm display
	NC Start disable
Remedy	Check the following data:
	Display machine data:
	MD9655: \$MM_CMM_CYC_PECKING_DIST
	MD9656: \$MM_CMM_CYC_DRILL_RELEASE_DIST
	MD9658: \$MM_CMM_CYC_MIN_COUNT_PO_TO_RAD
	MD9664: \$MM_CMM_MAX_INP_FEED_P_MIN
	MD9665: \$MM_CMM_MAX_INP_FEED_P_ROT
	MD9666: \$MM_CMM_MAX_INP_FEED_P_TOOTH
	MD9670: \$MM_CMM_START_RAD_CONTOUR_POCKET
	MD9752: \$MM_CMM_MEASURING_DISTANCE
	MD9753. \$MM_CMM_MEAS_DIST_MAN
	MD9755: \$MM_CMM_MEAS_DIST_TOOL_LENGTT
	MD9756: \$MM_CMM_MEASURING_FEED
	MD9757: \$MM_CMM_FEED_WITH_COLL_CTRL
	MD9758: \$MM_CMM_POS_FEED_WITH_COLL_CTRL
	MD9759: \$MM_CMM_MAX_CIRC_SPEED_ROT_SP
	MD9761: \$MM_CMM_MIN_FEED_ROT_SP
	MD9762: \$MM_CMM_MEAS_TOL_ROT_SP
	MD9765: \$MM_CMM_T_PROBE_DIAM_LENGTH_MEAS
	MD9766: \$MM_CMM_T_PROBE_DIAM_RAD_MEAS
	MD9767: \$MM_CMM_T_PROBE_DIST_RAD_MEAS
	MD10240: \$MN_SCALING_SYSTEM_IS_METRIC
	MD20150 [12]: \$MC_GCODE_RESET_VALUES
	• Tool data for various edges D.
	Length Z, radius R,
	wear lengths Z and R
	• Work offsets:
	Base offset
	Position in X, Y, Z and A, C (if available)
	Work offset
	 Settings in MANUAL operating mode:
	Retraction plane
	Safety clearance
Note	This alarm is only output on a hardware fault.
112500	Error in the NC interpreter % module %1
Explanation	The ShopMill program cannot be opened.
Response	Alarm displayed
	interpreter stopped
Remedy	Please note the error text and contact the Siemens A&D MC Hotline.

112502	Not enough memory
	Program aborted in line %1
Explanation	%1 = Line number
	Program contains too many program blocks
Response	Alarm display
	Program not loaded
Remedy	Modify program in operating area PROGRAMS CNC-ISO operator interface.
112503	ShopMill XXXX
Explanation	A system error has occurred.
Response	Alarm display
Remedy	Please note the error text and contact the Siemens A&D MC Hotline.
112504	File does not exist or is incorrect: %1
Explanation	%1 = Name of file/contour
	Program cannot interpret a program block with contour programming.
	Contour does not exist in directory.
Response	Alarm display
	NC Start disable
Remedy	Load contour in directory.
112505	Error while trying to interpret contour %1
Explanation	%1 = Name of contour
	Contour incorrect
Response	Alarm display
	NC Start disable
Remedy	Check machining sequence of contour
112506	Maximum number of contour elements exceeded %1
Explanation	%1 = Name of contour
	Max. permissible number of 50 contour elements exceeded during
	interpretation of machining sequence of a contour.
Response	Alarm display
Remedy	Check machining sequence of contour and change if necessary.
112541	Program cannot be interpreted
Explanation	The program cannot be interpreted as a sequential control program during loading, as the program header is missing.
Response	Alarm display NC Start disable
Remedy	_

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112542	GUD variable not available or too small in the field dimension: %1
Explanation	The required GUD variable was not found during read or write access.
Response	Alarm display
Remedy	Include the right GUD variables.
112543	Prog. was created with higher software version
Explanation	The part program was created with a higher software version than the existing software version.
Response	Alarm display
Remedy	Delete the machining operation and, if necessary, program it elsewhere.
112544	Program cannot be opened. It is already being edited.
Explanation	The program is already opened in another editor (e.g. in HMI Advanced).
Response	Alarm display
Remedy	Close the program
112546	Program cannot be opened. No read rights on file.
Explanation	The file has no read rights for the current access level.
Response	Alarm display
Remedy	Set the read rights by means of keyswitch or password entry.
112550	Sequential control programming not opened
Explanation	The "sequential control programming" option has not been set.
Response	Alarm display
	The program is opened as G code.
Remedy	Buy option.
112604	Connection to PLC broken
Explanation	Acknowledgement to the PLC user program, that the connection with
Doctorio	the PCU has been broken oπ.
Response	ShopMill PLC is shut down
Remedy	Check PLC user program.
112605	Asynchronous subroutine has not been executed
Note	Input values could not be processed correctly by the NC.
Response	Alarm display
Remedy	Perform NC reset.

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112611	NC Start not possible: % Deselect SBL mode
Explanation	A program was activated with block search, while at the same time
Response	NC Start disable
	Interface signals are set
	Alarm display
Remedy	Deselect single block mode.
112650	Unknown PLC error
Explanation	An error unknown to the user interface has been output by the PLC.
Response	Alarm display
	NC Start disable
Remedy	Press Power ON, inform Siemens.

8.3	User data	
		User data are variables that are used internally both by ShopMill programs and G code programs. These user data can be displayed in a list.
=?		 The following types of variables are defined: Global User Data (GUD) Global user data is valid in all programs. The display of global user data (GUD) can be disabled via keyswitch or password.
		 Local User Data (LUD) Local User Data is only valid in the program or subroutine in which it was defined. When executing the program, ShopMill displays the LUD between the current block and the end of the program. If you press the "Cycle Stop" key, the LUD list is updated. The values, however, are continuously updated.
		 Global Program User Data (PUD) Global program user data is created from the local variables (LUD) defined in the main program. PUD is valid in all subroutines, where it can also be read and written. The local data is also displayed with the global program user data.
		Channel-specific user data Channel-specific user data is only applicable in one channel.
		ShopMill does not display user data of type AXIS and FRAME.
		For details of which variables ShopMill displays, please refer to the machine manufacturer's instructions.
	Displaying user data	



- > Press the "Tools WOs" softkey or the "Offset" key.
- Press the "Expansion" key.
- > Press the "User data" softkey.
- Activate one of the softkeys to choose the user data that you want to display.

Alarms and Messages 8.4 Version display



PCU 20: cmm.dll..... V xx.yy.zz

Examples

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9)

9.1 Example 1: Machining with rectang./circ. pocket and circumf. slot

Program Part_4

- 1. Program header
- Define the blank:
- **X0** 0 abs **Y0** 0 abs **Z0** 0 abs **X1** 180 abs Y1 180 abs **Z1** -20 abs
- Press the Accept softkey.
- 2. Face milling
- Mill-ing Face milling > Select via the softkeys and choose a • machining strategy

180

Example of technological data: T FACING TOOL F 0.1 mm/tooth **V** 1200 m/min Machining Roughing X0 0 abs Y0 0 abs **Z**0 1 abs X1 180 abs Y1 180 abs

10.04 Examples 9.1 Example 1: Machining with rectang./circ. pocket and circumf. slot



	Z1 DXY DZ UZ • Press the Accept	0 abs 80 % 0.5 0 softkey.
 Outside contour of workpiece 	The outside contour car here . It is, of course, als	a be defined as a rectangular spigot as shown so possible to use the contour milling function.
	 Select via the Assign technological the following parameters 	parameters T, F and S accordingly and enter eters:
	Position of	Bottom left
	Machining	$\nabla $
	Type of position	✓ Single position
	X0	0 abs
	YO	0 abs
	Z0	0 abs
	W	180 abs
	L	180 abs
	R	10 abs
	al	0 degrees
	71	20 inc
	D7	20
		0
		ů N
	W1	185 (fictitious blank dimension)
	11	185 (fictitious blank dimension)
	Accent	
	Press the	_l softkey.
4. Outside contour of island	To machine the entire s pocket around the blank entire surface area is m	urface outside the island, define a contour and then program the island. In this way, the achined and no residual material is left behind.
a) Outside contour of pocket	 Select via the Enter the contour na 	me (here: Part_4_pocket) and confirm
	 Fill out the start screet Tool axis Z X -20 abs 	en form for the contour Y 0 abs
	and confirm with Acc	ept

	٠	Enter the fo	ollowing contour	elements and co	onfirm each one	by
		pressing the	e Accept so	oftkey:		
		1. ←•→	X 200 abs			
		2.	Y 200 abs			
		3. ←•→	X -20 abs			
		4. Close contour				
	•	Press the	accept softk	ey.		
a) Outside contour of island	•	Select via tl	he Cont .	^{lew} ^{ontour >} softkeys		
	•	Enter the co	ontour name (he	ere: Part_4_Islar	ld) and confirm	
	•	Tool axis Z	start screen form	i for the contour		
		X 90 abs	Y 25 ab	os T		
		and confirm	with Accept	<u>.</u>		
	٠	Enter the fo	ollowing contour	elements and co	onfirm each one	by
		pressing the	e Accept so	oftkey:		
		1. ←•→	X 25 abs	FS 15		
		2.	Y 115 abs	R 20		
		3.	X 15 abs	Y 135 abs		
		4.	Y 155 abs	R 10		
		5.	X 60 abs	R 15		
		6.	Y 135 abs	R 20		
		7.	$\begin{array}{c} \text{Prec. elem.} \\ \textbf{R} & 25 \textbf{X} & 110 \end{array}$	Direction of r	otation 🖸	
		8.	Tangent to prec. elem.			
			Y 155 abs	R 15		
		9. ←•→	R 0			
		10.	X 165 abs	Y 95 abs	α1 290 deg.	R 0
		11.	X 155 abs	α 1 240 deg.	R 28	
		12.	FS 0			

Examples9.1 Example 1: Machining with rectang./circ. pocket and circumf. slot

9

		13. X 140	abs Y	25 abs	α1 225 deg.	R 0
		14. Close Accept				
c) Mill/solid machine a		The contract of the contract o	Solid			
contour	٠	Select via the	111.	> softkeys	S	
	٠	Assign technological	l paramete	ers T, F and S	S accordingly (e	e.g.
		cutter diameter 10) a	and enter	the following	parameters:	
		Machining	\bigtriangledown			
		Z0	0 abs			
		Z1	10 inc.			
		DXY	4.5 mm			
		DZ	10			
		UXY	0 mm			
		UZ	0			
		Start point	Auto			
		Insertion	Center			
		FZ	0.1 mm	/tooth		
		Retraction mode	Select t	he mode, e.g	i. to retraction p	lane
	•	Accept				
	N	otes:				
	٠	When selecting the r	milling too	l, please mak	ke sure that the	tool
		diameter is large end	ough to cu	it the intende	d pocket. A me	ssage
		will be displayed if ye	ou make a	a mistake.		
	٠	If you want to finish o	cut the po	cket, you mu	st assign paran	neters
		UXY and UZ accord	ingly and	add a second	d solid machinir	ig cycle
		for finishing.				
5. Mill a rectangular pocket		Select via the	ill- ing	et Rectang.	softkovs	
(large)	•		nical data			
	•	T MILL 10	F 0 1 m	1m/tooth	V 200 m/min	n
			• • • •		20011/1	I
		Position of	Center			
		reference point				
		Machining		acition		
			00 ahs	JUSILIUTI		
		X0 X0	60 abs			
		Z0	0 ahs			
		W	40			
		L	70			
		R	10			
		α0	15			
		Z1	4 inc.			
		DXY	4.5 mm			

Examples 10.04 9.1 Example 1: Machining with rectang./circ. pocket and circumf. slot

9

6 Mill a rootangular poakat	DZ UXY UZ Insertion EP ER Remove stock	4 0 0 Helical 2 2 Complete machining
(small)	Select via the	ing Pocket > Rectang. pocket softkeys
	• Enter parameters:	
	X0	90 abs
	Y0	60 abs
	Z0	-4 abs
	W	20
	L	35
	R	5
	α 0	15
	Z1	4 inc.
	DXY	4.5 mm
	DZ	2
		0
	UZ	
	FW	10 degrees
	Remove stock	Complete machining
	Accept	
7. Mill a circumferential slot	Select via the	Slot > Circumferential slot Softkeys
	Example of technol	ogical data:
	T MILL8V 150m/min	F0.5mm/tooth FZ 0.02mm/tooth
	Machining Full / pitch circle X0 Y0 Z0 W R R α0	 ▽ Pitch circle 85 abs 135 abs 0 abs 10 40 180 degrees 180 degrees



Note:

If this obstacle cycle is not inserted, the drill will violate the right-hand corner of the island contour. Alternately, you could increase the safety clearance.

9

12.Positions	•	Select via the	Dri.	11- 19	Positions >	\checkmark	softkeys
	٠	Enter paramete	ers:				2
				Rec	tangular		
		Z0		-10 a	abs		
		X2		165	abs		
		Y2		165	abs		
		X3		15 a	ıbs		
		Y3		165	abs		
	•	Accept					
13.Mill a circular pocket	•	Select via the	Mil in	Լ1- ոց	Pocket >	Circular pocket	softkeys
	•	Example of tech	hnolog	ical c	lata:		
		T MILL8		F 0.	.15 mm/1	tooth	V 300 m/min
	٠	Enter paramete	ers:				
		Machining		\bigtriangledown			
		Type of position	on	Sing	le positi	on	
		X0		85 a	ıbs		
		Y0		135	abs		
		Z0		-6 al	bs		
		Diameter		30			
		Z1		15 ir	ιс.		
		DXY		4			
		DZ		5			
		UXY		0 mi	m		
		UZ		0			
		Insertion		Cen	ter		
		FZ		0.1 ı	mm/tootl	า	
		Remove stock		Corr	plete m	achining	
	•	Accept					

Result

• Programming graphics

 10.04
 Examples

 9.1
 Example 1: Machining with rectang./circ. pocket and circumf. slot

9





• ShopMill program representation

TEI	L_4			
Р	NS	TEIL_4		🖃 🖂 🖂 🖃
孛	N10	Face milling 7	7	T=FRAESER60 F0.2/Z S400rev. X0=0 Y0=0
2223	N15	Rectang.spigot 7	7	T=FRAESER60 F0.2/Z S500rev. X0=0 Y0=0
\sim -	N2Ø	TEIL_4_TASCHE		
\sim -	N25	TEIL_4_INSEL		
M -	N30	Solid machin. 🛛 🕅	7	T=FRAESER10 F0.2/Z S300rev. Z0=0
<u>۳</u>	N35	Rectang.pocket 7	7	T=FRAESER10 F0.1/Z S200rev. X0=90 Y0=60
<u>شار</u>	N40	Rectang.pocket 7	7	T=FRAESER10 F0.1/Z S200rev. X0=90 Y0=60
55	N45	Circ.slot 7	7	T=FRAESER8 F0.5/Z S150M X0=85 Y0=135
	N50	Centering		T=ZENTRIERER F300/min S300rev. ø16
777777	N55	DRILL		T=B0HRER10 F0.5/min S200M Z1=-25
Ν-	N6Ø	001: Positions		Z0=-10 X0=15 Y0=15 X1=165 Y1=15
<u>-</u>	N65	Obstacle		Z2
Л-	N70	002: Positions		Z0=-10 X0=15 Y0=15 X1=165 Y1=15 X2=165
O	N75	Circ. pocket 7	7	T=FRAESER8 F0.15/Z S300M X0=85 Y0=135
END	N8Ø	Program end		

9.2 Example 2: Translation and mirroring of a contour



	1. $\leftarrow \bullet \rightarrow$ X 60 abs R 3
	2. X 10 abs Y 40 abs R 3
	3. X 10 abs Y 10 abs R 3
•	Press the Accept softkey.
4. Remove stock	Select via the Cont . Remove stock > softkeys
•	Assign technological parameters T, F and S accordingly (e.g. cutter diameter 3) and enter the following parameters:
	Machining \bigtriangledown
	Z0 0 abs
	Z1 10 inc.
	DXY 1.5 mm
	DZ 2
	UXY 0.5
	UZ 0.5 Start point Auto
	Insertion Center
	FZ 0.1 mm/tooth
	Retraction mode Select the mode, e.g. to retraction plane
	Accept
5. Set end marker for contour	Select via the Mics. Set
	Set end marking with "Marker2"
	Accept
6. Translate	Select via the Mics. Transfor- mations > Offset > softkeys
•	Set the following parameters:
	New/additive New
	X 120
	Y 60
	Z 0
	Accept
7. Mirror	Select via the Mics. Transfor- mations > Mirror > softkeys
•	Set the following parameters:

New/additive Add Х On Υ On Ζ Off Accept 8. Repetition of contour Repetition Mics. Select via the softkeys . Set the following markers: Start marker Marker 1 End marker Marker 2 Number of 1 repetitions Accept Result Programming graphics . TEIL Q-6 58 ∆÷4 ⊿≁⊾ ٥ END 100 50 ť. ShopMill program representation • * NS MARKE1: $\sim_{\sf T}$ N10 TEIL_1_3ECK 🕅 N15 Solid machin. ∇ T=FRAESER3 F0.2/Z S1000rev. Z0=0 * N20 MARKE2: 4→4 N30 Offset X120 Y60 Z0 A→1 N25 Mirroring add XY ≣{ N35 Repetition MARKE1 MARKE2 END Program end

9.3 Example 3: Cylinder surface transformation



X 10 abs Y 0 abs **Z** 50 abs A 0 abs F *rapid traverse* mm/min Radius compensation off Accept Press the softkey. 4. Activate cylinder surface Transfor-Cylinder Mics. mations > surface > Select via the softkeys transformation Enter parameters: Transformation On 80 Ø Slot wall offset Off Accept Press the softkey. 5. Activate the work offset in Define the work offset for the machining operation on the developed the program cylinder surface. Transfor-Work Mics. offset mations > softkeys Select via the Accept Select the required work offset and then press the softkey. 6. Enter contour with contour Cont New mill contour Select via the softkeys calculator Enter the contour name and confirm Fill out the contour start screen form Tool axis Ζ Cylinder surface yes Ø 80 Х Yα 10abs 0 Note: Delete the Y value, then enter the Y α value (in this case 10°). Enter the following contour elements and confirm each one by Accept softkey: pressing the -60 abs 1 Х 2. Yα 90 abs 3. X -45 abs Yα 30 abs 4 5. Х 0 abs Accept Press the softkey.



7. Path milling	Path
	Select via the softkeys
	Enter parameters
	T CUTTER8 F 0.2 mm/tooth S 5000 rev/min
	Radius compensation $\stackrel{ m NO}{ m o}$ Machining \bigtriangledown
	Z0 40 abs Z1 10 inc. DZ 10
	UZ0
	UXY 0
	Approach Straight line
	Depth infeed
	L12
	FZ 0.1 mm/tooth
	Retract Straight line
	Retraction strategy
	Retraction mode To retraction plane
	Press the Accept softkey.
8. Deactivate cylinder	Transfor- Cylinder
surface transformation	 Select via the softkeys
	Enter parameters:
	Transformation Off
	Press the Accept softkey
0 Decult	Des encourses encourses in a
9. Result	Programming graphics
	8 200-
	\diamond
	END
	100-
	e-

• ShopMill program representation

ZYLINDER							
P	NS	ZYLINDER		∍			
e	N10	Zero offset	1 654				
→	N15	RAPID 🛛 X10 Y0 Z50					
6	N20	Cylind.surface	on None Groove wall compensation				
e	N50	Zero offset	2 655				
\sim	N25	ZYLINDER_					
<i>14</i> -	N30	Path milling □ ▽	T=CUTTER_8 F0.2/Z S5000rev. Z0=40				
0	N35	Cylind.surface	off				
END	N40	Program end					
9.4 Example 4: Slot side compensation

A slot with parallel slot sides is milled in a pipe. In this instance, it is not the slot contour that is programmed, but the imaginary center-point path of a bolt inserted in the slot.



Requirements

- There is a rotary axis, e.g. axis A, and the transformation is configured via machine data.
- The reference points on the cylinder are predefined. Program the reference points X0, Y0, Z0 and the required work offset, for example, in "Machine Manual", "Workpiece zero", and "Edge".

	The work offset calculated from these is entered in the work offset list.
Program	
1. Program header	 The blank dimensions correspond to the developed cylinder peripheral surface. X0 0 abs Y0 0 abs Z0 25 abs X1 -130 abs Y1 157.08 abs Z1 22 abs RP 50 SC 1 Note: Y1 is calculated according to equation: Y1 = Ø • π In this case: Diameter 50 multiplied by 3.14 Press the Accept softkey.
2. Activate the work offset in the program	Select work offset for cylinder surface transformation (e.g. offset the zero point on the center point of the cylinder end face).
	 Select via the Mics. Transformations> Work offset > softkeys Select the required work offset and then press the Accept
3. Position the Y axis	 Position the tool in the Y axis over the center of the cylinder. The reason for this is that the Y axis is not traversed after cylinder surface transformation is selected. Select via the Strain Straight line softkeys
	 Enter parameters: X 10 abs Y 0 abs Z 40 abs F *rapid traverse* mm/min Radius compensation off Press the Accept softkey.
 Activate cylinder surface transformation 	 Select via the Mics. Transformations> Cylinder surface > softkeys Enter parameters: Transformation On Ø 50 Slot wall offset On D 6 Note: D is the distance from the imaginary center-point path to the slot wall.
	Press the Accept softkey.

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- 5. Activate the work offset in Define the work offset for the machining operation on the developed cylinder surface (shift zero point to the zero point on the workpiece drawing).
 - Select via the
 Mics.
 Transfor mations>
 Work
 offset > softkeys
 - Select the required work offset and then press the Accept softkey.
- 6. Enter contour with contour calculator
- Select via the **Cont**. New contour softkeys
- Enter the contour name (here: cylinder) and confirm
- Fill out the contour start screen form Tool axis Z Cylinder surface yes Ø 50 X -25 abs Yα 0 al

Ø 50 X -25 abs Y α 0 abs Note: Delete the Y value, then enter the Y α value (in this case 0°).

- Press the Accept softkey.
- Enter the following contour elements and confirm each one by





P		NØ	NUTWAND	
e		N5	Zero offset	1 654
→		N10	RAPID X10 Y0 Z40	
6		N15	Cylind.surface	on wth Groove wall compensation
e		N2Ø	Zero offset	2 655
\sim	٦	N25	NUTWANDKORREKT_1	
<i>14</i> 6	7	N3Ø	Path milling	T=CUTTER_8 F0.2/Z S5000rev. Z0=25
6		N35	Cylind.surface	off
END			Program end	

9.5 Example 5: Swiveling





This example involves multiple swiveling of the machining plane.

Program example 4 1. Program header Define the blank: **X0** 0 abs Y0 0 abs **Z0** 0 abs X1 -50 abs Y1 -50 abs Z1 -50 abs Accept Press the softkey. • 2. Rectangular pocket Mill-Pocket Rectang. ing Select via the pocket softkeys Example of technological data: • T MILL_4 **D** 1 F 0.1 mm/tooth V 200 m/min • Enter the following parameters: Position of Center reference point Machining type Roughing Type of position Single position X0 -25 abs **Y0** -25 abs **Z0** 0 abs W 10 20 L R 2 -45° α0 5 inc. **Z1** DXY 3 mm DZ 2.5 UXY 0 mm UΖ 0 Center Insertion FΖ 0.05 mm/tooth Complete mach. **Remove stock** Accept



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9

 Select via the Example of technol T MILL_4 	Mics. Transfor- mations > Swiveling > softkeys ogical data: D 1
 Enter the following 	parameters:
Retraction Swiveling Transformation X0 Y0 Z0 Swiveling X Y Z X1 Y1 Z1 Direction	Yes Yes New 0 -50 0 Axis by axis 90° 0° 0° 0° 0 0 0
 Select via the Example of technol T MILL_4 Enter the following 	Pocket Rectang. pocket softkeys ogical data: D 1 F 0.1 mm/tooth V 200 m/min parameters: V V V
Position of reference point Machining type Type of position X0 Y0 Z0 W L L R α0 Z1 DXY DZ UXY UZ Insertion	Center Roughing Single position -25 abs -25 abs 0 abs 10 20 2 45° 5 inc. 3 mm 2.5 0 mm 0 Center
	 Select via the Example of technol T MILL_4 Enter the following Retraction Swiveling Transformation X0 Y0 Z0 Swiveling X Y1 Z X1 Y1 Z1 Direction Select via the Example of technol T MILL_4 Select via the Example of technol T MILL_4 Enter the following Position of reference point Machining type Type of position X0 Y0 Z0 W L R α0 Z1 DXY DZ UXY UZ Insertion

5. Swiveling	 Accept Select via the Example of technology T MILL_4 	Mics. Transfor- mations > Swiveling > softkeys ogical data: D 1
	• Enter the following	parameters:
	Retraction Swiveling Transformation X0 Y0 Z0 Swiveling Z X Y X1 Y1 Z1 Direction	Yes Yes New -50 -50 0 Axis by axis -90° 90° 0° 0 0 0
6. Rectangular pocket	 Select via the 	Pocket Rectang. pocket pocket softkeys
	Example of technol	ogical data:
	I MILL_4	D 1 F 0.1 mm/tootn V 200 m/min
	Enter the following Position of reference point	Center
	Machining type	Roughing
	Type of position	Single position
	YO	-25 abs
	Z0	0 abs
	W	10
	L R	20
	α0	-45°
	Z1	5 inc.
	DXY	3 mm
		2.5 0 mm
		0
	Insertion	Center

FΖ

9)

0.05 mm/tooth

		Remove stock	Complete mach.
7.	Setting	 Define a different blank shows the machining of Select via the shark: 	so that the visible section of the simulation the inclined plane: cs. Settings softkeys
		 Define the blank. X0 -17.678 abs X1 17.678 abs Press the Accept Accept 	Y0 10.206 abs Z0 0 abs Y1 -20.413 abs Z1 -10 abs softkey.
8.	Swiveling	 Select via the Example of technolog T FACING TOOL 	cs. Transfor- mations Swiveling > softkeys gical data: D 1
		 Enter the following part of the	arameters: Yes Yes New -50 -50 -25 Axis by axis -45° 54.736° 0° 0 20.413 0
9.	Face milling	 Select via the machining strategy Example of technolog T FACING TOOL 	Ili- ing Face milling > softkeys and choose a gical data: D 1 F 0.1 mm/tooth V 200 m/min
		 Enter the following particular descent states and the	arameters: Roughing -17.678 abs

9)

	Y0	-20.413 abs
	Z 0	14.434 abs
	X1	17.678 abs
	Y1	10.206 abs
	Z1	0 abs
	DXY	80 %
	DZ	2.5
	UZ	0
	Occasit	-
10. Borina	• <u>hccept</u>	Drill- Drilling
	 Select via the 	ing Reaming > Drilling softkeys
	 Example of technologies 	ological data:
	T DRILL 3	D 1 F 0.1 mm/rev S 2000 rev/mir
	 Enter the following 	g parameters:
	Shank/tip	Shank
	Z1	5 inc.
	DT	0 s
	Accent	
	• nccept	
11. Position pattern	 Select via the 	ing > softkeys
	Enter the following	
	Enter the following Eull circle/pitch	Eull circlo
	circlo	Fuil circle
		0 aba
	20	
	X0 X0	
	YU	
	α0	-90°
	R	5
	Ν	3
	Positioning	Straight line
	Accept	
12. Swiveling	Return swivel head o	or swivel table to original position:
		Mics. Transfor- Swiveling
	 Select via the 	mations > softkeys
	Example of technol	ological data:
	T 0 D	1
	• Enter the following	g parameters:
	Retraction	Yes
	Swiveling	Yes
	Transformation	New
	XO	0
	~~~	0

Resu	lt

,	ShopMill	program	representation
---	----------	---------	----------------

0

0°

0°

0°

0

0

0

_

Axis by axis

Y0

**Z**0

X Y

Ζ

X1

Y1

**Z1** 

•

Direction

Accept

Swiveling

BEI	SPIE	L4	
Р	NS	BEISPIEL4	
<u>ش</u>	N10	Rectang.pocket 🛛 🗸	T=CUTTER_4 F0.1/Z V200M X0=-25 Y0=-25
类	N15	Swivel	X90 Y0 Z0 T=CUTTER_4
<u>ش</u>	N20	Rectang.pocket 🛛 🗸	T=CUTTER_4 F0.1/Z V200M X0=-25 Y0=-25
疉	N25	Swivel	Z-90 X90 Y0 T=CUTTER_4
ļ,	N30	Rectang.pocket 💎 🗸	T=CUTTER_4 F0.1/Z V200M X0=-25 Y0=-25
¢	N35	Setting	RP25 Blank
鹦	N40	Swivel	Z-45 X54.736 YØ T=CUTTER
ŧ	N45	Face milling	T=CUTTER F0.1/Z V200M X0=-17.678
78 <del>/</del> 77	N50	DRILL	T=DRILL F0.1/rev S2000rev. Z1=Sinc
Q-	NSS	001: Hole full cir.	Z0=0 X0=0 Y0=0 R5 N3
类	N6Ø	Swivel	T=0
END	N65	Program end	

9







# Appendix

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Α

Abbreviations

10.04



ABS	Absolute dimensions
CNC	Computerized Numerical Control: Computerized numerical control
СОМ	Communication: Communication Component of NC control that performs and coordinates communication.
D	Cutting edge
DIN	Deutsche Industrie Norm (German Industry Standard)
DRF	Differential Resolver Function: Differential resolver function The function in conjunction with an electronic handwheel generates an incremental work offset in automatic mode.
DRY	Dry Run: Dry run feedrate
F	Feed
GUD	Global User Data: Global user data
нw	Hardware
INC	Increment
INC	Incremental dimensions
INI	Initializing Data: Initializing data
LED	Light Emitting Diode: Light emitting diode
M01	M function: Programmed stop
M17	M function: End of subprogram
MCS	Machine Coordinate System
MD	Machine data
MDA	Manual Data Automatic
MLFB	Machine-readable product designation
MPF	Main Program File: Main program



NC	Numerical Control: Numerical control The NC control comprises the components NCK, PLC, PCU and COM.
NCK	Numerical Control Kernel: Numerical control kernel Component of NC control that executes programs and basically coordinates movements for the machine tool.
ОР	Operator Panel: Operator panel
PC	Personal Computer
PCU	Personal Computer Unit Component of NC control allowing communication between operator and machine.
PLC	Programmable Logic Control: Programmable logic control Component of NC control for processing machine tool control logic
PRT	Program Test
REF	Approaching a reference point
REPOS	Repositioning
ROV	Rapid override: Rapid override
RS-232-C	Serial interface
S	Spindle speed
SBL	Single Block: Single block
SI	Safety Integrated
SK	Softkey
SKP	SKiP: Skip block
SPF	Sub Program File: Subroutine
sw	Software
т	ΤοοΙ
тмz	Tool Magazine Zero
v	Cutting rate



WCS	Workpiece Coordinate System
WO	Zero offset
WPD	Workpiece Directory: Workpiece directory
wz	Tool





An overview of publications that is updated monthly is provided in a number of languages in the Internet at:

http://www.siemens.com/motioncontrol

via "Support" "Technical documentation" "Overview of publications"

#### **General Documentation**

- /BU/ SINUMERIK & SIMODRIVE, Automation Systems for Machine Tools Catalog NC 60
- /IKPI/ Industrial Communication and Field Devices Catalog IC PI
- /ST7/ SIMATIC Products for Totally Integrated Automation and Micro Automation Catalog ST 70
- IZI
   MOTION-CONNECT

   Cable, Connectors & System Components for SIMATIC, SINUMERIK,

   MASTERDRIVES, and SIMOTION

   Catalog NC Z

Safety Integrated Application Manual The Safety System for Industry

#### **Electronic Documentation**

/CD1/ The SINUMERIK System DOC ON CD (includes all SINUMERIK 840D/840Di/810D/802- and SIMODRIVE publications)



#### **User Documentation**

/AUK/	SINUMERIK 840D/810D Short Guide AutoTurn Operation
/AUP/	SINUMERIK 840D/810D Operator's Guide <b>AutoTurn Graphic Programming System</b> Programming / Setup
/BA/	SINUMERIK 840D/810D Operator's Guide <b>MMC</b>
/BAD/	SINUMERIK 840D/840Di/810D Operator's Guide <b>HMI Advanced</b>
/BAH/	SINUMERIK 840D/840Di/810D Operator's Guide <b>HT 6</b>
/BAK/	SINUMERIK 840D/840Di/810D Short Guide Operation
/BAM/	SINUMERIK 810D/840D Operation/Programming <b>ManualTurn</b>
/BAS/	SINUMERIK 840D/840Di/810D Operation/Programming <b>ShopMill</b>
/BAT/	SINUMERIK 840D/810D Operation/Programming <b>ShopTurn</b>
/BEM/	SINUMERIK 840D/810D Operator's Guide <b>HMI Embedded</b>
/BNM/	SINUMERIK 840D/840Di/810D User's Guide <b>Measuring Cycles</b>
/BTDI/	SINUMERIK 840D/840Di/810D Motion Control Information System (MCIS) User's Guide <b>Tool Data Information</b>
/CAD/	SINUMERIK 840D/840Di/810D Operator's Guide <b>CAD Reader</b> (part of the online help)
/DA/	SINUMERIK 840D/840Di/810D Diagnostics Guide
/KAM/	SINUMERIK 840D/810D Short Guide <b>ManualTurn</b>
/KAS/	SINUMERIK 840D/810D Short Guide <b>ShopMill</b>
/KAT/	SINUMERIK 840D/810D Short Guide <b>ShopTurn</b>





/PG/	SINUMERIK 840D/840Di/810D Programming Guide <b>Fundamentals</b>
/PGA/	SINUMERIK 840D/840Di/810D Programming Guide <b>Advanced</b>
/PGA1/	SINUMERIK 840D/840Di/810D List Manual <b>System Variables</b>
/PGK/	SINUMERIK 840D/840Di/810D Short Guide <b>Programming</b>
/PGM/	SINUMERIK 840D/840Di/810D Programming Guide <b>ISO Milling</b>
/PGT/	SINUMERIK 840D/840Di/810D Programming Guide <b>ISO Turning</b>
/PGZ/	SINUMERIK 840D/840Di/810D Programming Guide <b>Cycles</b>
/PI/	PCIN 4.4 Software for Data Transfer to/from <b>MMC Modules</b> Order number: 6FX2060-4AA00-4XB0 (English, German, French) Order from: WK Fürth
/SYI/	SINUMERIK 840Di System Overview



#### Manufacturer/Service Documentation

a) Lists /LIS/	SINUMERIK 840D/840Di/810D SIMODRIVE 611D Lists
b) Hardware /ASAL/	SIMODRIVE 611, MASTERDRIVES VC/MC Planning Guide General Information for <b>Asynchronous Motors</b>
/APH2/	SIMODRIVE 611 Planning Guide <b>Asynchronous Motors 1PH2</b>
/APH4/	SIMODRIVE 611 Planning Guide <b>Asynchronous Motors 1PH4</b>
/APH7S/	SIMODRIVE 611 Planning Guide <b>Asynchronous Motors 1PH7</b>
/APH7M/	MASTERDRIVES MC Planning Guide Asynchronous Motors 1PH7
/APL6/	MASTERDRIVES VC/MC Planning Guide Asynchronous Motors 1PL6
/BH/	SINUMERIK 840D/840Di/810D Operator Components Manual
/BHA/	SIMODRIVE Sensor User Guide (HW) Absolute Position Sensor with Profibus DP
/EMV/	SINUMERIK, SIROTEC, SIMODRIVE, SIMOTION Planning Guide EMC Installation Guideline
	The up-to-date declaration of conformity can be viewed on the Internet at <u>http://www4.ad.siemens.de</u>
	Please enter the ID no.: 15257461 in the "Search" field (top right) and click "go".
/GHA/	SINUMERIK/SIMOTION ADI4 - Analog Drive Interface for 4 Axes Manual
/PFK6/	SIMODRIVE 611, MASTERDRIVES MC Planning Guide <b>1FK6 Three-Phase AC Servomotors</b>
/PFK7/	SIMODRIVE 611, MASTERDRIVES MC Planning Guide <b>1FK7 Three-Phase AC Servomotors</b>
/PFS6/	MASTERDRIVES MC Planning Guide <b>1FS6 Three-Phase AC Servomotors</b>
/PFT5/	SIMODRIVE 611 Planning Guide <b>1FT5 Three-Phase AC Servomotors</b>





/PFT6/	SIMODRIVE 611, MASTERDRIVES MC Planning Guide Synchronous Servomotors 1FT6
/PFU/	SINAMICS, MASTERDRIVES MICROMASTER SIEMOSYN Motors 1FU8
/PHC/	SINUMERIK 810D Configuring Manual (HW)
/PHD/	SINUMERIK 840D Configuring Manual (HW)
/PJAL/	SIMODRIVE 611, MASTERDRIVES MC Planning Guide Three-Phase Servomotors General Part for 1FT / 1FK Motors
/PJAS/	SIMODRIVE 611, MASTERDRIVES VC/MC Planning Guide Asynchronous Motors Contents: General Part, 1PH2, 1PH4, 1PH7, 1PL6
/PJFE/	SIMODRIVE Planning Guide <b>1FE1 Built-In Synchronous Motors</b> Three-Phase AC Motors for Main Spindle Drives
/PJF1/	SIMODRIVE Installation Guide <b>1FE1 0511FE1 147</b> . <b>Built-In Synchronous Motors</b> AC Motors for Main Spindle Drives
/PJLM/	SIMODRIVEPlanning Guide 1FN1, 1FN3 Linear MotorsALLGeneral Information about Linear Motor1FN11FN1 Three-Phase AC Linear Motor1FN31FN3 Three-Phase AC Linear MotorCONConnections
/PJM2/	SIMODRIVE 611, MASTERDRIVES MC Planning Guide <b>Servomotors</b> Contents: General Part, 1FT5, 1FT6, 1FK6, 1FK7, 1FS6
/PJTM/	SIMODRIVE Planning Guide <b>1FW6 Built-In Torque Motors 1FW6</b>
/PJU/	SIMODRIVE 611 Planning Guide <b>Converters</b>
/PKTM/	MASTERDRIVES Planning Guide <b>Torque Motors 1FW3</b>
/PMH/	SIMODRIVE Sensor Configuring/Installation Guide Hollow-Shaft Measuring System SIMAG H
/PMH2/	SIMODRIVE Sensor Configuring/Installation Guide Hollow-Shaft Measuring System SIMAG H2

/Δ`

/PMHS/	SIMODRIVE Installation Guide <b>Measuring System for Main Spindle Drives</b> SIZAG2 Toothed-Wheel Encoder
/PMS/	SIMODRIVE Planning Guide ECO Motor Spindle for Main Spindle Drives
/PPH/	SIMODRIVE Planning Guide <b>1PH2 / 1PH4 / 1PH7 Motors</b> AC Induction Motors for Main Spindle Drives
/PPM/	SIMODRIVE Planning Guide Hollow-Shaft Motors for <b>1PM4 and 1PM6</b> Main Spindle Drives
c) Software /FB1/	<ul> <li>SINUMERIK 840D/840Di/810D/FM-NC</li> <li>Description of Functions Basic Machine (Part 1) (the individual sections are listed below)</li> <li>A2 Various Interface Signals</li> <li>A3 Axis Monitoring, Protection Zones</li> <li>B1 Continuous-Path Mode, Exact Stop and Look Ahead</li> <li>B2 Acceleration</li> <li>D1 Diagnostic Tools</li> <li>D2 Interactive Programming</li> <li>F1 Traverse to Fixed Stop</li> <li>G2 Velocities, Setpoint/Actual Value Systems, Closed-Loop Control</li> <li>H2 Output of Auxiliary Functions to PLC</li> </ul>
	<ul> <li>K1 Mode Group, Channel, Program Operation Mode</li> <li>K2 Axes, Coordinate Systems, Frames, Actual-Value System for Workpiece, External Zero Offset</li> <li>K4 Communication</li> <li>N2 EMERGENCY STOP</li> <li>P1 Traverse Axes</li> <li>P3 Basic PLC Program</li> <li>R1 Reference Point Approach</li> <li>S1 Spindles</li> <li>V1 Feeds</li> <li>W1 Tool Offset</li> </ul>



/FB2/

SINUMERIK 840D/840Di/810D Description of Functions **Extended Functions (Part 2)** including FM-NC: Turning, Stepper Motor (the various manuals are listed below)

- A4 Digital and Analog NCK I/Os
- B3 Several Operator Panels and NCUs
- B4 Operation via PG/PC
- F3 Remote Diagnostics
- H1 JOG with/without Handwheel
- K3 Compensations
- K5 Mode Groups, Channels, Axis Replacement
- L1 FM NC Local Bus
- M1 Kinematic Transformation
- M5 Measurement
- N3 Software Cams, Position Switching Signals
- N4 Punching and Nibbling
- P2 Positioning Axes
- P5 Oscillation
- R2 Rotary Axes
- S3 Synchronous Spindle
- S5 Synchronized Actions (SW 3 and lower, higher /FBSY/)
- S6 Stepper Motor Control
- S7 Memory Configuration
- T1 Indexing Axes
- W3 Tool Change
- W4 Grinding

/FB3/

#### SINUMERIK 840D/840Di/810D Description of Functions **Special Functions (Part 3)** (the various sections are listed below)

- F2 3-Axis to 5-Axis Transformation
- G1 Gantry Axes
- G3 Clock Times
- K6 Contour Tunnel Monitoring
- M3 Coupled Motion and Leading Value Coupling
- S8 Constant Workpiece Speed for Centerless Grinding
- T3 Tangential Control
- TE0 Installation and Activation of Compile Cycles
- TE1 Clearance Control
- TE2 Analog Axes
- TE3 Master-Slave for Drives
- TE4 Transformation Package Handling
- TE5 Setpoint Exchange
- TE6 MCS Coupling
- TE7 Retrace Support
- TE8 Pulse-Independent Path-Synchronized Switching Signal Output
- V2 Preprocessing
- W5 3D Tool Radius Compensation

/Δ`

/FBA/	SIMODRIVE 611D/SINUMERIK 840D/810D Description of Functions <b>Drive Functions</b> (the individual sections are listed below)
	<ul> <li>DB1 Operating Messages/Alarm Reactions</li> <li>DD1 Diagnostic Functions</li> <li>DD2 Speed Control Loop</li> <li>DE1 Extended Drive Functions</li> <li>DF1 Enable Commands</li> <li>DG1 Encoder Parameterization</li> <li>DL1 Linear Motor MD</li> <li>DM1 Calculating Motor/Power Section Parameters and Controller Data</li> <li>DS1 Current Control Loop</li> <li>DÜ1 Monitors/Limitations</li> </ul>
/FBAN/	SINUMERIK 840D/SIMODRIVE 611 DIGITAL Description of Functions <b>ANA MODULE</b>
/FBD/	SINUMERIK 840D Description of Functions <b>Digitizing</b>
	<ul> <li>DI1 Start-Up</li> <li>DI2 Scan with Tactile Sensor (scancad scan)</li> <li>DI3 Scan with Laser (scancad laser)</li> <li>DI4 Milling Program Generation (scancad mill)</li> </ul>
/FBDM/	SINUMERIK 840D/840Di/810D Description of Functions DNC <b>NC Program Management</b> DNC Machines
/FBDN/	SINUMERIK 840D/840Di/810D Motion Control Information System (MCIS) Description of Functions <b>DNC NC Program Management</b>
	DN1 DNC Plant / DNC Cell DN2 DNC IFC SINUMERIK, NC Data Transfer via Network
/FBFA/	SINUMERIK 840D/840Di/810D Description of Functions <b>ISO Dialects for SINUMERIK</b>
/FBFE/	SINUMERIK 840D/810D Motion Control Information System (MCIS) Description of Functions <b>Remote Diagnosis</b>
	FE1 Remote Diagnosis ReachOut FE3 RCS Host/RCS Viewer (pcAnywhere)
/FBH/	SINUMERIK 840D/840Di/810D HMI Configuring Package included with the software
	Part 1 User's Guide Part 2 Description of Functions
/FBH1/	SINUMERIK 840D/840Di/810D HMI Configuring Package ProTool/Pro Option SINUMERIK included with the software



/FBHL/	SINUMERIK 840D/SIMODRIVE 611 digital Description of Functions <b>HLA Module</b>
/FBIC/	SINUMERIK 840D/840Di/810D Motion Control Information System (MCIS) Description of Functions <b>TDI Ident Connection</b>
/FBMA/	SINUMERIK 840D/810D Description of Functions <b>ManualTurn</b>
/FBO/	SINUMERIK 840D/810D Description of Functions Configuring <b>OP 030 Operator Interface</b> (the various sections are listed below)
	<ul> <li>BA Operator's Guide</li> <li>EU Development Environment (Configuring Package)</li> <li>PSE Introduction to Configuring of Operator Interface</li> <li>(IK Screen Kit: Software Update and Configuration)</li> </ul>
/FBP/	SINUMERIK 840D Description of Functions <b>C-PLC Programming</b>
/FBR/	SINUMERIK 840D/840Di/810D Description of Functions <b>RPC SINUMERIK Computer Link</b>
	NFL Host Computer Interface NPL PLC/NCK Interface
/FBSI/	SINUMERIK 840D/SIMODRIVE Description of Functions SINUMERIK <b>Safety Integrated</b>
/FBSP	SINUMERIK 840D/840Di/810D Description of Functions <b>ShopMill</b>
/FBST/	SIMATIC Description of Functions FM STEPDRIVE/SIMOSTEP
/FBSY/	SINUMERIK 840D/810D Description of Functions <b>Synchronized Actions</b>
/FBT/	SINUMERIK 840D/810D Description of Functions <b>ShopTurn</b>
/FBTC/	SINUMERIK 840D/810D IT Solutions Description of Functions <b>Tool Data Communication SinTDC</b>
/FBTD/	SINUMERIK 840D/810D IT solutions Description of Functions <b>Tool Information System (SinTDI)</b> with Online Help
/FBTP/	SINUMERIK 840D/840Di/810D Motion Control Information System (MCIS) Description of Functions <b>Preventive Maintenance TPM</b>
/FBU/	SIMODRIVE 611 universal/universal E Description of Functions Closed-Loop Control Component for Speed Control and Positioning







/S7M/	MATIC S7-300 <b>M 357.2 Multimodule</b> for Servo and Stepper Drives Order with the configuring package	
/SP/	SIMODRIVE 611-A/611-D SimoPro 3.1 Program for Configuring Machine-Tool Drives	
d) Installation and Start-up /BS/	MODRIVE 611 analog Description Start-Up Software for Main Spindle and Asynchronous Motor Modules Version 3.20	
/IAA/	MODRIVE 611A	
/IAC/	SINUMERIK 810D <b>nstallation and Start-Up Guide</b> ncluding description of SIMODRIVE 611D start-up oftware)	
/IAD/	SINUMERIK 840D/SIMODRIVE 611D <b>nstallation &amp; Start-Up Guide</b> ncluding description of SIMODRIVE 611D start-up oftware)	
/IAM/	SINUMERIK 840D/840Di/810D Installation and Start-Up Guide <b>HMI/MMC</b>	
	<ul> <li>LE1 Updates/Supplements</li> <li>LE1 Expanding the Operator Interface</li> <li>LE1 Online Help</li> <li>M2 Starting Up HMI Embedded</li> <li>M4 Starting Up HMI Advanced</li> <li>Creating Foreign Language Texts with Windows 95 / NT</li> <li>X2 Creating Foreign Language Texts with Windows 2000 / XF</li> </ul>	D







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То	Suggestions
SIEMENS AG	Corrections
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